

Student Handout 1

This student handout contains the Advance Sheet.

Student Handout 1

Advance Sheet

Lesson Hours This lesson consists of 8.5 hours of small group instruction and a 4.5 hour practical exercise reinforcement training package (RTP) overview

Overview During this lesson you will receive reinforcement training for the skill level one and two map reading skills necessary to read a map. You should have received initial training on these tasks in basic training or in your unit. This lesson will also serve as a foundation for future lesson on land navigation. Successful completion of the Primary leadership Development Course (PLDC) depends on your ability to apply map reading skills.

Learning Objective Terminal Learning Objective (TLO).

Action:	Apply map reading skills.
Conditions:	In a classroom and field environment given a 1:50,000 TENINO map, 1:50,000 map of local training area, lensatic compass, GTA 5-2-12, (Coordinate Scale and Protractor), pencil, paper, and SH-2 and SH-3.
Standards:	Applied map reading skills to-- <ul style="list-style-type: none">• Determine elevation on a map.• Orient a map using a lensatic compass.• Determine direction on a map using a protractor.• Determine polar coordinates.• Convert azimuths using the declination diagram.• Find unknown locations on a map using intersection and resection. IAW STP 21-24-SMCT, STP 21-1-SMCT, FM 3-25.26, and FM 21-31.

ELO A: Review reinforcement training package.

ELO B: Determine elevation on a map.

ELO C: Orient a map using a lensatic compass.

ELO D: Determine direction on a map.

ELO E: Convert azimuths using the declination diagram.

ELO F: Determine polar coordinates.

ELO G: Locate an unknown point on a map and on the ground by intersection.

ELO H: Locate an unknown point on a map and on the ground by resection.

Assignment The student assignments for this lesson are:

- Read SH-2, SH-3.
 - Study and complete the Reinforced Training Package (RTP) provided to you at inprocessing and answer all quizzes. Turn in your quiz answer sheets to your SGL NLT three days prior to the start of Lesson W221, Map Reading.
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**Additional
Subject Area
Resources**

None

Bring to Class

You must bring the following materials to class:

- All reference material received for this lesson.
 - Pencil and writing paper.
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Note to Students

It is your responsibility to do the homework prior to class. We expect you to come to class prepared. You will participate in small group discussion. We expect you to participate in the discussion by providing information you learned from your study, and also your personal and observed experiences. Failure to study and read the assignments above will result in your inability to participate with the rest of the group. Not having your input affects the group's ability to fully discuss the information.

Student Handout 2

This student handout contains 87 pages of extracted material from FM 3-25.26:

Page	(Reading/Study) Requirement
SH-2-2 thru SH-2-7	Chapter 3, pages 3-1 thru 3-6, read
SH-2-8 thru SH-2-21	Chapter 4, pages 4-12 thru 4-25, read
SH-2-22 thru SH-2-31	Chapter 5, pages 5-1 thru 5-10, read
SH-2-32 thru SH-2-50	Chapter 6, page 6-1 thru 6-19, read
SH-2-51 thru SH-2-63	Chapter 9, pages 9-1 thru 9-13, read
SH-2-64 thru SH-2-74	Chapter 10, pages 10-1 thru 10-11, read
SH-2-75 thru SH-2-88	Chapter 11, pages 11-1 thru 11-14, read

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CHAPTER 3

MARGINAL INFORMATION AND SYMBOLS

A map could be compared to any piece of equipment, in that before it is placed into operation the user must read the instructions. It is important that you, as a soldier, know how to read these instructions. The most logical place to begin is the marginal information and symbols, where useful information telling about the map is located and explained. All maps are not the same, so it becomes necessary every time a different map is used to examine the marginal information carefully.

3-1. MARGINAL INFORMATION ON A MILITARY MAP

Figure 3-1 shows a reduced version of a large-scale topographic map. The circled numbers indicate the items of marginal information that the map user needs to know. These circled numbers correspond to the following listed items.

a. **Sheet Name (1).** The sheet name is found in bold print at the center of the top and in the lower left area of the map margin. A map is generally named for the settlement contained within the area covered by the sheet, or for the largest natural feature located within the area at the time the map was drawn.

b. **Sheet Number (2).** The sheet number is found in bold print in both the upper right and lower left areas of the margin, and in the center box of the adjoining sheets diagram, which is found in the lower right margin. It is used as a reference number to link specific maps to overlays, operations orders, and plans. For maps at 1:100,000 scale and larger, sheet numbers are based on an arbitrary system that makes possible the ready orientation of maps at scales of 1:100,000, 1:50,000, and 1:25,000.

c. **Series Name (3).** The map series name is found in the same bold print as the sheet number in the upper left corner of the margin. The name given to the series is generally that of a major political subdivision, such as a state within the United States or a European nation. A map series usually includes a group of similar maps at the same scale and on the same sheet lines or format designed to cover a particular geographic area. It may also be a group of maps that serve a common purpose, such as the military city maps.

d. **Scale (4).** The scale is found both in the upper left margin after the series name, and in the center of the lower margin. The scale note is a representative fraction that gives the ratio of a map distance to the corresponding distance on the earth's surface. For example, the scale note 1:50,000 indicates that one unit of measure on the map equals 50,000 units of the same measure on the ground.

e. **Series Number (5).** The series number is found in both the upper right margin and the lower left margin. It is a sequence reference expressed either as a four-digit numeral (1125) or as a letter, followed by a three- or four-digit numeral (M661; T7110).

f. **Edition Number (6).** The edition number is found in bold print in the upper right area of the top margin and the lower left area of the bottom margin. Editions are numbered consecutively; therefore, if you have more than one edition, the highest numbered sheet is the most recent. Most military maps are now published by the DMA, but older editions of maps may have been produced by the US Army Map Service. Still others may have been drawn, at

least in part, by the US Army Corps of Engineers, the US Geological Survey, or other agencies affiliated or not with the United States or allied governments. The credit line, telling who produced the map, is just above the legend. The map information date is found immediately below the word "LEGEND" in the lower left margin of the map. This date is important when determining how accurately the map data might be expected to match what you will encounter on the ground.

g. **Index to Boundaries (7).** The index to boundaries diagram appears in the lower or right margin of all sheets. This diagram, which is a miniature of the map, shows the boundaries that occur within the map area, such as county lines and state boundaries.

h. **Adjoining Sheets Diagram (8).** Maps at all standard scales contain a diagram that illustrates the adjoining sheets. On maps at 1:100,000 and larger scales and at 1:1,000,000 scale, the diagram is called the index to adjoining sheets. It consists of as many rectangles representing adjoining sheets as are necessary to surround the rectangle that represents the sheet under consideration. The diagram usually contains nine rectangles, but the number may vary depending on the locations of the adjoining sheets. All represented sheets are identified by their sheet numbers. Sheets of an adjoining series, whether published or planned, that are at the same scale are represented by dashed lines. The series number of the adjoining series is indicated along the appropriate side of the division line between the series.

i. **Elevation Guide (9).** This is normally found in the lower right margin. It is a miniature characterization of the terrain shown. The terrain is represented by bands of elevation, spot elevations, and major drainage features. The elevation guide provides the map reader with a means of rapid recognition of major landforms.

j. **Declination Diagram (10).** This is located in the lower margin of large-scale maps and indicates the angular relationships of true north, grid north, and magnetic north. On maps at 1:250,000 scale, this information is expressed as a note in the lower margin. In recent edition maps, there is a note indicating the conversion of azimuths from grid to magnetic and from magnetic to grid next to the declination diagram.

k. **Bar Scales (11).** These are located in the center of the lower margin. They are rulers used to convert map distance to ground distance. Maps have three or more bar scales, each in a different unit of measure. Care should be exercised when using the scales, especially in the selection of the unit of measure that is needed.

l. **Contour Interval Note (12).** This note is found in the center of the lower margin normally below the bar scales. It states the vertical distance between adjacent contour lines of the map. When supplementary contours are used, the interval is indicated. In recent edition maps, the contour interval is given in meters instead of feet.

m. **Spheroid Note (13).** This note is located in the center of the lower margin. Spheroids (ellipsoids) have specific parameters that define the X Y Z axis of the earth. The spheroid is an integral part of the datum.

n. **Grid Note (14).** This note is located in the center of the lower margin. It gives information pertaining to the grid system used and the interval between grid lines, and it identifies the UTM grid zone number.

o. **Projection Note (15).** The projection system is the framework of the map. For military maps, this framework is of the conformal type; that is, small areas of the surface of the earth retain their true shapes on the projection; measured angles closely approximate true values; and

the scale factor is the same in all directions from a point. The projection note is located in the center of the lower margin. Refer to DMA for the development characteristics of the conformal-type projection systems.

(1) Between 80° south and 84° north, maps at scales larger than 1:500,000 are based on the transverse Mercator projection. The note reads TRANSVERSE MERCATOR PROJECTION.

(2) Between 80° south and 84° north, maps at 1:1,000,000 scale and smaller are based on standard parallels of the Lambert conformal conic projection. The note reads, for example, LAMBERT CONFORMAL CONIC PROJECTIONS 36° 40' N AND 39° 20' N.

(3) Maps of the polar regions (south of 80° south and north of 84° north) at 1:1,000,000 and larger scales are based on the polar stereographic projection. The note reads POLAR STEREOGRAPHIC PROJECTION.

p. **Vertical Datum Note (16).** This note is located in the center of the lower margin. The vertical datum or vertical-control datum is defined as any level surface (for example, mean sea level) taken as a surface of reference from which to determine elevations. In the United States, Canada, and Europe, the vertical datum refers to the mean sea level surface. However, in parts of Asia and Africa, the vertical-control datum may vary locally and is based on an assumed elevation that has no connection to any sea level surface. Map readers should habitually check the vertical datum note on maps, particularly if the map is used for low-level aircraft navigation, naval gunfire support, or missile target acquisition.

q. **Horizontal Datum Note (17).** This note is located in the center of the lower margin. The horizontal datum or horizontal-control datum is defined as a geodetic reference point (of which five quantities are known: latitude, longitude, azimuth of a line from this point, and two constants, which are the parameters of reference ellipsoid). These are the basis for horizontal-control surveys. The horizontal-control datum may extend over a continent or be limited to a small local area. Maps and charts produced by DMA are produced on 32 different horizontal-control data. Map readers should habitually check the horizontal datum note on every map or chart, especially adjacent map sheets. This is to ensure the products are based on the same horizontal datum. If products are based on different horizontal-control data, coordinate transformations to a common datum must be performed. UTM coordinates from the same point computed on different data may differ as much as 900 meters.

r. **Control Note (18).** This note is located in the center of the lower margin. It indicates the special agencies involved in the control of the technical aspects of all the information that is disseminated on the map.

s. **Preparation Note (19).** This note is located in the center of the lower margin. It indicates the agency responsible for preparing the map.

t. **Printing Note (20).** This note is also located in the center of the lower margin. It indicates the agency responsible for printing the map and the date the map was printed. The printing data should not be used to determine when the map information was obtained.

u. **Grid Reference Box (21).** This box is normally located in the center of the lower margin. It contains instructions for composing a grid reference.

v. **Unit imprint and Symbol (22).** The unit imprint and symbol is on the left side of the lower margin. It identifies the agency that prepared and printed the map with its respective symbol. This information is important to the map user in evaluating the reliability of the map.

w. **Legend (23).** The legend is located in the lower left margin. It illustrates and identifies the topographic symbols used to depict some of the more prominent features on the map. The symbols are not always the same on every map. Always refer to the legend to avoid errors when reading a map.

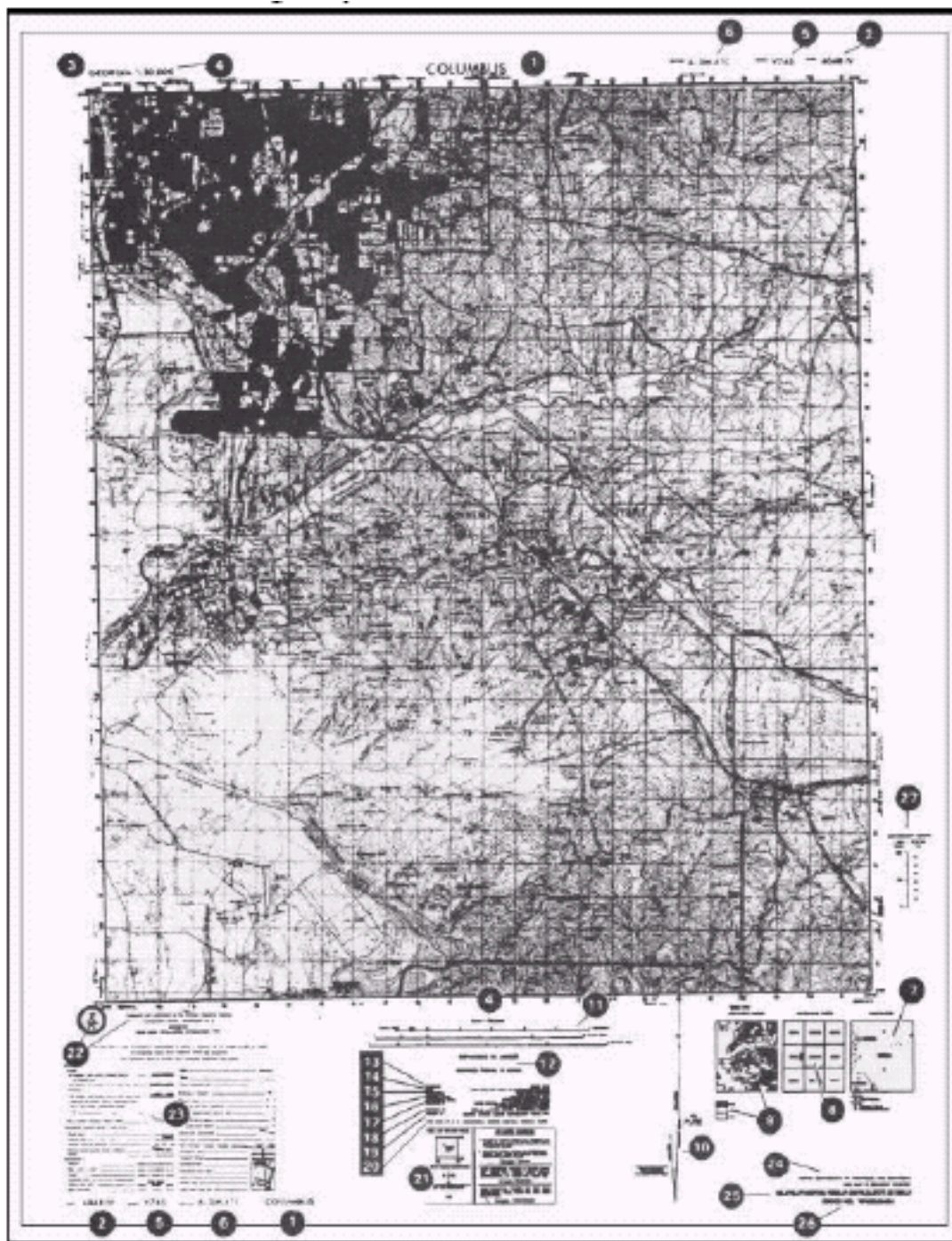


Figure 3-1. Topographical Map

3-2. ADDITIONAL NOTES

Not all maps contain the same items of marginal information. Under certain conditions, special notes and scales may be added to aid the map user. The following are examples:

a. **Glossary.** This is an explanation of technical terms or a translation of terms on maps of foreign areas where the native language is other than English.

b. **Classification.** Certain maps require a note indicating the security classification. This is shown in the upper and lower margins.

c. **Protractor Scale.** This scale may appear in the upper margin on some maps. It is used to lay out the magnetic-grid declination for the map, which, in turn, is used to orient the map sheet with the aid of the lensatic compass.

d. **Coverage Diagram.** On maps at scales of 1:100,000 and larger, a coverage diagram may be used. It is normally in the lower or right margin and indicates the methods by which the map was made, dates of photography, and reliability of the sources. On maps at 1:250,000 scale, the coverage diagram is replaced by a reliability diagram.

e. **Special Notes (24).** A special note is any statement of general information that relates to the mapped area. It is normally found in the lower right margin. For example: This map is red-light readable.

f. **User's Note (25).** This note is normally located in the lower right-hand margin. It requests cooperation in correcting errors or omissions on the map. Errors should be marked and the map forwarded to the agency identified in the note.

g. **Stock Number Identification (26).** All maps published by the DMA that are in the Department of the Army map supply system contain stock number identifications that are used in requisitioning map supplies. The identification consists of the words "STOCK NO" followed by a unique designation that is composed of the series number, the sheet number of the individual map and, on recently printed sheets, the edition number. The designation is limited to 15 units (letters and numbers). The first 5 units are allotted to the series number; when the series number is less than 5 units, the letter "X" is substituted as the fifth unit. The sheet number is the next component; however, Roman numerals, which are part of the sheet number, are converted to Arabic numerals in the stock number. The last 2 units are the edition number; the first digit of the edition number is a zero if the number is less than 10. If the current edition number is unknown, the number 01 is used. The latest available edition will be furnished. Asterisks are placed between the sheet number and the edition number when necessary to ensure there are at least 11 units in the stock number.

h. **Conversion Graph (27).** Normally found in the right margin, this graph indicates the conversion of different units of measure used on the map.

3-3. TOPOGRAPHIC MAP SYMBOLS

The purpose of a map is to permit one to visualize an area of the earth's surface with pertinent features properly positioned. The map's legend contains the symbols most commonly used in a particular series or on that specific topographic map sheet. Therefore, the legend should be referred to each time a new map is used. Every effort is made to design standard symbols that resemble the features they represent. If this is not possible, symbols are selected that logically imply the features they portray. For example, an open-pit mining operation is represented by a small black drawing of a crossed hammer and pickax.

a. Ideally, all the features within an area would appear on a map in their true proportion, position, and shape. This, however, is not practical because many of the features would be unimportant and others would be unrecognizable because of their reduction in size.

b. The mapmaker has been forced to use symbols to represent the natural and man-made features of the earth's surface. These symbols resemble, as closely as possible, the actual features themselves as viewed from above. They are positioned in such a manner that the center of the symbol remains in its true location. An exception to this would be the position of a feature adjacent to a major road. If the width of the road has been exaggerated, then the feature is moved from its true position to preserve its relation to the road. FM 21-31 gives a description of topographic features and abbreviations authorized for use on our military maps.

3-4. MILITARY SYMBOLS

In addition to the topographic symbols used to represent the natural and man-made features of the earth, military personnel require some method for showing identity, size, location, or movement of soldiers; and military activities and installations. The symbols used to represent these military features are known as military symbols. These symbols are not normally printed on maps because the features and units that they represent are constantly moving or changing; military security is also a consideration. They do appear in special maps and overlays (Chapter 7) The map user draws them in, in accordance with proper security precautions. Refer to FM 101-5-1 for complete information on military symbols.

3-5. COLORS USED ON A MILITARY MAP

By the fifteenth century, most European maps were carefully colored. Profile drawings of mountains and hills were shown in brown, rivers and lakes in blue, vegetation in green, roads in yellow, and special information in red. A look at the legend of a modern map confirms that the use of colors has not changed much over the past several hundred years. To facilitate the identification of features on a map, the topographical and cultural information is usually printed in different colors. These colors may vary from map to map. On a standard large-scale topographic map, the colors used and the features each represent are:

- a. **Black.** Indicates cultural (man-made) features such as buildings and roads, surveyed spot elevations, and all labels.
- b. **Red-Brown.** The colors red and brown are combined to identify cultural features, all relief features, non-surveyed spot elevations, and elevation, such as contour lines on red-light readable maps.
- c. **Blue.** Identifies hydrography or water features such as lakes, swamps, rivers, and drainage.
- d. **Green.** Identifies vegetation with military significance, such as woods, orchards, and vineyards.
- e. **Brown.** Identifies all relief features and elevation, such as contours on older edition maps, and cultivated land on red-light readable maps.
- f. **Red.** Classifies cultural features, such as populated areas, main roads, and boundaries, on older maps.
- g. **Other.** Occasionally other colors may be used to show special information. These are indicated in the marginal information as a rule.

CHAPTER 4

GRIDS

This chapter covers how to determine and report positions on the ground in terms of their location on a map. Knowing where you are (position fixing) and being able to communicate that knowledge is crucial to successful navigation as well as to the effective employment of direct and indirect fire, tactical air support, and medical evacuation. It is essential for valid target acquisition; accurate reporting of NBC contamination and various danger areas; and obtaining emergency resupply. Few factors contribute as much to the survivability of troops and equipment and to the successful accomplishment of a mission as always knowing where you are. The chapter includes explanation of geographical coordinates, Universal Transverse Mercator grids, the military grid reference system, and the use of grid coordinates.

4-4. UNITED STATES ARMY MILITARY GRID REFERENCE SYSTEM

This grid reference system is designated for use with the UTM and UPS grids. The coordinate value of points in these grids could contain as many as 15 digits if numerals alone were used. The US military grid reference system reduces the length of written coordinates by substituting single letters for several numbers. Using the UTM and the UPS grids, it is possible for the location of a point (identified by numbers alone) to be in many different places on the surface of the earth. With the use of the military grid reference system, there is no possibility of this happening.

a. **Grid Zone Designation.** The world is divided into 60 grid zones, which are large, regularly shaped geographic areas, each of which is given a unique identification called the grid zone designation.

(1) **UTM Grid.** The first major breakdown is the division of each zone into area 6° wide by 80 high and 60 wide by 120 high. Remember, for the transverse Mercator projection, the earth's surface between 80°S and 84°N is divided into 60 N-S zones, each 6° wide. These zones are numbered from west to east, 1 through 60, starting at the 180° meridian. This surface is divided into 20 each-west rows in which 19 are 8° high and 1 row at the extreme north is 12° high. These rows are then lettered, from south to north, C through X (I and O were omitted). Any 6° by 8° zone or 6° by 12° zone is identified by giving the number and letter of the grid zone and row in which it lies. These are read RIGHT and UP so the number is always written before the letter. This combination of zone number and row letter constitutes the grid zone designation. Columbus lies in zone 16 and row S, or in grid zone designation 16S.

(2) **UPS Grid.** The remaining letters of the alphabet, A, B, Y, and Z, are used for the UPS grids. Each polar area is divided into two zones separated by the 0-180° meridian. In the south polar area, the letter A is the grid zone designation for the area west of the 0-180° meridian, and B for the area to the east. In the north polar area, Y is the grid zone designation for the western area and Z for the eastern area (Figure 4-10)

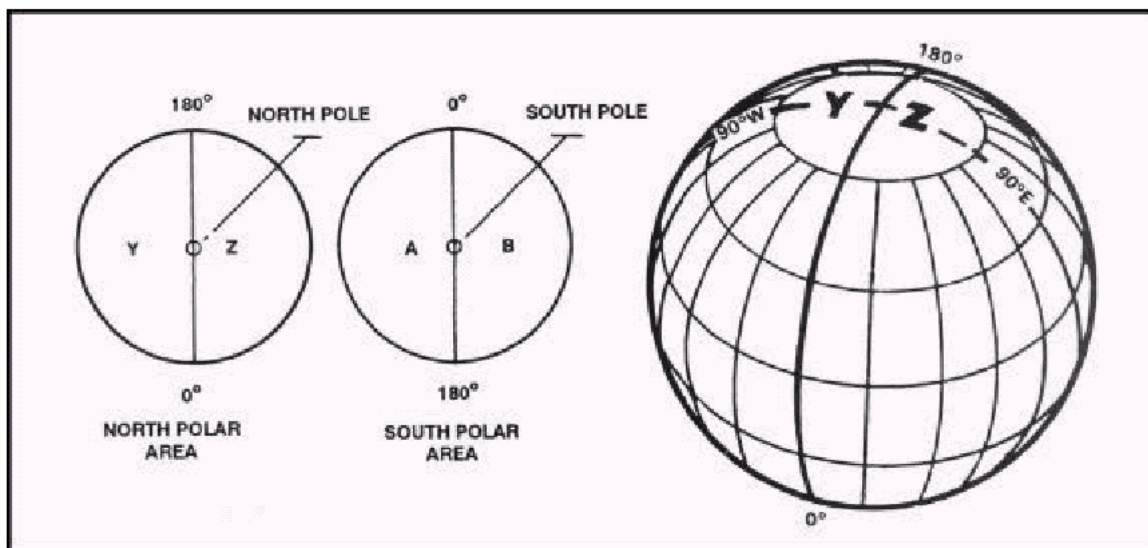


Figure 4-10. Grid zone designation for UPS grid.

b. **100,000-Meter Square.** Between 84°N and 80°S, each 6° by 8° or 6° by 12° zone is covered by 100,000-meter squares that are identified by the combination of two alphabetical letters. This identification is unique within the area covered by the grid zone designation. The first letter is the column designation; the second letter is the row designation (Figure 4-11, page 4-14). The north and south polar areas are also divided into 100,000-meter squares by columns and rows. A detailed discussion of the polar system can be found in Technical Report 8358.1. The 100,000-meter square identification letters are located in the grid reference box in the lower margin of the map.

PLATE 12

96°		580,000m					90°		500,000m					84°	
QV	TQ	UQ	VQ	WQ	XQ	YQ	BV	CV	DV	EV	FV	GV	KQ		
QU	TP	UP	VP	WP	XP	YP	BU	CU	DU	EU	FU	GU	KP		
QT	TN	UN	VN	WN	XN	YN	BT	CT	DT	ET	FT	GT	KN		
QS	TM	UM	VM	WM	XM	YM	BS	CS	DS	ES	FS	GS	KM		
QR	TL	UL	VL	WL	XL	YL	BR	CR	DR	ER	FR	GR	K		
QQ	TK	UK	VK	WK	XK	YK	BQ	CQ	DQ	EQ	FQ	GQ	K		
QP	TJ	UJ	VJ	WJ	XJ	YJ	BP	CP	DP	EP	FP	GP	K		
QN	TH	UH	VH	WH	XH	YH	BN	CN	DN	EN	FN	GN	K		
QM	TG	UG	VG	WG	XG	YG	BM	CM	DM	EM	FM	GM	K		
QL	TF	UF	VF	WF	XF	YF	BL	CL	DL	EL	FL	GL	K		

Figure 4-11. Grid zone designation and 100,000-meter square identification.

c. **Grid Coordinates.** We have now divided the earth's surface into 6° by 8° quadrangles, and covered these with 100,000-meter squares. The military grid reference of a point consists of the numbers and letters indicating in which of these areas the point lies, plus the coordinates locating the point to the desired position within the 100,000-meter square. The next step is to tie in the coordinates of the point with the larger areas. To do this, you must understand the following.

(1) **Grid Lines.** The regularly spaced lines that make the UTM and the UPS grid on any large-scale maps are divisions of the 100,000-meter square; the lines are spaced at 10,000- or 1,000-meter intervals (Figure 4-12). Each of these lines is labeled at both ends of the map with its false easting or false northing value, showing its relation to the origin of the zone. Two digits of the values are printed in large type, and these same two digits appear at intervals along the grid lines on the face of the map. These are called the principal digits, and represent the 10,000 and 1,000 digits of the grid value. They are of major importance to the map reader because they are the numbers he will use most often for referencing points. The smaller digits complete the UTM grid designation.

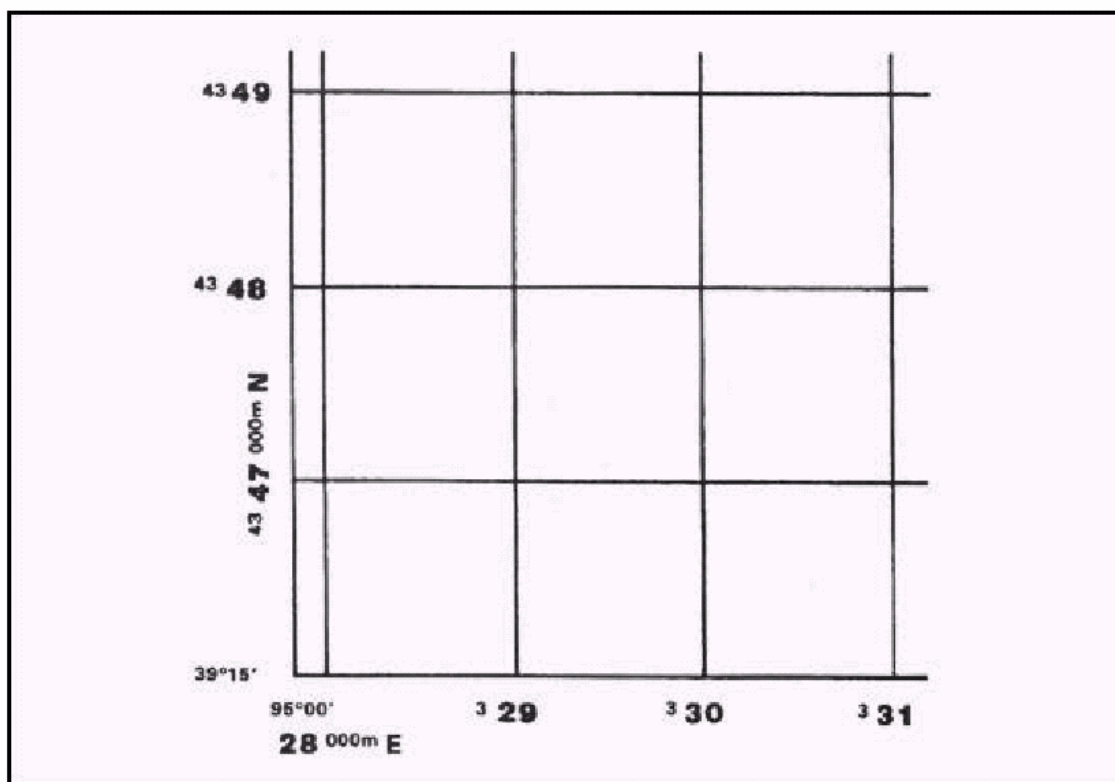


Figure 4-12. Grid lines.

EXAMPLE: The first grid line north of the south-west corner of the Columbus map is labeled 3570000m N. This means its false northing (distance north of the equator) is 3,570,000 meters. The principal digits, 70, identify the line for referencing points in the northerly direction. The smaller digits, 35, are part of the false coordinates and are rarely used. The last three digits, 000, of the value are omitted. Therefore, the first grid line east of the south-west corner is labeled 689000m E. The principal digits, 89, identify the line for referencing points in the easterly direction (Figure 4-13, page 4-16).

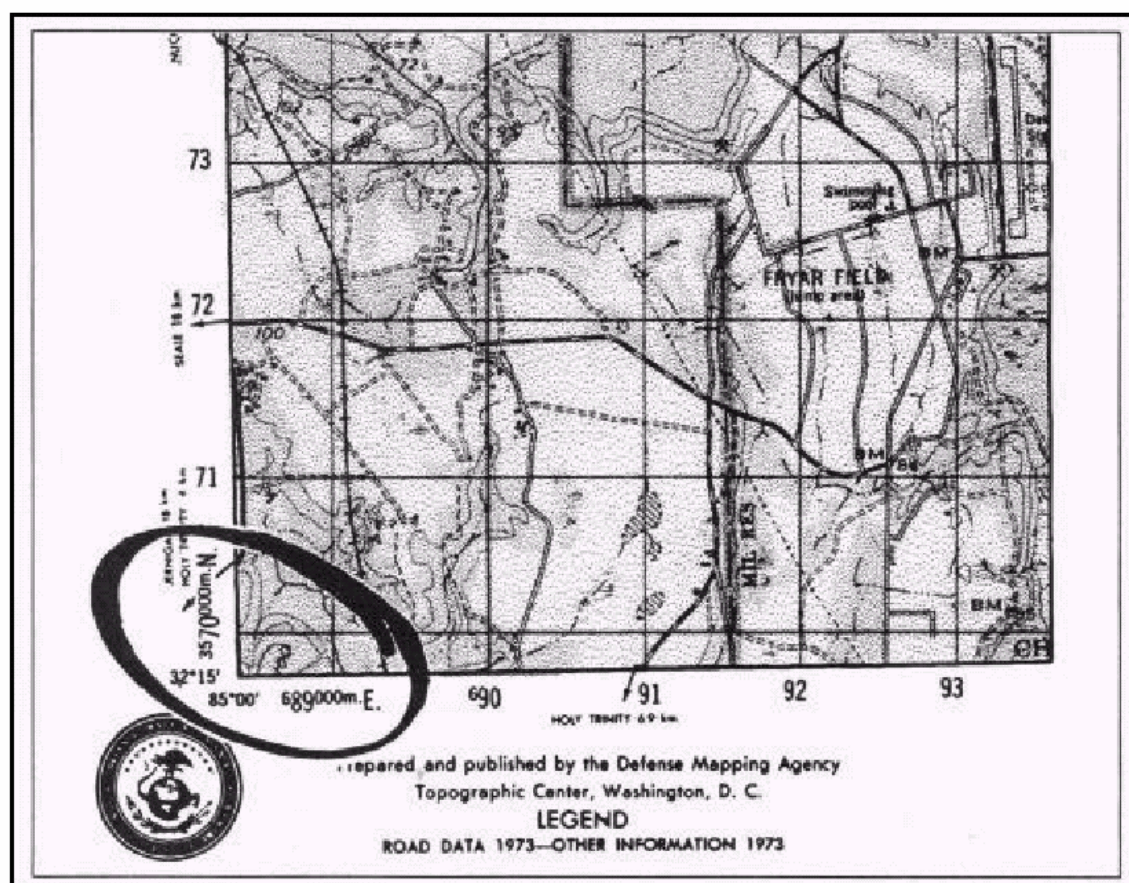


Figure 4-13. Columbus map, southwest corner.

(2) **Grid Squares.** The north-south and east-west grid lines intersect at 90°, forming grid squares. Normally, the size of one of these grid squares on large-scale maps is 1,000 meters (1 kilometer).

(3) **Grid Coordinate Scales.** The primary tool for plotting grid coordinates is the grid coordinate scale. The grid coordinate scale divides the grid square more accurately than can be done by estimation, and the results are more consistent. When used correctly, it presents less chance for making errors. GTA 5-2-12, 1981, contains four types of coordinate scales (Figure 4-14).

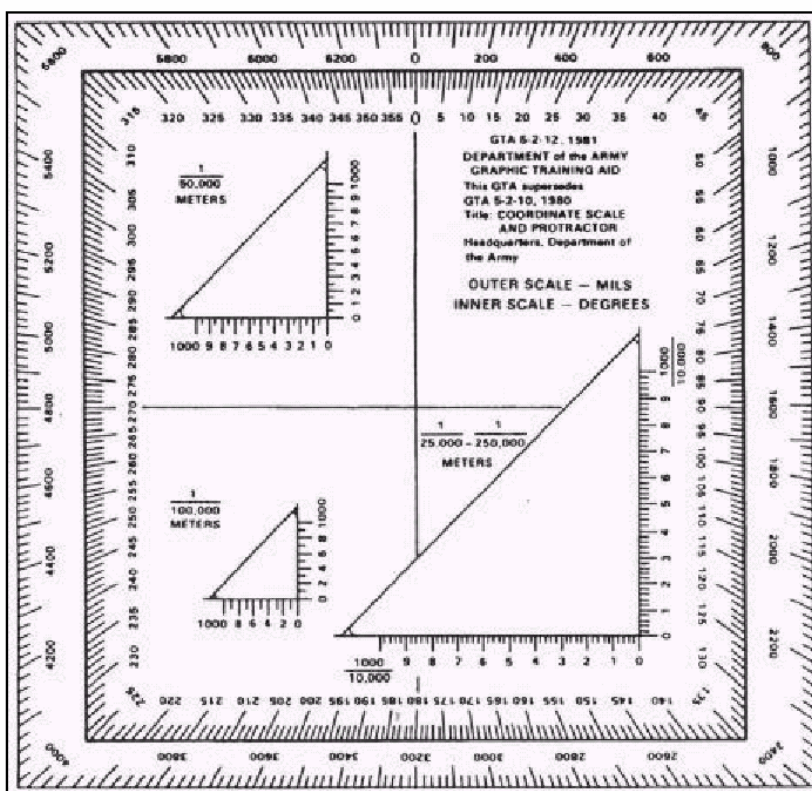


Figure 4-14. Coordinate scales.

(a) The 1:25,000/1:250,000 (lower right in figure) can be used in two different scale maps, 1:25,000 or 1:250,000. The 1:25,000 scale subdivides the 1,000-meter grid block into 10 major subdivisions, each equal to 100 meters. Each 100-meter block has five graduations, each equal to 20 meters. Points falling between the two graduations can be read accurately by the use of estimation. These values are the fourth and eighth digits of the coordinates. Likewise, the 1:250,000 scale is subdivided in 10 major subdivisions, each equal to 1,000 meters. Each 1,000-meter block has five graduations, each equal to 200 meters. Points falling between two graduations can be read approximately by the use of estimation.

(b) The 1:50,000 scale (upper left in Figure 4-14) subdivides the 1,000-meter block into 10 major subdivisions, each equal to 100 meters. Each 100-meter block is then divided in half. Points falling between the graduations must be estimated to the nearest 10 meters for the fourth and eighth digits of the coordinates.

(c) The 1:100,000 scale (lower left in Figure 4-14) subdivides the 1,000-meter grid block into five major subdivisions of 200 meters each. Each 200-meter block is then divided in half at 100-meter intervals.

4-5. LOCATE A POINT USING GRID COORDINATES

Based on the military principle for reading maps (RIGHT and UP), locations on the map can be determined by grid coordinates. The number of digits represents the degree of precision to

to which a point has been located and measured on a map—the more digits the more precise the measurement.

a. **Without a Coordinate Scale.** Determine grids without a coordinate scale by referring to the north-south grid lines numbered at the bottom margin of any map. Then read RIGHT to the north-south grid line that precedes the desired point (this first set of two digits is the RIGHT reading). Then by referring to the east-west grid lines numbered at either side of the map, move UP to the east-west grid line that precedes the desired point (these two digits are the UP reading). Coordinate 1484 locate the 1,000-meter grid square in which point X is located; the next square to the right would be 1584; the next square up would be 1485, and so forth (Figure 4-15). Locate the point to the nearest 100 meters using estimation. Mentally divide the grid square in tenths, estimate the distance from the grid line to the point in the same order (RIGHT and UP). Give complete coordinate RIGHT, then complete coordinate UP. Point X is about two-tenths or 200 meters to the RIGHT into the grid square and about seven-tenths or 700 meters UP.

RESULTS: The coordinates to the nearest 100 meters are 142847.

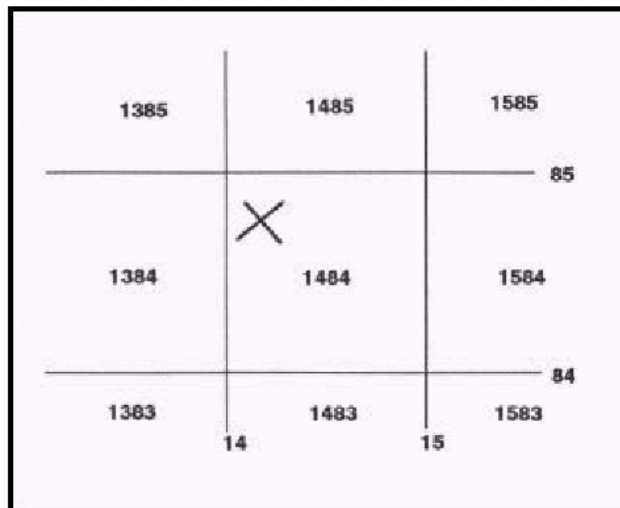


Figure 4-15. Determining grids without coordinate point.

b. **With a Coordinate Scale (1:25,000).** In order to use the coordinate scale for determining grid coordinates, ensure that the appropriate scale is being used on the corresponding map, and that the scale is right side up. To ensure the scale is correctly aligned, place it with the zero-zero point at the lower left corner of the grid square. Keeping the horizontal line of the scale directly on top of the east-west grid line, slide it to the right until the vertical line of the scale touches the point for which the coordinates are desired (Figure 4-16). When reading coordinates, examine the two sides of the coordinate scale to ensure that the horizontal line of the scale is aligned with the east-west grid line, and the vertical line of the scale is parallel with the north-south grid line. Use the scale when precision of more than 100 meters is required. To locate the point to the nearest 10 meters, measure the hundredths of a grid square RIGHT and UP from the grid lines to the point.

Point X is about 17 hundredths or 170 meters RIGHT and 84 hundredths or 840 meters UP.
The coordinates to the nearest 10 meters are 14178484.

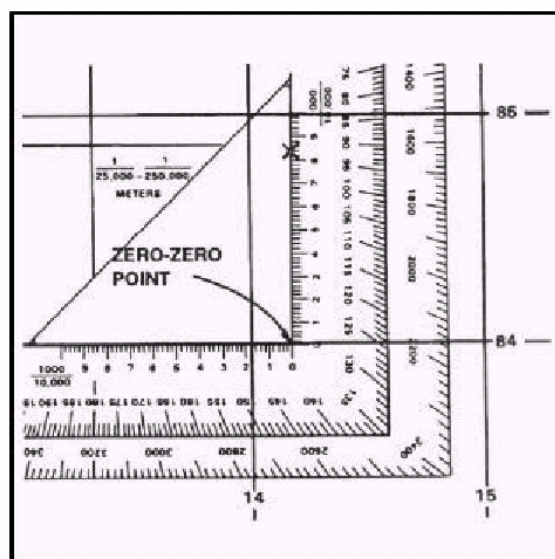


Figure 4-16. Placing a coordinate scale on a grid.

NOTE: Care should be exercised by the map reader using the coordinate scale when the desired point is located within the zero-zero point and the number 1 on the scale. Always prefix a zero if the hundredths reading is less than 10. In Figure 4-17, the desired point is reported as 14818407.

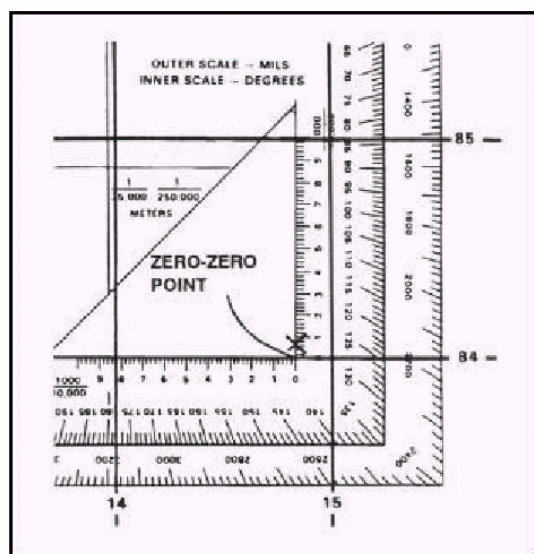


Figure 4-17. Zero-zero point.

c. **1:50,000 Coordinating Scale.** On the 1:50,000 coordinate scale, there are two sides: vertical and horizontal. These sides are 1,000 meters in length. The point at which the sides meet is the zero-zero point. Each side is divided into 10 equal 100-meter segments by a long tick mark and number. Each 100-meter segment is subdivided into 50-meter segments by a short tick mark (Figure 4-18). By using interpolation, mentally divide each 50-meter segment into tenths. For example, a point that lies after a whole number but before a short tick mark is identified as 10, 20, 30, or 40 meters and any point that lies after the short tick mark but before the whole number is identified as 60, 70, 80, or 90 meters.

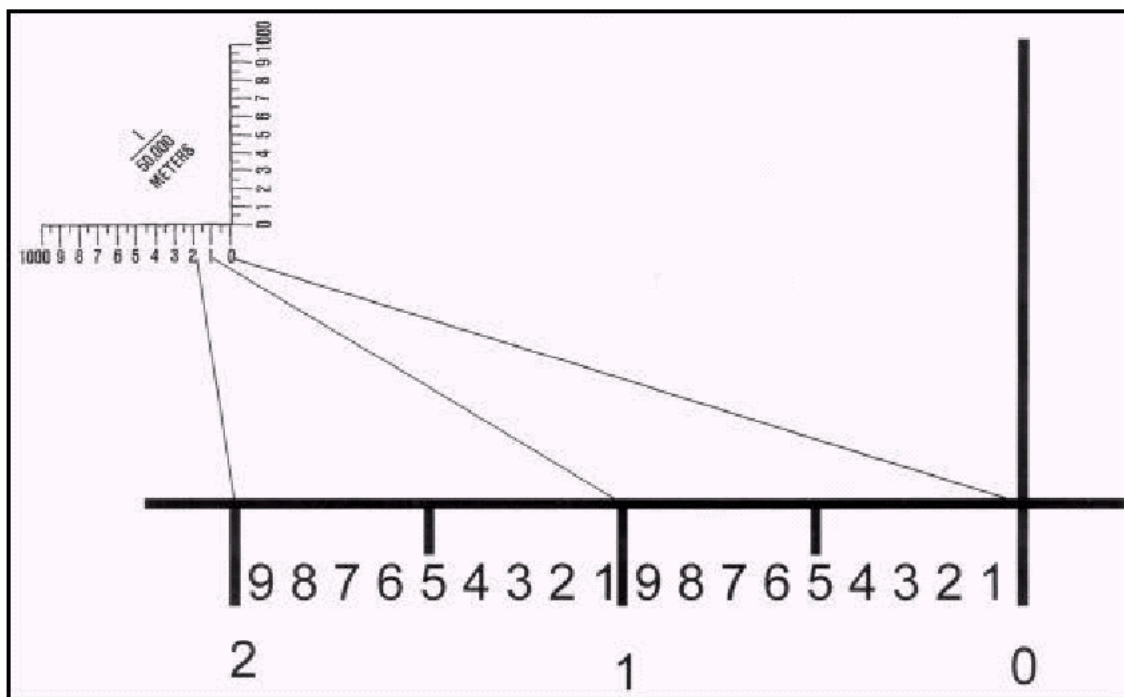


Figure 4-18. 1:50,000 coordinating scale.

d. **Example of Obtaining an Eight-Digit Coordinate Using 1:50,000 Scale.** To ensure the scale is correctly aligned, place it with the zero-zero point at the lower left corner of the grid square. Keeping the horizontal line of the scale directly on top of the east-west grid line, slide the scale to the right until the vertical line of the scale touches the point for which the coordinates are desired (Figure 4-19, page 4-21). Reading **right**, you can see that the point lies **530** meters to the right into the grid square, which gives a right reading of **7853**. Reading **up**, you can see that the point lies **320** meters up into the grid square, giving an up reading of **0032**.

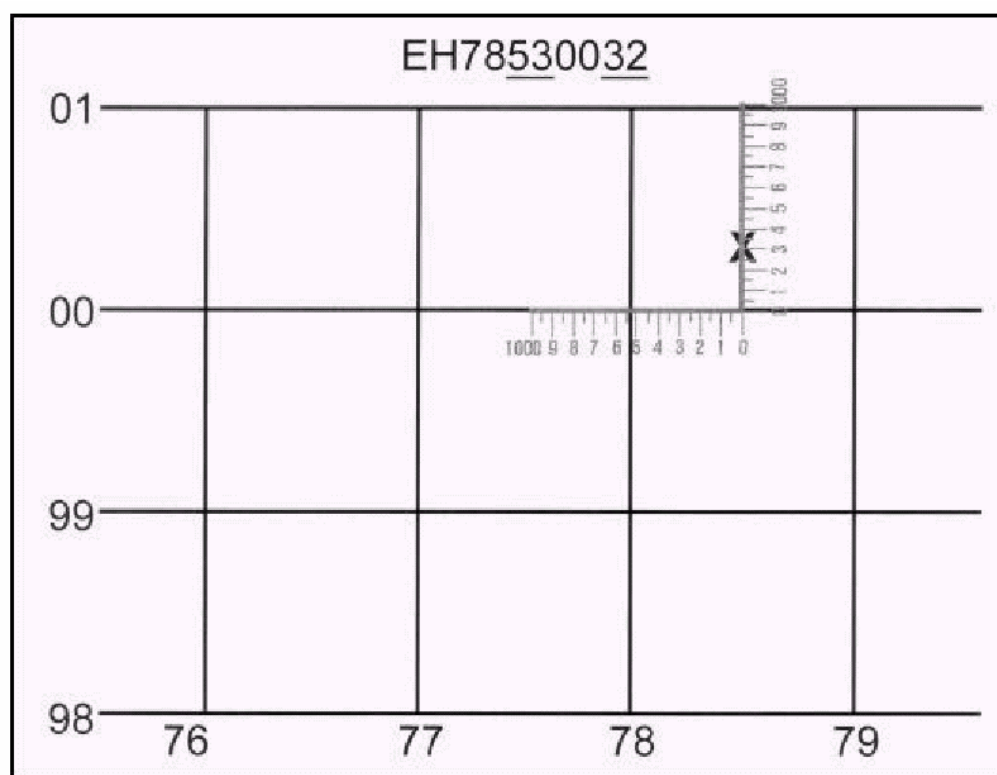


Figure 4-19. Example of obtaining an eight-digit coordinate using 1:50,000 scale.

e. **Recording and Reporting Grid Coordinates.** Coordinates are written as one continuous number without spaces, parentheses, dashes, or decimal points; they must always contain an even number of digits. Therefore, whoever is to use the written coordinates must know where to make the split between the RIGHT and UP readings. It is a military requirement that the 100,000-meter square identification letters be included in any point designation. Normally, grid coordinates are determined to the nearest 100 meters (six digits) for reporting locations. With practice, this can be done without using plotting scales. The location of targets and other point locations for fire support are determined to the nearest 10 meters (eight digits).

NOTE: Special care should be exercised when recording and reporting coordinates.

Transposing numbers or making errors could be detrimental to military operations.

4-6. LOCATE A POINT USING THE US ARMY MILITARY GRID REFERENCE SYSTEM

There is only one rule to remember when reading or reporting grid coordinates—always read to the RIGHT and then UP. The first half of the reported set of coordinate digits represents the left-to-right (easting) grid label, and the second half represents the label as read from the

bottom to top (northing). The grid coordinates may represent the location to the nearest 10-, 100-, or 1,000-meter increment.

a. **Grid Zone.** The number 16 locates a point within zone 16, which is an area 6° wide and extends between 80°S latitude and 84°N latitude (Figure 4-8, page 4-11).

b. **Grid Zone Designation.** The number and letter combination, 16S, further locates a point within the grid zone designation 16S, which is a quadrangle 6° wide by 8° high. There are 19 of these quads in zone 16. Quad X, which is located between 72°N and 84°N latitude, is 12° high (Figure 4-8, page 4-11).

c. **100,000-Meter Square Identification.** The addition of two more letters locates a point within the 100,000-meter grid square. Thus 16SGL (Figure 4-11, page 4-14) locates the point within the 100,000-meter square GL in the grid zone designation 16S. For information on the lettering system of 100,000-meter squares, see TM 5-241-1.

d. **10,000-Meter Square.** The breakdown of the US Army military grid reference system continues as each side of the 100,000-meter square is divided into 10 equal parts. This division produces lines that are 10,000 meters apart. Thus the coordinates 16SGL08 would locate a point as shown in Figure 4-20. The 10,000-meter grid lines appear as index (heavier) grid lines on maps at 1:100,000 and larger.

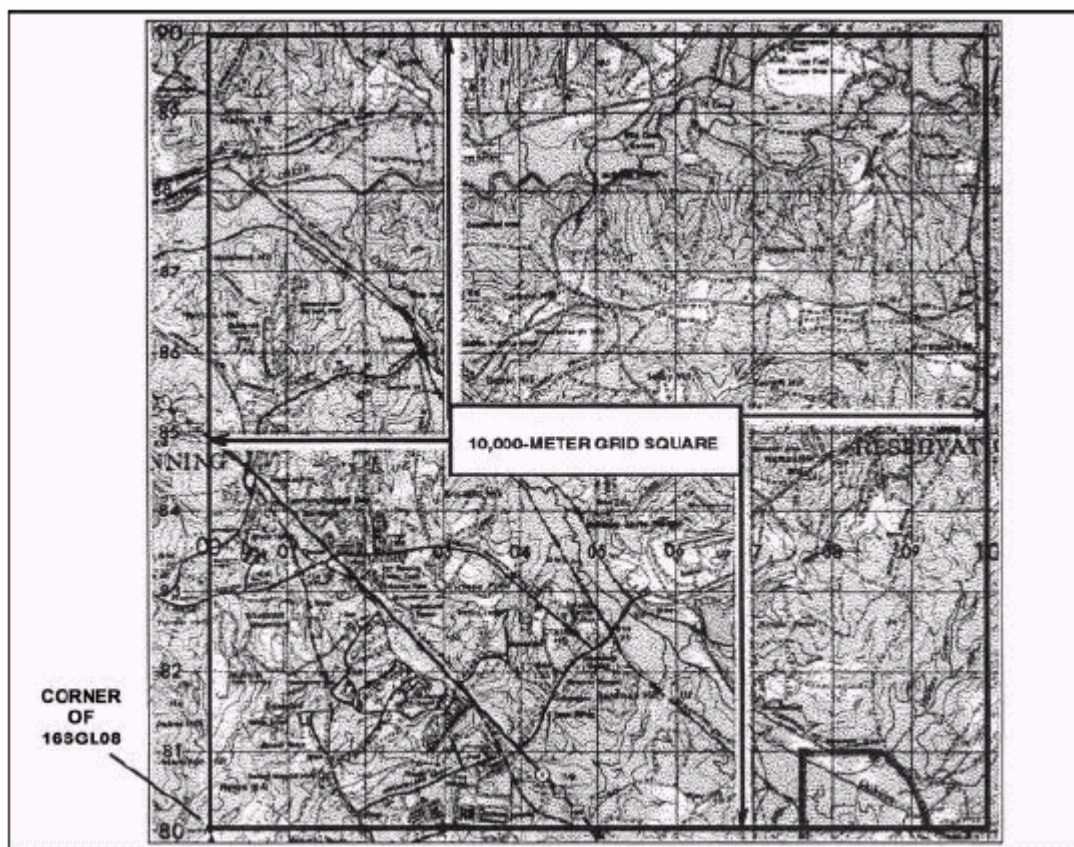


Figure 4-20. The 10,000-meter grid square.

e. **1,000-Meter Square.** To obtain 1,000-meter squares, each side of the 10,000-meter square is divided into 10 equal parts. This division appears on large-scale maps as the actual grid lines; they are 1,000 meters apart. On the Columbus map, using coordinates 16SGL0182, the easting 01 and the northing 82 gives the location of the southwest corner of grid square 0182 or to the nearest 1,000 meters of a point on the map (Figure 4-21).

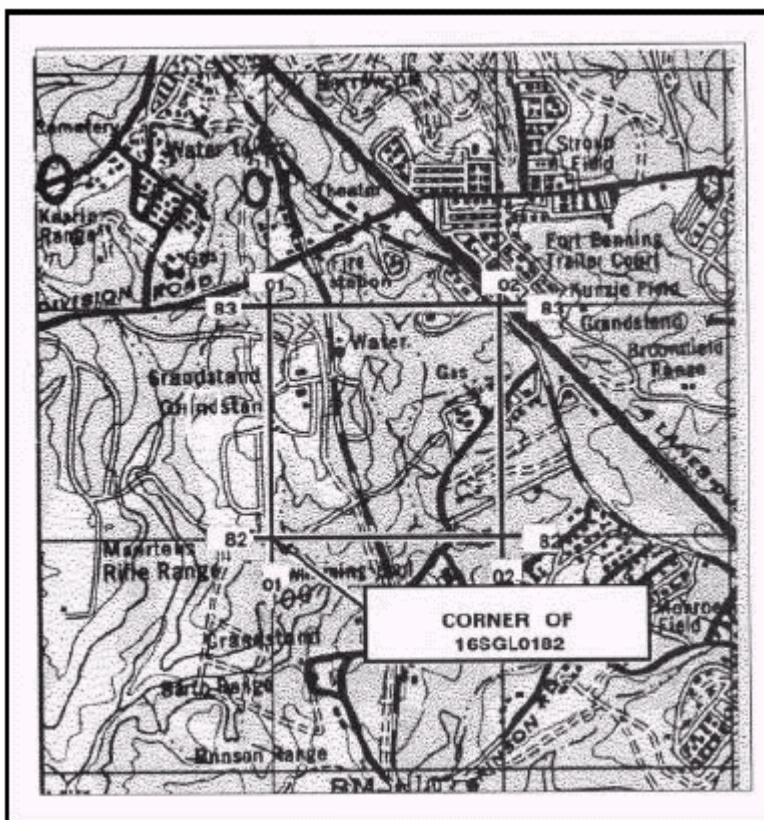


Figure 4-21. The 1,000-meter grid square.

f. **100-Meter Identification.** To locate to the nearest 100 meters, the grid coordinate scale can be used to divide the 1,000-meter grid squares into 10 equal parts (Figure 4-22, page 4-24).

g. **10-Meter Identification.** The grid coordinate scale has divisions every 50 meters on the 1:50,000 scale and every 20 meters on the 1:25,000 scale. These can be used to estimate to the nearest 10 meters and give the location of one point on the earth's surface to the nearest 10 meters.

EXAMPLE: 16SGL01948253 (gas tank) (Figure 4-22).

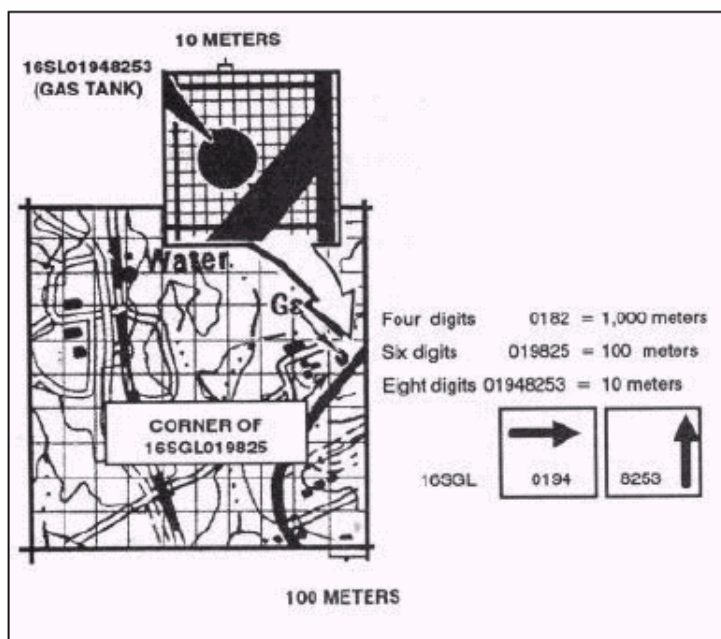


Figure 4-22. The 100-meter and 10-meter grid squares.

h. **Precision.** The precision of a point's location is shown by the number of digits in the coordinates; the more digits, the more precise the location (Figure 4-22, insert).

4-7. GRID REFERENCE BOX

A grid reference box (Figure 4-23) appears in the marginal information of each map sheet. It contains step-by-step instructions for using the grid and the US Army military grid reference system. The grid reference box is divided into two parts.

a. The left portion identifies the grid zone designation and the 100,000-meter square. If the sheet falls in more than one 100,000-meter square, the grid lines that separate the squares are shown in the diagram and the letters identifying the 100,000-meter squares are given.

EXAMPLE: On the Columbus map sheet, the vertical line labeled 00 is the grid line that separates the two 100,000-meter squares, FL and GL. The left portion also shows a sample for the 1,000-meter square with its respective labeled grid coordinate numbers and a sample point within the 1,000-meter square.

b. The right portion of the grid reference box explains how to use the grid and is keyed on the sample 1,000-meter square of the left side. The following is an example of the military grid reference:

EXAMPLE: 16S locates the 6° by 8° area (grid zone designation).

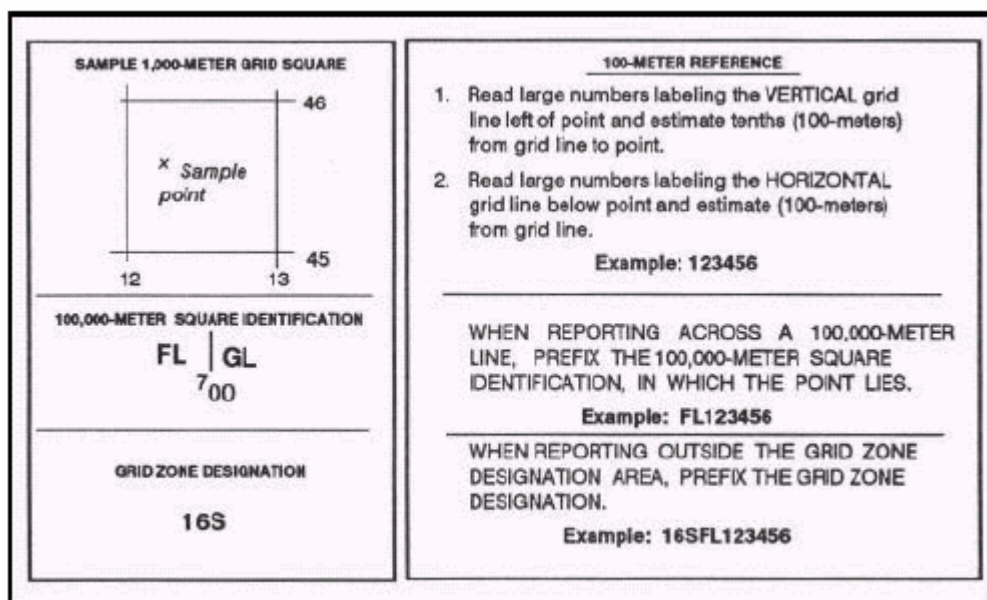


Figure 4-23. Grid reference box.

4-8. OTHER GRID SYSTEMS

The military grid reference system is not universally used. Soldiers must be prepared to interpret and use other grid systems, depending on the area of operations or the personnel the soldiers are operating with.

a. **British Grids.** In a few areas of the world, British grids are still shown on military maps. However, the British grid systems are being phased out. Eventually all military mapping will be converted to the UTM grid.

b. **World Geographic Reference System (GEOREF).** This system is a worldwide position reference system used primarily by the US Air Force. It may be used with any map or chart that has latitude and longitude printed on it. Instructions for using GEOREF data are printed in blue and are found in the margin of aeronautical charts (Figure 4-24, page 4-26). This system is based upon a division of the earth's surface into quadrangles of latitude and longitude having a systematic identification code. It is a method of expressing latitude and longitude in a form suitable for rapid reporting and plotting. Figure 4-24 illustrates a sample grid reference box using GEOREF. The GEOREF system uses an identification code that has three main divisions.

CHAPTER 5

SCALE AND DISTANCE

A map is a scaled graphic representation of a portion of the earth's surface. The scale of the map permits the user to convert distance on the map to distance on the ground or vice versa. The ability to determine distance on a map, as well as on the earth's surface, is an important factor in planning and executing military missions.

5-1. REPRESENTATIVE FRACTION

The numerical scale of a map indicates the relationship of distance measured on a map and the corresponding distance on the ground. This scale is usually written as a fraction and is called the representative fraction. The RF is always written with the map distance as 1 and is independent of any unit of measure. (It could be yards, meters, inches, and so forth.) An RF of 1/50,000 or 1:50,000 means that one unit of measure on the map is equal to 50,000 units of the same measure on the ground.

a. The ground distance between two points is determined by measuring between the same two points on the map and then multiplying the map measurement by the denominator of the RF or scale (Figure 5-1, page 5-2).

EXAMPLE:

The map scale is 1:50,000

RF = 1/50,000

The map distance from point A to point B is 5 units

5 x 50,000 = 250,000 units of ground distance

b. Since the distance on most maps is marked in meters and the RF is expressed in this unit of measurement in most cases, a brief description of the metric system is needed. In the metric system, the standard unit of measurement is the meter.

1 meter contains 100 centimeters (cm).

100 meters is a regular football field plus 10 meters.

1,000 meters is 1 kilometer (km).

10 kilometers is 10,000 meters.

Appendix C contains the conversion tables.

c. The situation may arise when a map or sketch has no RF or scale. To be able to determine ground distance on such a map, the RF must be determined. There are two ways to do this:

(1) **Comparison with Ground Distance.**

(a) Measure the distance between two points on the map—map distance (MD).

(b) Determine the horizontal distance between these same two points on the ground—ground distance (GD).

(c) Use the RF formula and remember that RF must be in the general form:

$$\text{RF} = \frac{1}{X} = \frac{\text{MD}}{\text{GD}}$$

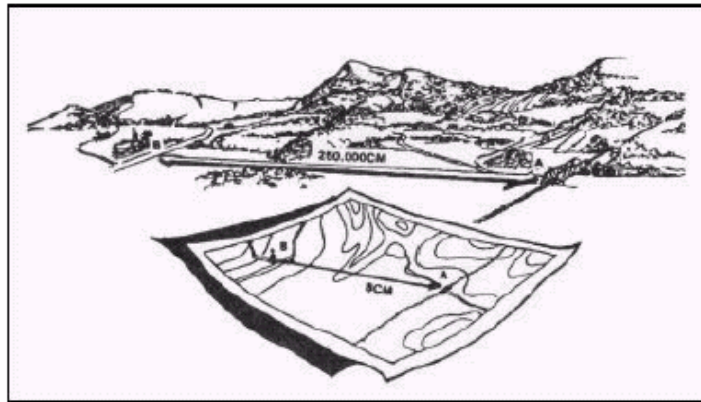


Figure 5-1. Converting map distance to ground distance.

(d) Both the MD and the GD must be in the same unit of measure and the MD must be reduced to 1.

EXAMPLE:

MD = 4.32 centimeters
GD = 2.16 kilometers
(216,000 centimeters)

$$\text{RF} = \frac{1}{\frac{4.32}{216,000}}$$

or

$$\frac{216,000}{4.32} = 50,000$$

therefore

$$\text{RF} = \frac{1}{50,000} \text{ or } 1:50,000$$

(2) Comparison With Another Map of the Same Area that Has an RF.

(a) Select two points on the map with the unknown RF. Measure the distance (MD) between them.

(b) Locate those same two points on the map that have the known RF. Measure the distance (MD) between them. Using the RF for this map, determine GD, which is the same for both maps.

(c) Using the GD and the MD from the first map, determine the RF using the formula:

$$\text{RF} = \frac{1}{\frac{\text{MD}}{\text{GD}}}$$

d. Occasionally it may be necessary to determine map distance from a known ground distance and the RF:

$$MD = \frac{GD}{\text{Denominator or RF}}$$

Ground Distance = 2,200 meters

RF = 1:50,000

$$MD = \frac{2,200 \text{ meters}}{50,000}$$

MD = 0.044 meters x 100 (centimeters per meter)

MD = 4.4 centimeters

e. When determining ground distance from a map, the scale of the map affects the accuracy. As the scale becomes smaller, the accuracy of measurement decreases because some of the features on the map must be exaggerated so that they may be readily identified.

5-2. GRAPHIC (BAR) SCALES

A graphic scale is a ruler printed on the map and is used to convert distances on the map to actual ground distances. The graphic scale is divided into two parts. To the right of the zero, the scale is marked in full units of measure and is called the primary scale. To the left of the zero, the scale is divided into tenths and is called the extension scale. Most maps have three or more graphic scales, each using a different unit of measure (Figure 5-2). When using the graphic scale, be sure to use the correct scale for the unit of measure desired.

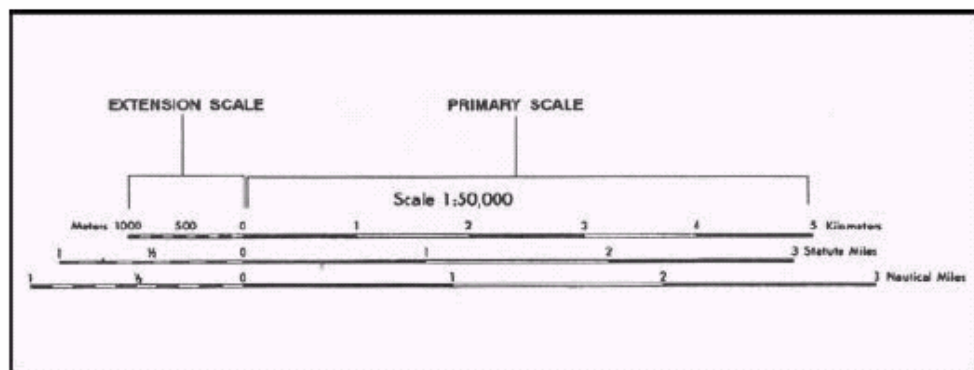


Figure 5-2. Using a graphic (bar) scale.

a. To determine straight-line distance between two points on a map, lay a straight-edged piece of paper on the map so that the edge of the paper touches both points and extends past them. Make a tick mark on the edge of the paper at each point (Figure 5-3).

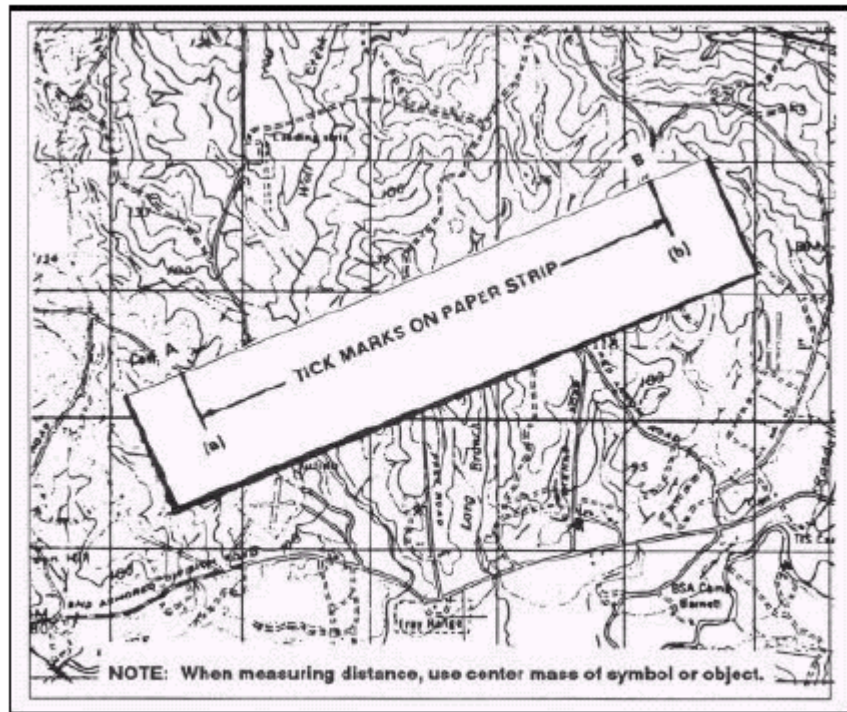


Figure 5-3. Transferring map distance to paper strip.

b. To convert the map distance to ground distance, move the paper down to the graphic bar scale, and align the right tick mark (b) with a printed number in the primary scale so that the left tick mark (a) is in the extension scale (Figure 5-4).

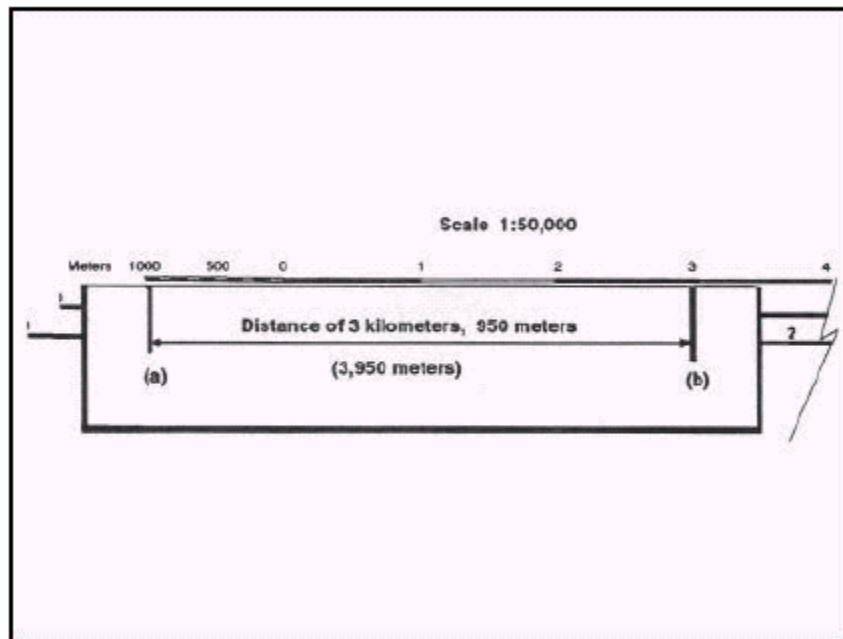


Figure 5-4. Measuring straight-line map distance.

c. The right tick mark (b) is aligned with the 3,000-meter mark in the primary scale, thus the distance is at least 3,000 meters. To determine the distance between the two points to the nearest 10 meters, look at the extension scale. The extension scale is numbered with zero at the right and increases to the left. When using the extension scale, always read right to left (Figure 5-4). From the zero left to the beginning of the first shaded area is 100 meters. From the beginning of the shaded square to the end of the shaded square is 100 to 200 meters. From the end of the first shaded square to the beginning of the second shaded square is 200 to 300 meters. Remember, the distance in the extension scale increases from right to left.

d. To determine the distance from the zero to tick mark (a), divide the distance inside the squares into tenths (Figure 5-4). As you break down the distance between the squares in the extension scale into tenths, you will see that tick mark (a) is aligned with the 950-meter mark. Adding the distance of 3,000 meters determined in the primary scale to the 950 meters you determined by using the extension scale, we find that the total distance between points (a) and (b) is 3,950 meters.

e. To measure distance along a road, stream, or other curved line, the straight edge of a piece of paper is used. In order to avoid confusion concerning the point to begin measuring from and the ending point, an eight-digit coordinate should be given for both the starting and ending points. Place a tick mark on the paper and map at the beginning point from which the curved line is to be measured. Align the edge of the paper along a straight portion and make a tick mark on both map and paper when the edge of the paper leaves the straight portion of the line being measured (Figure 5-5A, page 5-7).

f. Keeping both tick marks together (on paper and map), place the point of the pencil close to the edge of the paper on the tick mark to hold it in place and pivot the paper until another straight portion of the curved line is aligned with the edge of the paper. Continue in this manner until the measurement is completed (Figure 5-5B, page 5-7).

g. When you have completed measuring the distance, move the paper to the graphic scale to determine the ground distance. The only tick marks you will be measuring the distance between are tick marks (a) and (b). The tick marks in between are not used (Figure 5-5C, page 5-7).

h. There may be times when the distance you measure on the edge of the paper exceeds the graphic scale. In this case, there are different techniques you can use to determine the distance.

(1) One technique is to align the right tick mark (b) with a printed number in the primary scale, in this case the 5. You can see that from point (a) to point (b) is more than 6,000 meters when you add the 1,000 meters in the extension scale. To determine the exact distance to the nearest 10 meters, place a tick mark (c) on the edge of the paper at the end of the extension scale (Figure 5-6A, page 5-8). You know that from point (b) to point (c) is 6,000 meters. With the tick mark (c) placed on the edge of the paper at the end of the extension scale, slide the paper to the right. Remember the distance in the extension is always read from right to left. Align tick mark (c) with zero and then measure the distance between tick marks (a) and (c). The distance between tick marks (a) and (c) is 420 meters. The total ground distance between start and finish points is 6,420 meters (Figure 5-6B, page 5-8).

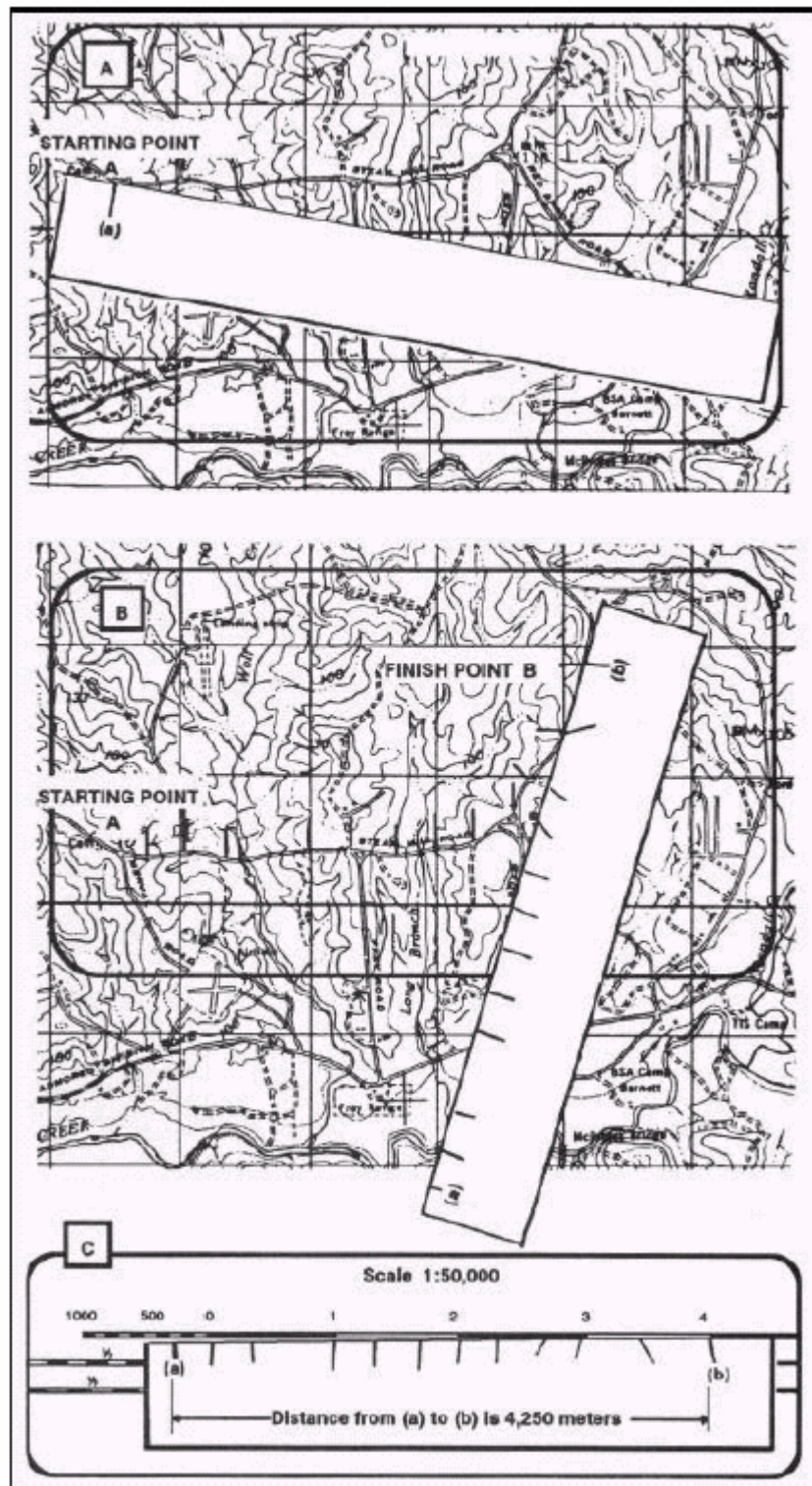


Figure 5-5. Measuring a curved line.

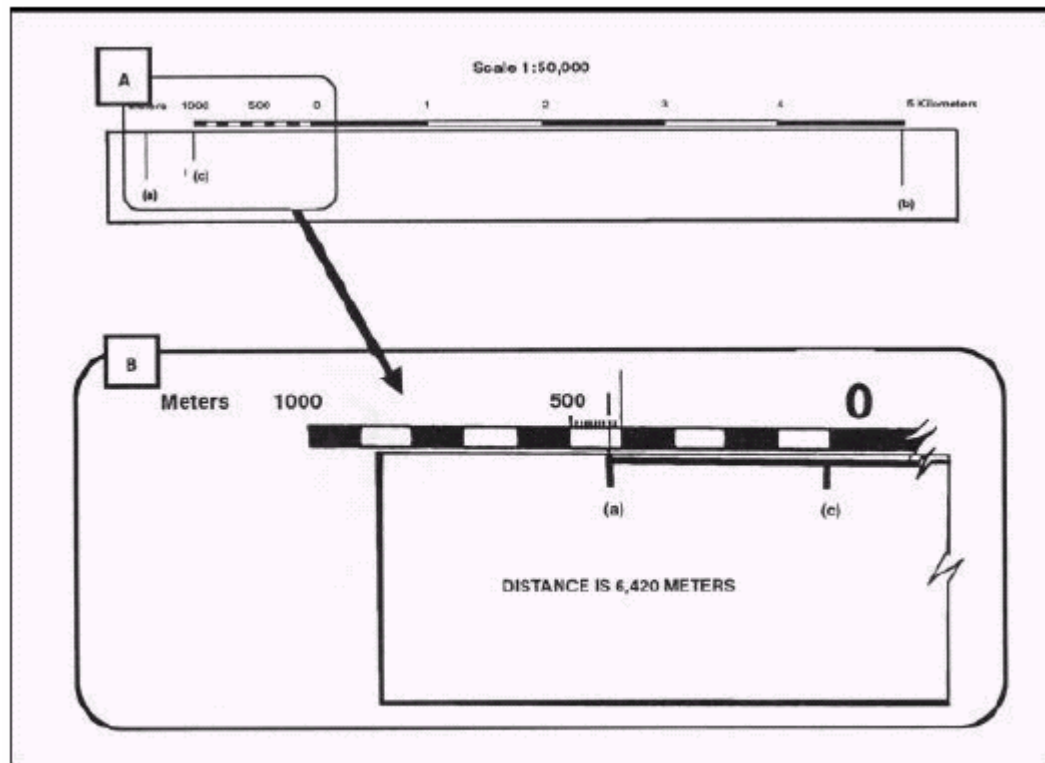


Figure 5-6. Determining the exact distance.

(2) Another technique that may be used to determine exact distance between two points when the edge of the paper exceeds the bar scale is to slide the edge of the paper to the right until tick mark (a) is aligned with the edge of the extension scale. Make a tick mark on the paper, in line with the 2,000-meter mark (c) (Figure 5-7A). Then slide the edge of the paper to the left until tick mark (b) is aligned with the zero. Estimate the 100-meter increments into 10-meter increments to determine how many meters tick mark (c) is from the zero line (Figure 5-7B). The total distance would be 3,030 meters.

(3) At times you may want to know the distance from a point on the map to a point off the map. In order to do this, measure the distance from the start point to the edge of the map. The marginal notes give the road distance from the edge of the map to some towns, highways, or junctions off the map. To determine the total distance, add the distance measured on the map to the distance given in the marginal notes. Be sure the unit of measure is the same.

(4) When measuring distance in statute or nautical miles, round it off to the nearest one tenth of a mile and make sure the appropriate bar scale is used.

(5) Distance measured on a map does not take into consideration the rise and fall of the land. All distances measured by using the map and graphic scales are flat distances. Therefore, the distance measured on a map will increase when actually measured on the ground. This must be taken into consideration when navigating across country.

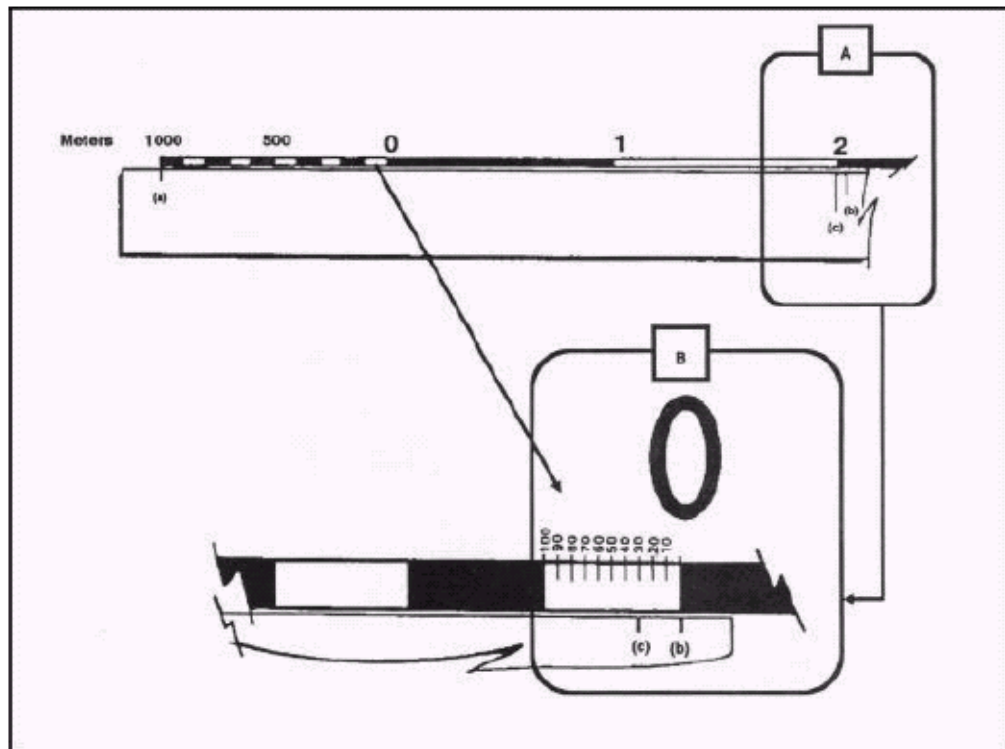


Figure 5-7. Reading the extension scale.

i. The amount of time required to travel a certain distance on the ground is an important factor in most military operations. This can be determined if a map of the area is available and a graphic time-distance scale is constructed for use with the map as follows:

R = Rate of travel (speed)

T = Time

D = Distance (ground distance)

$$T = \frac{D}{R}$$

For example, if an infantry unit is marching at an average rate (R) of 4 kilometers per hour, it will take about 3 hours (T) to travel 12 kilometers.

$$\frac{12 (D)}{4 (R)} = 3 (T)$$

j. To construct a time-distance scale (Figure 5-8A), knowing your length of march, rate of speed, and map scale, that is, 12 kilometers at 3 kilometers per hour on a 1:50,000-scale map, use the following process:

(1) Mark off the total distance on a line by referring to the graphic scale of the map or, if this is impracticable, compute the length of the line as follows:

(a) Convert the ground distance to centimeters: 12 kilometers x 100,000 (centimeters per kilometer) = 1,200,000 centimeters.

(b) Find the length of the line to represent the distance at map scale—

$$MD = \frac{1}{50,000} = \frac{1,200,000}{50,000} = 24 \text{ centimeters}$$

(c) Construct a line 24 centimeters in length (Figure 5-8A).

(2) Divide the line by the rate of march into three parts (Figure 5-8B), each part representing the distance traveled in one hour, and label.

(3) Divide the scale extension (left portion) into the desired number of lesser time divisions—

1-minute divisions — 60

5-minute divisions — 12

10-minute divisions — 6

(4) Figure 5-8C shows a 5-minute interval scale. Make these divisions in the same manner as for a graphic scale. The completed scale makes it possible to determine where the unit will be at any given time. However, it must be remembered that this scale is for one specific rate of march only, 4 kilometers per hour.

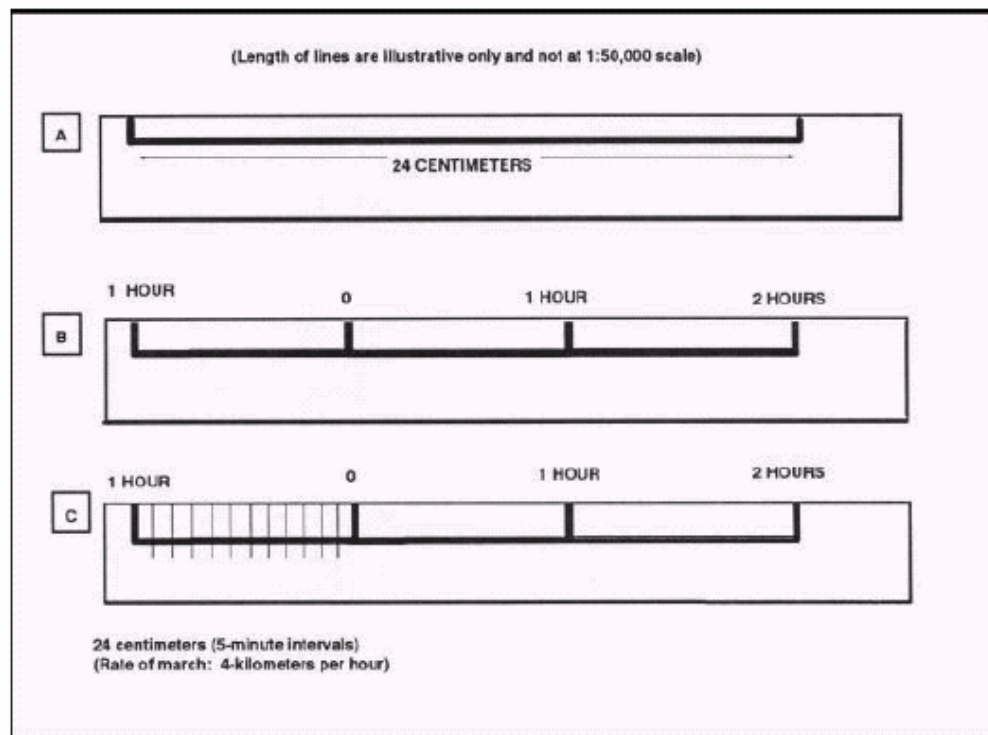


Figure 5-8. Constructing a time-distance scale.

CHAPTER 6

DIRECTION

Being in the right place at the prescribed time is necessary to successfully accomplish military missions. Direction plays an important role in a soldier's everyday life. It can be expressed as right, left, straight ahead, and so forth; but then the question arises, "To the right of what?" This chapter defines the word azimuth and the three different norths. It explains in detail how to determine the grid and the magnetic azimuths with the use of the protractor and the compass. It explains the use of some field-expedient methods to find directions, the declination diagram, and the conversion of azimuths from grid to magnetic and vice versa. It also includes some advanced aspects of map reading, such as intersection, resection, modified resection, and polar plots.

6-1. METHODS OF EXPRESSING DIRECTION

Military personnel need a way of expressing direction that is accurate, is adaptable to any part of the world, and has a common unit of measure. Directions are expressed as units of angular measure.

a. **Degree.** The most common unit of measure is the degree (°) with its subdivisions of minutes (') and seconds (").

1 degree = 60 minutes.

1 minute = 60 seconds.

b. **Mil.** Another unit of measure, the mil (abbreviated m/), is used mainly in artillery, tank, and mortar gunnery. The mil expresses the size of an angle formed when a circle is divided into 6,400 angles, with the vertex of the angles at the center of the circle. A relationship can be established between degrees and mils. A circle equals 6400 mils divided by 360 degrees, or 17.78 mils per degree. To convert degrees to mils, multiply degrees by 17.78.

c. **Grad.** The grad is a metric unit of measure found on some foreign maps. There are 400 grads in a circle (a 90-degree right angle equals 100 grads). The grad is divided into 100 centesimal minutes (centigrads) and the minute into 100 centesimal seconds (milligrads).

6-2. BASE LINES

In order to measure something, there must always be a starting point or zero measurement. To express direction as a unit of angular measure, there must be a starting point or zero measure and a point of reference. These two points designate the base or reference line. There are three base lines—true north, magnetic north, and grid north. The most commonly used are magnetic and grid.

a. **True North.** A line from any point on the earth's surface to the north pole. All lines of longitude are true north lines. True north is usually represented by a star (Figure 6-1, page 6-2).

b. **Magnetic North.** The direction to the north magnetic pole, as indicated by the northseeking needle of a magnetic instrument. The magnetic north is usually symbolized by

a line ending with half of an arrowhead (Figure 6-1). Magnetic readings are obtained with magnetic instruments, such as lensatic and M2 compasses.

c. **Grid North.** The north that is established by using the vertical grid lines on the map. Grid north may be symbolized by the letters GN or the letter “y” (Figure 6-1).

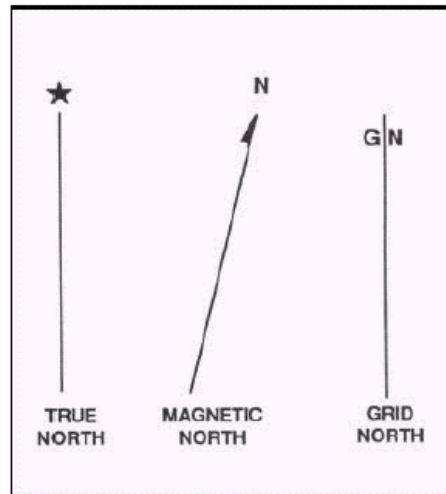


Figure 6-1. Three norths.

6-3. AZIMUTHS

An azimuth is defined as a horizontal angle measured clockwise from a north base line. This north base line could be true north, magnetic north, or grid north. The azimuth is the most common military method to express direction. When using an azimuth, the point from which the azimuth originates is the center of an imaginary circle (Figure 6-2). This circle is divided into 360 degrees or 6400 mils (Appendix G).

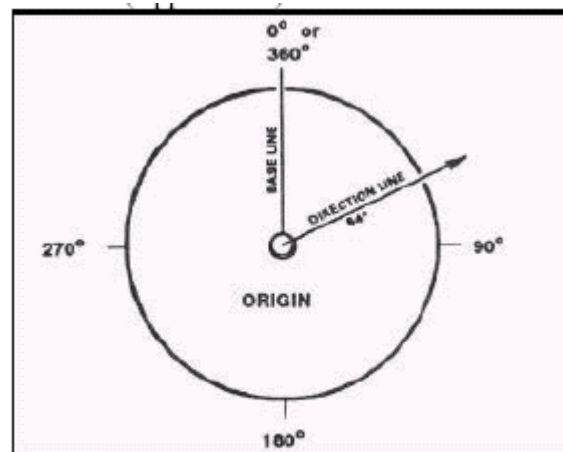


Figure 6-2. Origin of azimuth circle.

a. **Back Azimuth.** A back azimuth is the opposite direction of an azimuth. It is comparable to doing “about face.” To obtain a back azimuth from an azimuth, add 180 degrees if the azimuth is 180 degrees or less, or subtract 180 degrees if the azimuth is 180 degrees or more (Figure 6-3). The back azimuth of 180 degrees may be stated as 0 degrees or 360 degrees. For mils, if the azimuth is less than 3200 mils, add 3200 mils, if the azimuth is more than 3200 mils, subtract 3200 mils.

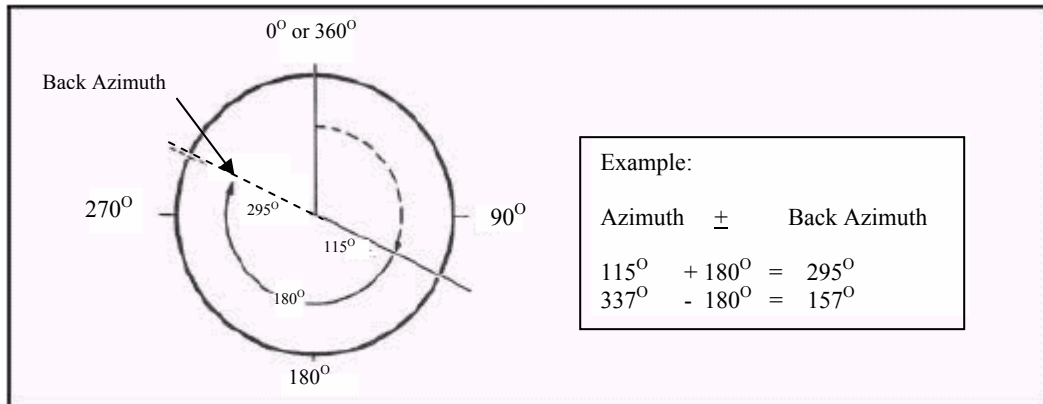


Figure 6-3. Back azimuth.

WARNING

When converting azimuths into back azimuths, extreme care should be exercised when adding or subtracting the 180 degrees. A simple mathematical mistake could cause disastrous consequences.

b. **Magnetic Azimuth.** The magnetic azimuth is determined by using magnetic instruments, such as lensatic and M2 compasses. Refer to Chapter 9, paragraph 4, for details.

c. **Field-Expedient Methods.** Several field-expedient methods to determine direction are discussed in Chapter 9, paragraph 5.

6-4. GRID AZIMUTHS

When an azimuth is plotted on a map between point A (starting point) and point B (ending point), the points are joined together by a straight line. A protractor is used to measure the angle between grid north and the drawn line, and this measured azimuth is the grid azimuth (Figure 6-4).

WARNING

When measuring azimuths on a map, remember that you are measuring from a starting point to an ending point. If a mistake is made and the reading is taken from then ending point, the grid azimuth will be opposite, thus causing the used to go in the wrong direction

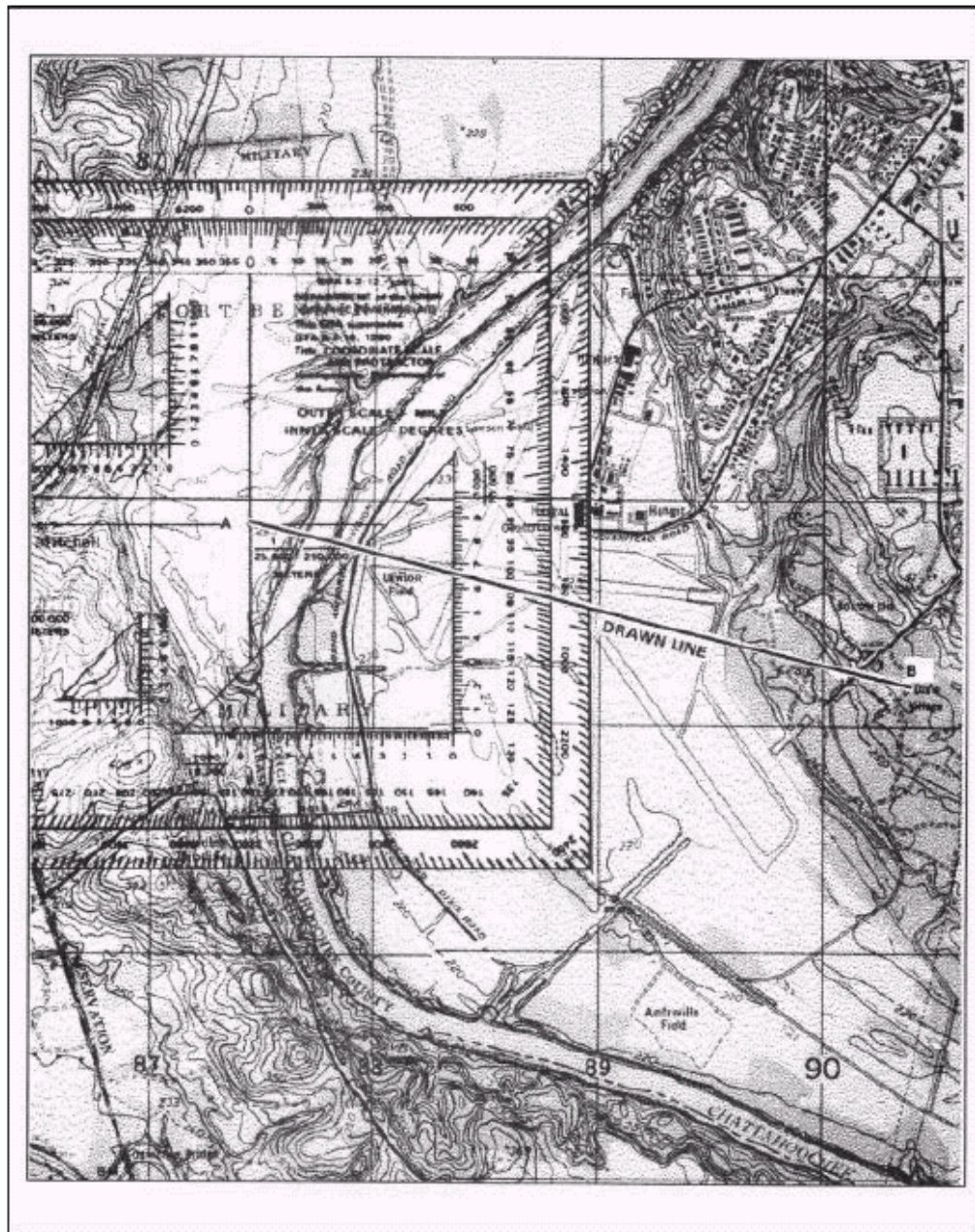


Figure 6-4. Measure an azimuth

6-5. PROTRACTOR

There are several types of protractors—full circle, half circle, square, and rectangular (Figure 6-5). All of them divide the circle into units of angular measure, and each has a scale around the outer edge and an index mark. The index mark is the center of the protractor circle from which all directions are measured.

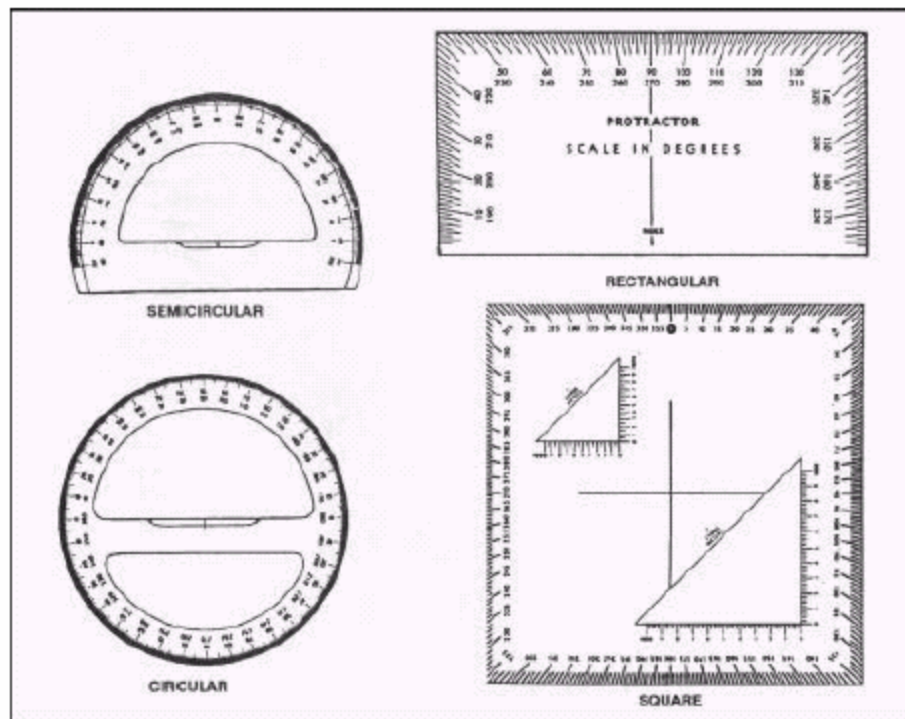


Figure 6-5. Types of protractors.

a. The military protractor, GTA 5-2-12, contains two scales: one in degrees (inner scale) and one in mils (outer scale). This protractor represents the azimuth circle. The degree scale is graduated from 0 to 360 degrees; each tick mark on the degree scale represents one degree. A line from 0 to 180 degrees is called the base line of the protractor. Where the base line intersects the horizontal line, between 90 and 270 degrees, is the index or center of the protractor (Figure 6-6).

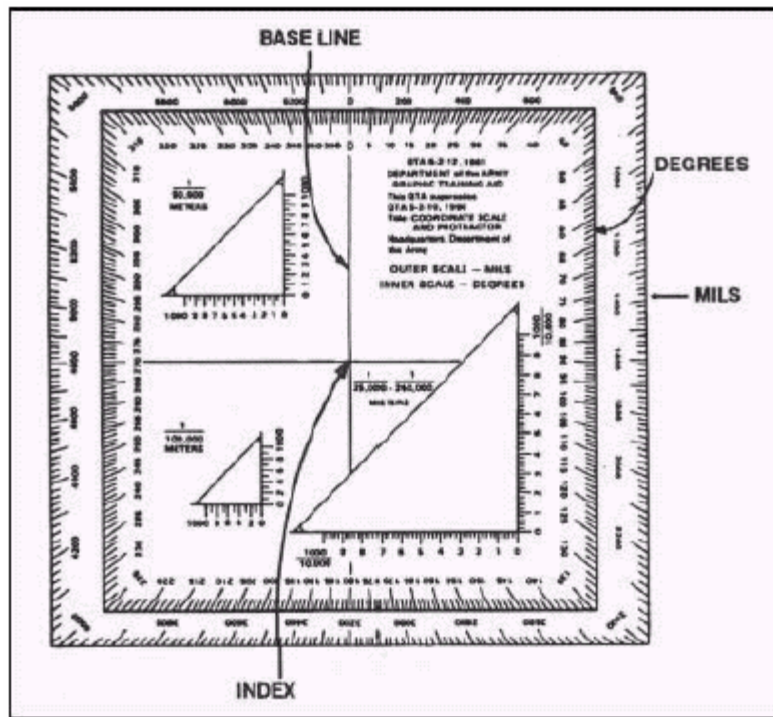


Figure 6-6. Military protractor

b. When using the protractor, the base line is always oriented parallel to a north-south grid line. The 0- or 360-degree mark is always toward the top or north on the map and the 90° mark is to the right.

(1) To determine the grid azimuth—

(a) Draw a line connecting the two points (A and B).

(b) Place the index of the protractor at the point where the drawn line crosses a vertical (north-south) grid line.

(c) Keeping the index at this point, align the 0- to 180-degree line of the protractor on the vertical grid line.

(d) Read the value of the angle from the scale; this is the grid azimuth from point A to point B (Figure 6-4).

(2) To plot an azimuth from a known point on a map (Figure 6-7)—

(a) Convert the azimuth from magnetic to grid, if necessary. (See paragraph 6-6.)

(b) Place the protractor on the map with the index mark at the center of mass of the known point and the base line parallel to a north-south grid line.

(c) Make a mark on the map at the desired azimuth.

(d) Remove the protractor and draw a line connecting the known point and the mark on the map. This is the grid direction line (azimuth).

NOTE: When measuring an azimuth, the reading is always to the nearest degree or 10 mils. Distance does not change an accurately measured azimuth.

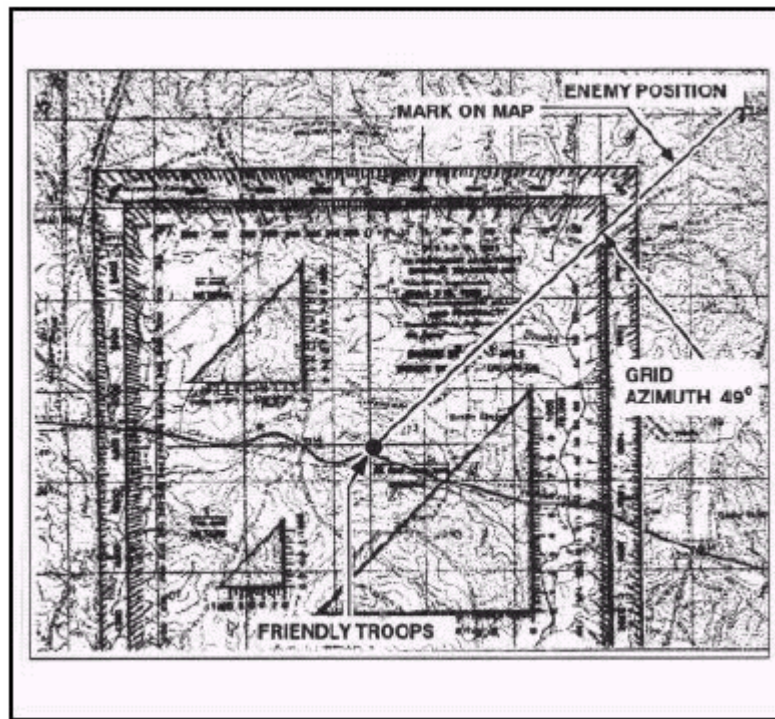


Figure 6-7. Plotting an azimuth on the map.

c. To obtain an accurate reading with the protractor (to the nearest degree or 10 mils), there are two techniques to check that the base line of the protractor is parallel to a northsouth grid line.

(1) Place the protractor index where the azimuth line cuts a north-south grid line, aligning the base line of the protractor directly over the intersection of the azimuth line with the north-south grid line. The user should be able to determine whether the initial azimuth reading was correct.

(2) The user should re-read the azimuth between the azimuth and north-south grid line to check the initial azimuth.

(3) Note that the protractor is cut at both the top and bottom by the same north-south grid line. Count the number of degrees from the 0-degree mark at the top of the protractor to this north-south grid line and then count the number of degrees from the 180-degree mark at the bottom of the protractor to this same grid line. If the two counts are equal, the protractor is properly aligned.

6-6. DECLINATION DIAGRAM

Declination is the angular difference between any two norths. If you have a map and a compass, the one of most interest to you will be between magnetic and grid north. The declination diagram (Figure 6-8) shows the angular relationship, represented by prongs, among grid, magnetic, and true norths. While the relative positions of the prongs are correct, they are seldom plotted to scale. Do not use the diagram to measure a numerical value. This

value will be written in the map margin (in both degrees and mils) beside the diagram.

a. **Location.** A declination diagram is a part of the information in the lower margin on most larger maps. On medium-scale maps, the declination information is shown by a note in the map margin.

b. **Grid-Magnetic Angle.** The G-M angle value is the angular size that exists between grid north and magnetic north. It is an arc, indicated by a dashed line, that connects the gridnorth and magnetic-north prongs. This value is expressed to the nearest 1/2 degree, with mil equivalents shown to the nearest 10 mils. The G-M angle is important to the map reader/land navigator because azimuths translated between map and ground will be in error by the size of the declination angle if not adjusted for it.

c. **Grid Convergence.** An arc indicated by a dashed line connects the prongs for true north and grid north. The value of the angle for the center of the sheet is given to the nearest full minute with its equivalent to the nearest mil. These data are shown in the form of a gridconvergence note.

d. **Conversion.** There is an angular difference between the grid north and the magnetic north. Since the location of magnetic north does not correspond exactly with the grid-north lines on the maps, a conversion from magnetic to grid or vice versa is needed.

(1) **With Notes.** Simply refer to the conversion notes that appear in conjunction with the diagram explaining the use of the G-M angle (Figure 6-8). One note provides instructions for converting magnetic azimuth to grid azimuth; the other, for converting grid azimuth to magnetic azimuth. The conversion (add or subtract) is governed by the direction of the magnetic-north prong relative to that of the north-grid prong.

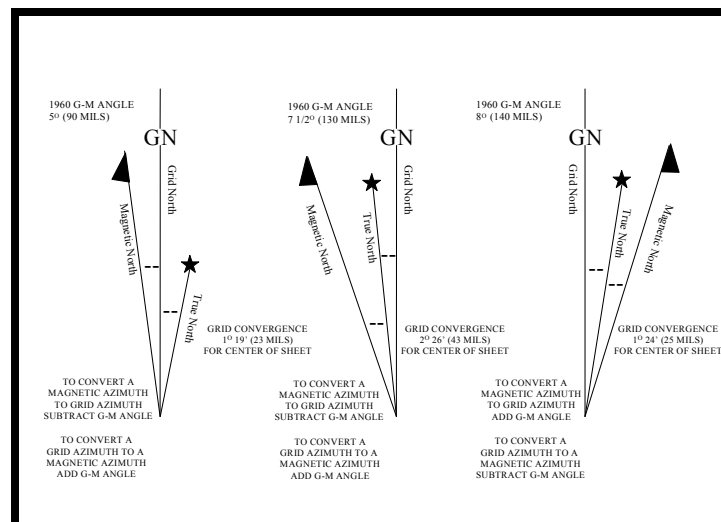


Figure 6-8. Declination diagrams.

(2) **Without Notes.** In some cases, there are no declination conversion notes on the margin of the map; it is necessary to convert from one type of declination to another. A magnetic compass gives a magnetic azimuth; but in order to plot this line on a gridded map, the magnetic azimuth value must be changed to grid azimuth. The declination diagram is used for these conversions. A rule to remember when solving such problems is this:

No matter where the azimuth line points, the angle to it is always measured clockwise from the reference direction (base line). With this in mind, the problem is solved by the following steps:

(a) Draw a vertical or grid-north line (prong). Always align this line with the vertical lines on a map (Figure 6-9).

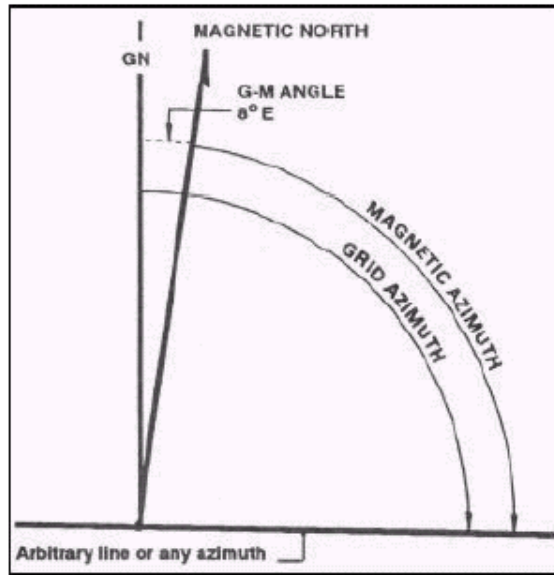


Figure 6-9. Declination diagram with arbitrary line.

(b) From the base of the grid-north line (prong), draw an arbitrary line (or any azimuth line) at a roughly right angle to north, regardless of the actual value of the azimuth in degrees (Figure 6-9).

(c) Examine the declination diagram on the map and determine the direction of the magnetic north (right-left or east-west) relative to that of the grid-north prong. Draw a magnetic prong from the apex of the grid-north line in the desired direction (Figure 6-9).

(d) Determine the value of the G-M angle. Draw an arc from the grid prong to the magnetic prong and place the value of the G-M angle (Figure 6-9).

(e) Complete the diagram by drawing an arc from each reference line to the arbitrary line. A glance at the completed diagram shows whether the given azimuth or the desired azimuth is greater, and thus whether the known difference between the two must be added or subtracted.

(f) The inclusion of the true-north prong in relationship to the conversion is of little importance.

e. **Applications.** Remember, there are no negative azimuths on the azimuth circle. Since 0 degree is the same as 360 degrees, then 2 degrees is the same as 362 degrees. This is because 2 degrees and 362 degrees are located at the same point on the azimuth circle. The grid azimuth can now be converted into a magnetic azimuth because the grid azimuth is now larger than the G-M angle.

(1) When working with a map having an east G-M angle:

- (a) To plot a magnetic azimuth on a map, first change it to a grid azimuth (Figure 6-10).

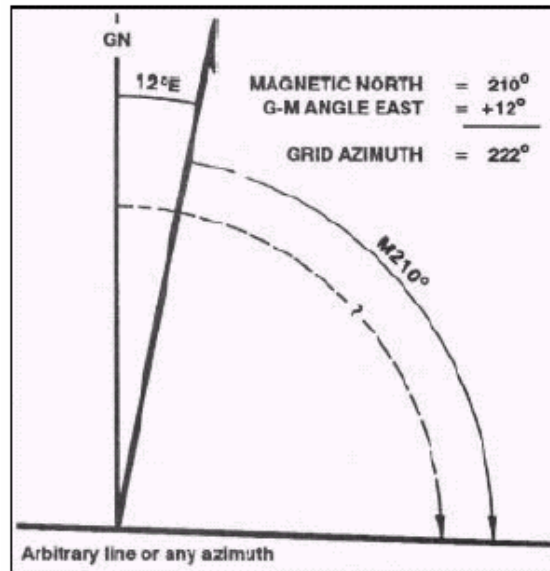


Figure 6-10. Converting to grid azimuth.

- (b) To use a magnetic azimuth in the field with a compass, first change the grid azimuth plotted on a map to a magnetic azimuth (Figure 6-11).

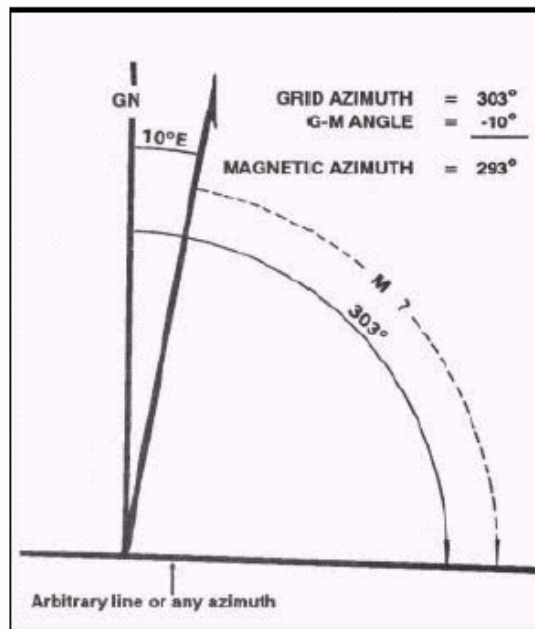


Figure 6-11. Converting to magnetic azimuth.

(c) Convert a grid azimuth to a magnetic azimuth when the G-M angle is greater than a grid azimuth (Figure 6-12).

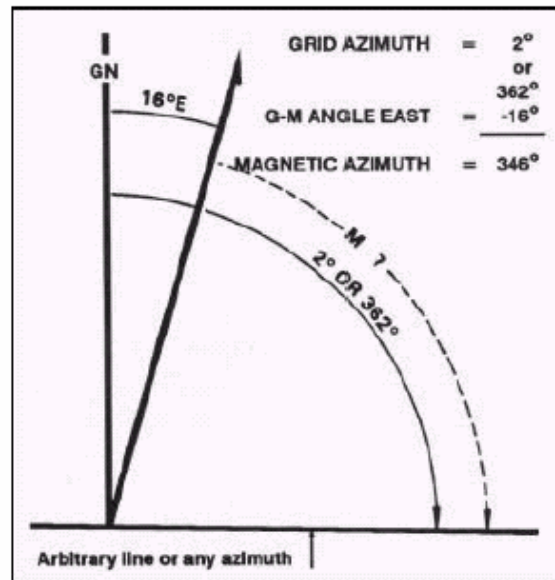


Figure 6-12. Converting to a magnetic azimuth when the G-M angle is greater.

(2) When working with a map having a west G-M angle:

(a) To plot a magnetic azimuth on a map, first convert it to a grid azimuth (Figure 6-13).

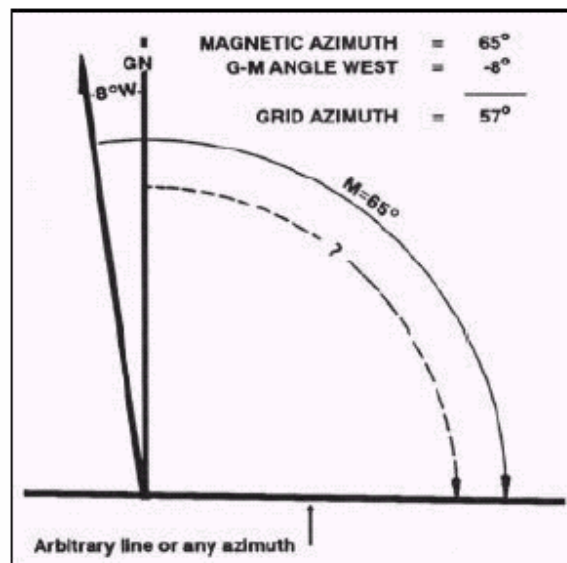


Figure 6-13. Converting to a grid azimuth on a map.

(b) To use a magnetic azimuth in the field with a compass, change the grid azimuth plotted on a map to a magnetic azimuth (Figure 6-14).

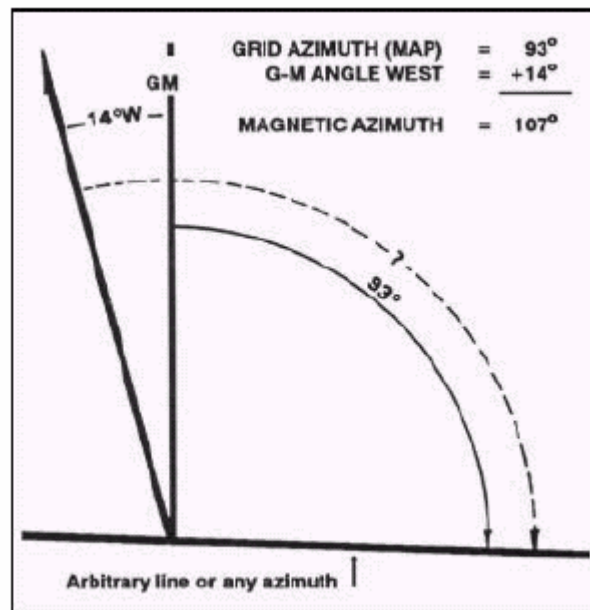


Figure 6-14. Converting to a magnetic azimuth on a map.

(c) Convert a magnetic azimuth when the G-M angle is greater than the magnetic azimuth (Figure 6-15).

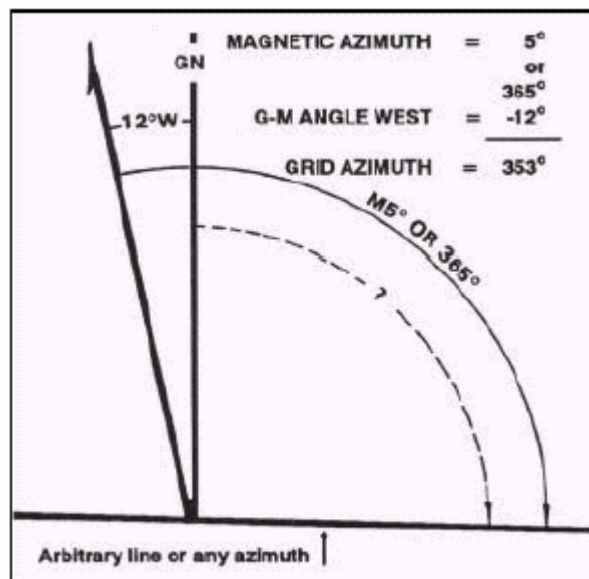


Figure 6-15. Converting to a grid azimuth when the G-M angle is greater.

(3) The G-M angle diagram should be constructed and used each time the conversion of azimuth is required. Such procedure is important when working with a map for the first time. It also may be convenient to construct a G-M angle conversion table on the margin of the map.

NOTE: When converting azimuths, exercise extreme care when adding and subtracting the G-M angle. A simple mistake of 1° could be significant in the field.

6-7. INTERSECTION

Intersection is the location of an unknown point by successively occupying at least two (preferably three) known positions on the ground and then map sighting on the unknown location. It is used to locate distant or inaccessible points or objects such as enemy targets and danger areas. There are two methods of intersection: the map and compass method and the straightedge method (Figures 6-16 and 6-17 on pages 6-14 and 6-15).

a. When using the map and compass method—

(1) Orient the map using the compass.

(2) Locate and mark your position on the map,

(3) Determine the magnetic azimuth to the unknown position using the compass.

(4) Convert the magnetic azimuth to grid azimuth.

(5) Draw a line on the map from your position on this grid azimuth.

(6) Move to a second known point and repeat steps 1, 2, 3, 4, and 5.

(7) The location of the unknown position is where the lines cross on the map. Determine the grid coordinates to the desired accuracy.

b. The straight edge method is used when a compass is not available. When using it—

(1) Orient the map on a flat surface by the terrain association method.

(2) Locate and mark your position on the map.

(3) Lay a straight edge on the map with one end at the user's position (A) as a pivot point; then, rotate the straightedge until the unknown point is sighted along the edge.

(4) Draw a line along the straight edge

(5) Repeat the above steps at position (B) and check for accuracy.

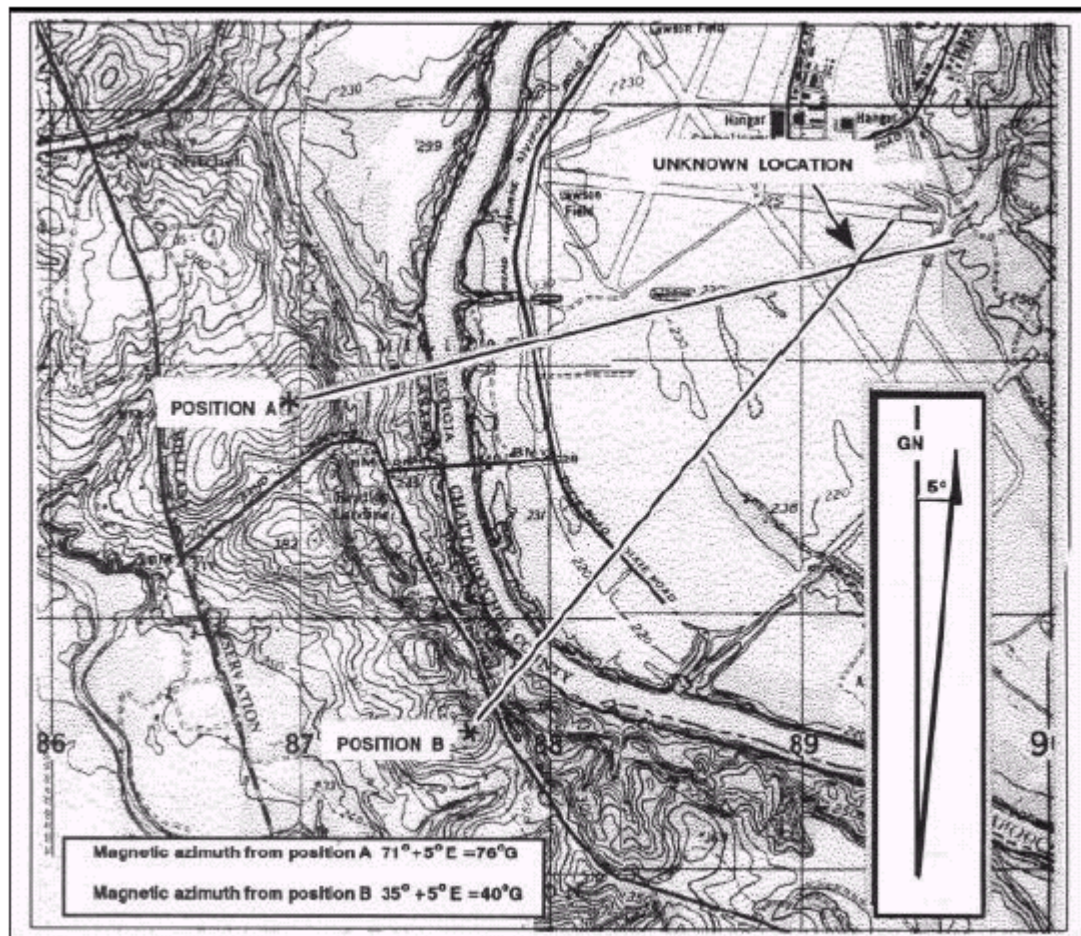


Figure 6-16. Intersection, using map and compass.

(6) The intersection of the lines on the map is the location of the unknown point (C). Determine the grid coordinates to the desired accuracy (Figure 6-17).

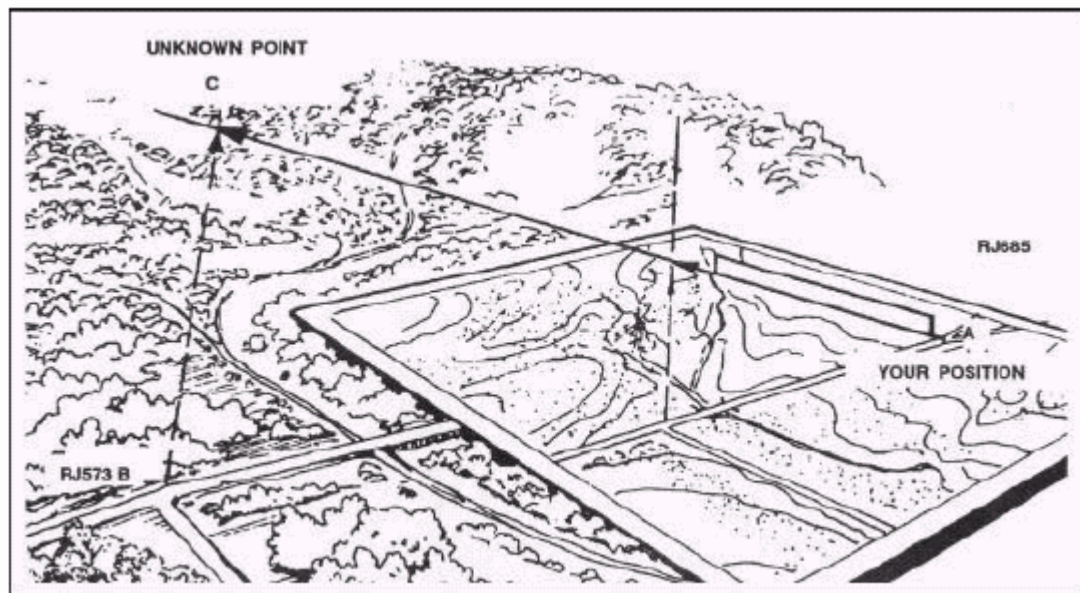


Figure 6-17. Intersection, using a straightedge.

6-8. RESECTION

Resection is the method of locating one's position on a map by determining the grid azimuth to at least two well-defined locations that can be pinpointed on the map. For greater accuracy, the desired method of resection would be to use three or more well-defined locations.

- a. When using the map and compass method (Figure 6-18)—
 - (1) Orient the map using the compass.
 - (2) Identify two or three known distant locations on the ground and mark them on the map.
 - (3) Measure the magnetic azimuth to one of the known positions from your location using a compass.
 - (4) Convert the magnetic azimuth to a grid azimuth.
 - (5) Convert the grid azimuth to a back azimuth. Using a protractor, draw a line for the back azimuth on the map from the known position back toward your unknown position.
 - (6) Repeat 3, 4, and 5 for a second position and a third position, if desired.

(7) The intersection of the lines is your location. Determine the grid coordinates to the desired accuracy.

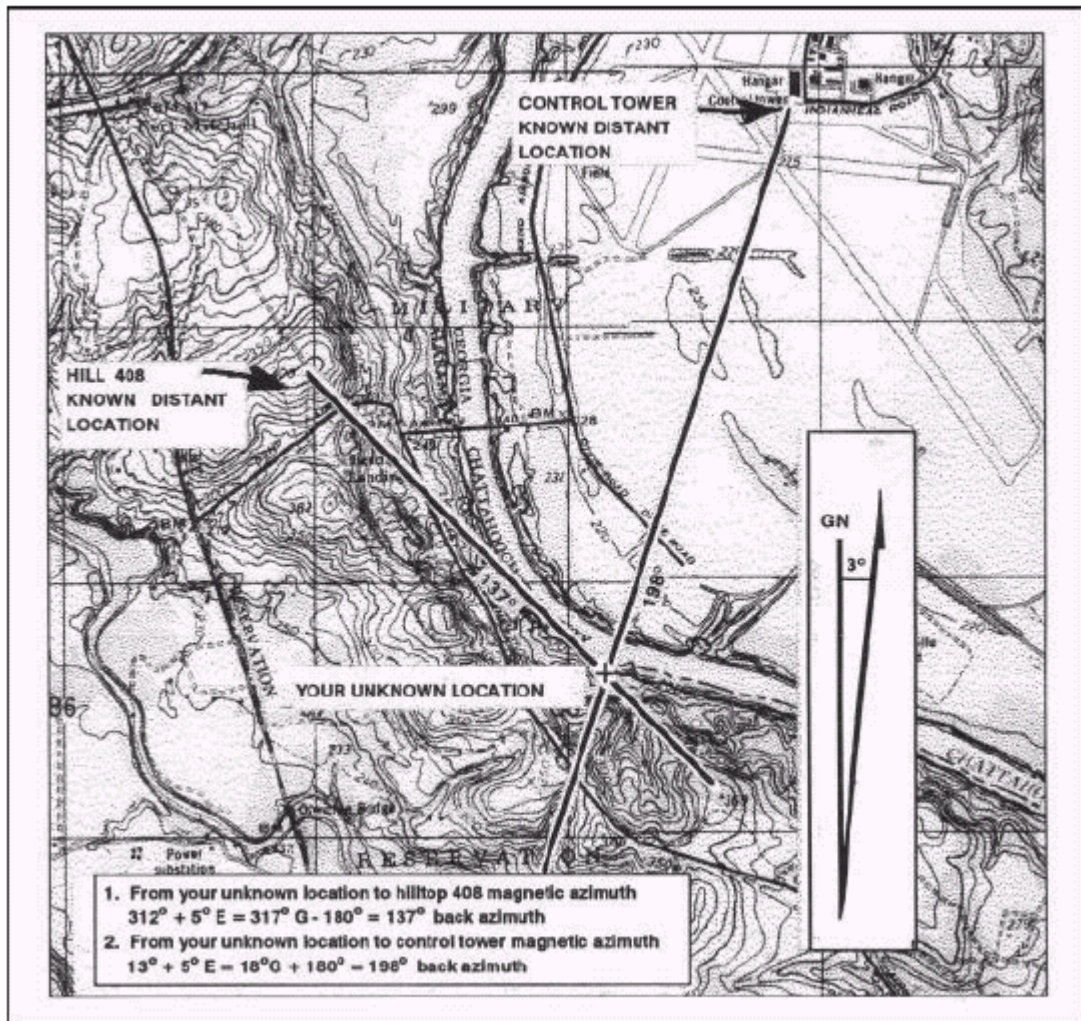


Figure 6-18. Resection with map and compass.

- a. When using the straightedge method (Figure 6-19)—
- (1) Orient the map on a flat surface by the terrain association method.
 - (2) Locate at least two known distant locations or prominent features on the ground and mark them on the map.
 - (3) Lay a straightedge on the map using a known position as a pivot point. Rotate the straightedge until the known position on the map is aligned with the known position on the ground.
 - (4) Draw a line along the straightedge away from the known position on the ground toward your position.
 - (5) Repeat 3 and 4 using a second known position.
 - (6) The intersection of the lines on the map is your location. Determine the grid coordinates to the desired accuracy.

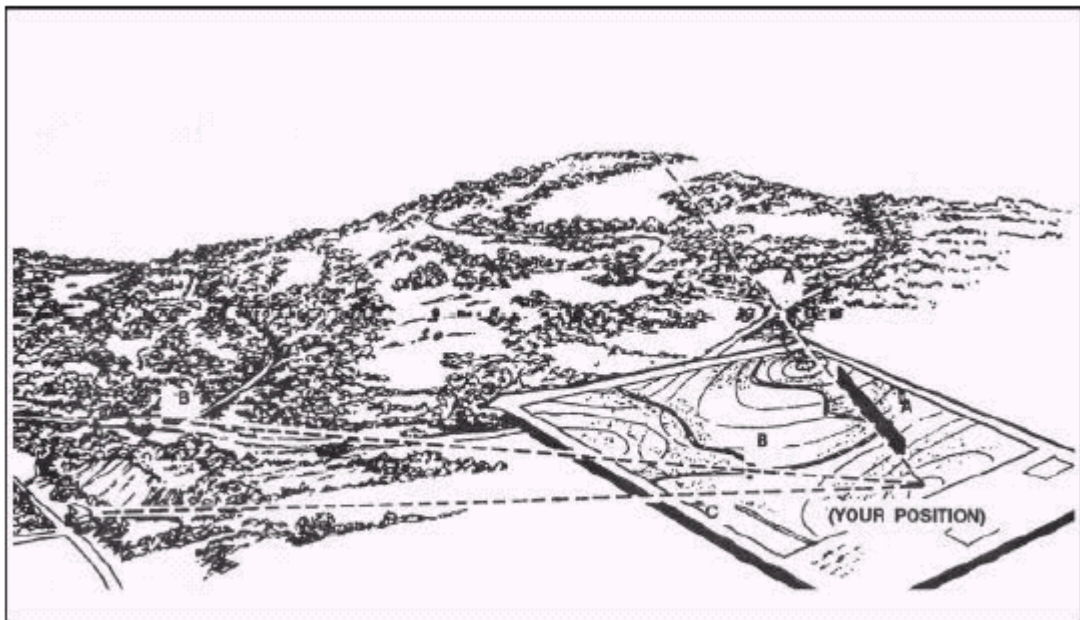


Figure 6-19. Resection with straightedge.

6-9. MODIFIED RESECTION

Modified resection is the method of locating one's position on the map when the person is located on a linear feature on the ground, such as a road, canal, or stream (Figure 6-20).

Proceed as follows:

- Orient the map using a compass or by terrain association.
- Find a distant point that can be identified on the ground and on the map.
- Determine the magnetic azimuth from your location to the distant known point.
- Convert the magnetic azimuth to a grid azimuth.
- Convert the grid azimuth to a back azimuth. Using a protractor, draw a line for the back azimuth on the map from the known position back toward your unknown position.
- The location of the user is where the line crosses the linear feature. Determine the grid coordinates to the desired accuracy.

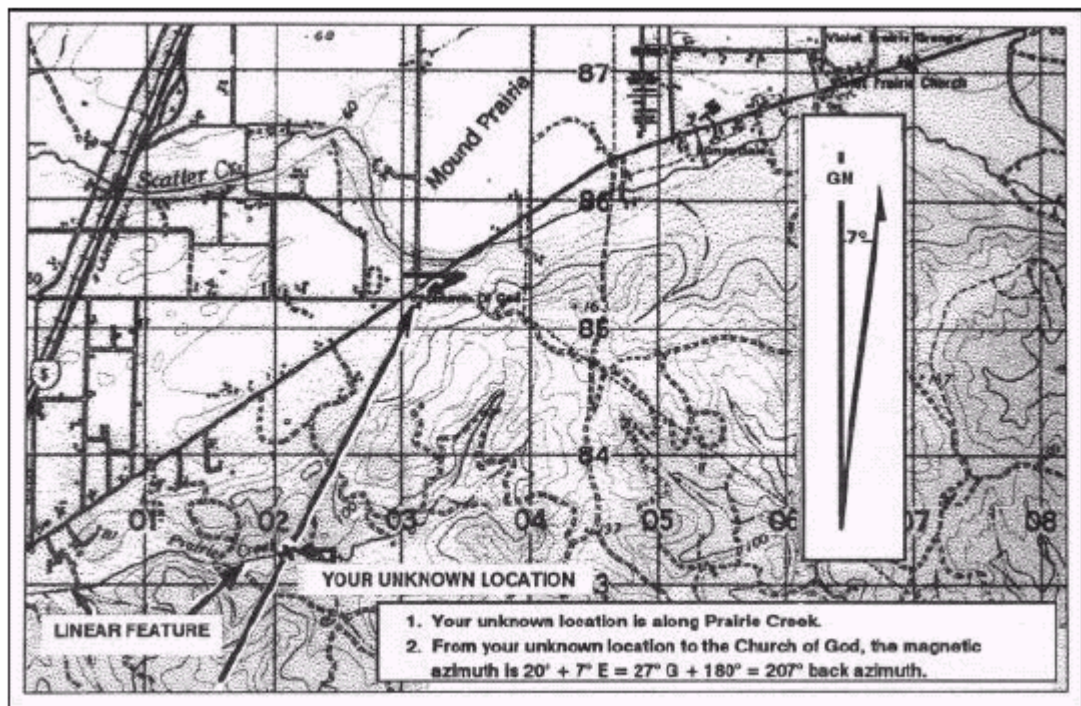


Figure 6-20. Modified resection.

6-10. POLAR COORDINATES

A method of locating or plotting an unknown position from a known point by giving a direction and a distance along that direction line is called polar coordinates. The following elements must be present when using polar coordinates (Figure 6-21).

- Present known location on the map.
- Azimuth (grid or magnetic).
- Distance (in meters).

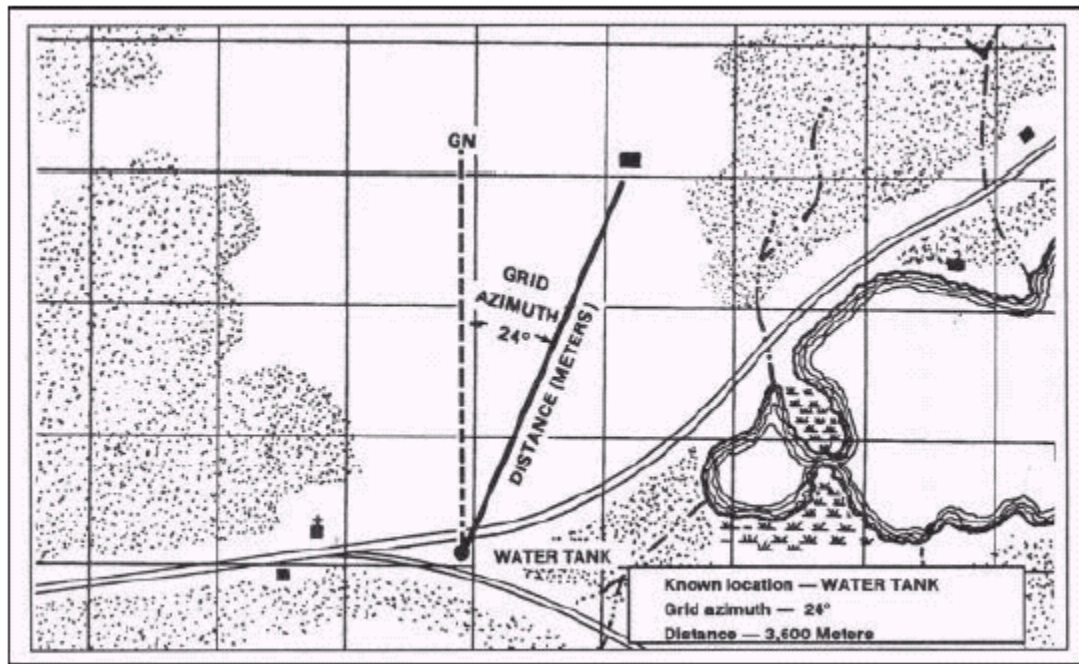


Figure 6-21. Polar plot.

Using the laser range finder to determine the range enhances your accuracy in determining the unknown position's location.

PART TWO LAND NAVIGATION

CHAPTER 9 NAVIGATION EQUIPMENT AND METHODS

Compasses are the primary navigation tools to use when moving in an outdoor world where there is no other way to find directions. Soldiers should be thoroughly familiar with the compass and its uses. Part One of this manual discussed the techniques of map reading. To complement these techniques, a mastery of field movement techniques is essential. This chapter describes the lensatic compass and its uses, and some of the field expedient methods used to find directions when compasses are not available.

9-1. TYPES OF COMPASSES

The **lensatic compass** is the most common and simplest instrument for measuring direction. It is discussed in detail in paragraph 9-2. The **artillery M2 compass** is a special-purpose instrument designed for accuracy; it will be discussed in Appendix G. The **wrist/pocket compass** is a small magnetic compass that can be attached to a wristwatch band. It contains a north-seeking arrow and a dial in degrees. A **protractor** can be used to determine azimuths when a compass is not available. However, it should be noted that when using the protractor on a map, only grid azimuths are obtained.

9-2. LENSATIC COMPASS

The lensatic compass (Figure 9-1) consists of three major parts: the cover, the base, and the lens.

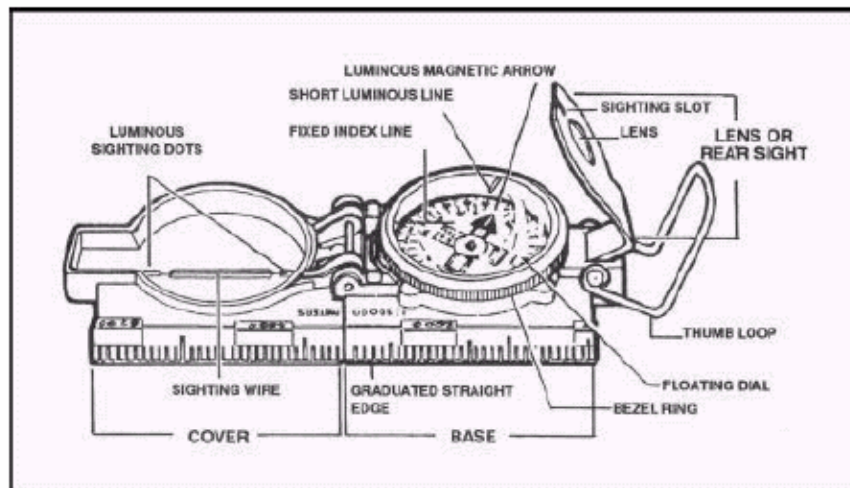


Figure 9-1. Lensatic compass.

a. **Cover.** The compass cover protects the floating dial. It contains the sighting wire (front sight) and two luminous sighting slots or dots used for night navigation.

b. **Base.** The body of the compass contains the following movable parts:

(1) The floating dial is mounted on a pivot so it can rotate freely when the compass is held level. Printed on the dial in luminous figures are an arrow and the letters E and W. The arrow always points to magnetic north and the letters fall at east (E) 90° and west (W) 270° on the dial. There are two scales; the outer scale denotes mils and the inner scale (normally in red) denotes degrees.

(2) Encasing the floating dial is a glass containing a fixed black index line.

(3) The bezel ring is a ratchet device that clicks when turned. It contains 120 clicks when rotated fully; each click is equal to 3°. A short luminous line that is used in conjunction with the north-seeking arrow during navigation is contained in the glass face of the bezel ring.

(4) The thumb loop is attached to the base of the compass.

c. **Lens.** The lens is used to read the dial, and it contains the rear-sight slot used in conjunction with the front for sighting on objects. The rear sight also serves as a lock and clamps the dial when closed for its protection. The rear sight must be opened more than 45° to allow the dial to float freely.

NOTE: When opened, the straightedge on the left side of the compass has a coordinate scale; the scale is 1:50,000 in newer compasses.

WARNING

Some older compasses will have a 1:25,000 scale. This scale can be used with a 1:50,000-scale map, but the values read must be halved. Check the scale.

9-3. COMPASS HANDLING

Compasses are delicate instruments and should be cared for accordingly.

a. **Inspection.** A detailed inspection is required when first obtaining and using a compass. One of the most important parts to check is the floating dial, which contains the magnetic needle. The user must also make sure the sighting wire is straight, the glass and crystal parts are not broken, the numbers on the dial are readable, and most important, that the dial does not stick.

b. **Effects of Metal and Electricity.** Metal objects and electrical sources can affect the performance of a compass. However, nonmagnetic metals and alloys do not affect compass readings. The following separation distances are suggested to ensure proper functioning of a compass:

High-tension power lines	55 meters.
Field gun, truck, or tank.....	18 meters.
Telegraph or telephone wires and barbed wire.....	10 meters.
Machine gun.....	2 meters.
Steel helmet or rifle.....	1/2 meter.

c. **Accuracy.** A compass in good working condition is very accurate. However, a compass has to be checked periodically on a known line of direction, such as a surveyed azimuth using a declination station. Compasses with more than 3° + variation should not be used.

d. **Protection.** If traveling with the compass unfolded, make sure the rear sight is fully folded down onto the bezel ring. This will lock the floating dial and prevent vibration, as well as protect the crystal and rear sight from damage.

9-4. USING A COMPASS

Magnetic azimuths are determined with the use of magnetic instruments, such as lensatic and M2 compasses. The techniques employed when using the lensatic compass are as follows:

a. **Using the Centerhold Technique.** First, open the compass to its fullest so that the cover forms a straightedge with the base. Move the lens (rear sight) to the rearmost position, allowing the dial to float freely. Next, place your thumb through the thumb loop, form a steady base with your third and fourth fingers, and extend your index finger along the side of the compass. Place the thumb of the other hand between the lens (rear sight) and the bezel ring; extend the index finger along the remaining side of the compass, and the remaining fingers around the fingers of the other hand. Pull your elbows firmly into your sides; this will place the compass between your chin and your belt. To measure an azimuth, simply turn your entire body toward the object, pointing the compass cover directly at the object. Once you are pointing at the object, look down and read the azimuth from beneath the fixed black index line (Figure 9-2). This preferred method offers the following advantages over the sighting technique:

- (1) It is faster and easier to use.
- (2) It can be used under all conditions of visibility.
- (3) It can be used when navigating over any type of terrain.
- (4) It can be used without putting down the rifle; however, the rifle must be slung well back over either shoulder.
- (5) It can be used without removing eyeglasses.

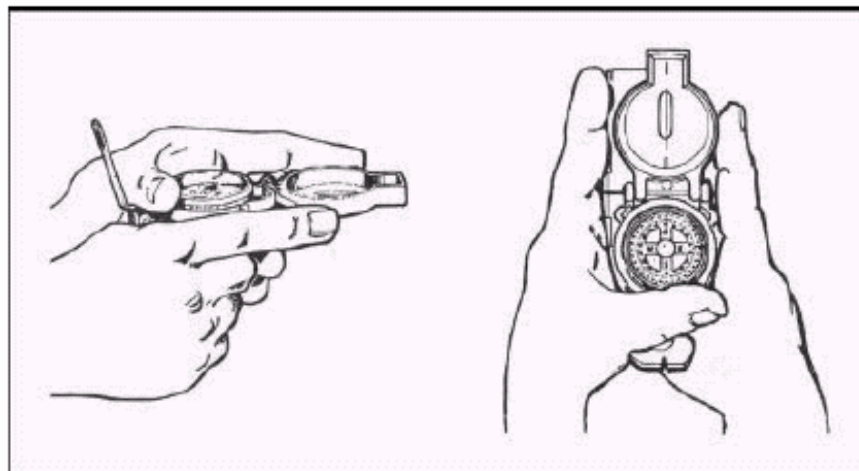


Figure 9-2. Centerhold technique.

b. **Using the Compass-to-Cheek Technique.** Fold the cover of the compass containing the sighting wire to a vertical position; then fold the rear sight slightly forward. Look through the rear-sight slot and align the front-sight hairline with the desired object in the distance. Then glance down at the dial through the eye lens to read the azimuth (Figure 9-3).

NOTE: The compass-to-cheek technique is used almost exclusively for sighting, and it is the best technique for this purpose.

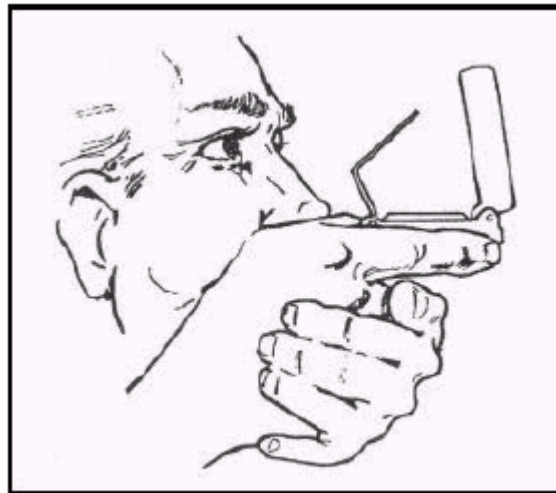


Figure 9-3. Compass-to-cheek technique.

c. **Presetting a Compass and Following an Azimuth.** Although different models of the lensatic compass vary somewhat in the details of their use, the principles are the same.

(1) During daylight hours or with a light source:

(a) Hold the compass level in the palm of the hand.

(b) Rotate it until the desired azimuth falls under the fixed black index line (for example, 320°), maintaining the azimuth as prescribed (Figure 9-4).

(c) Turn the bezel ring until the luminous line is aligned with the north-seeking arrow. Once the alignment is obtained, the compass is preset.

(d) To follow an azimuth, assume the centerhold technique and turn your body until the north-seeking arrow is aligned with the luminous line. Then proceed forward in the direction of the front cover's sighting wire, which is aligned with the fixed black index line that contains the desired azimuth.

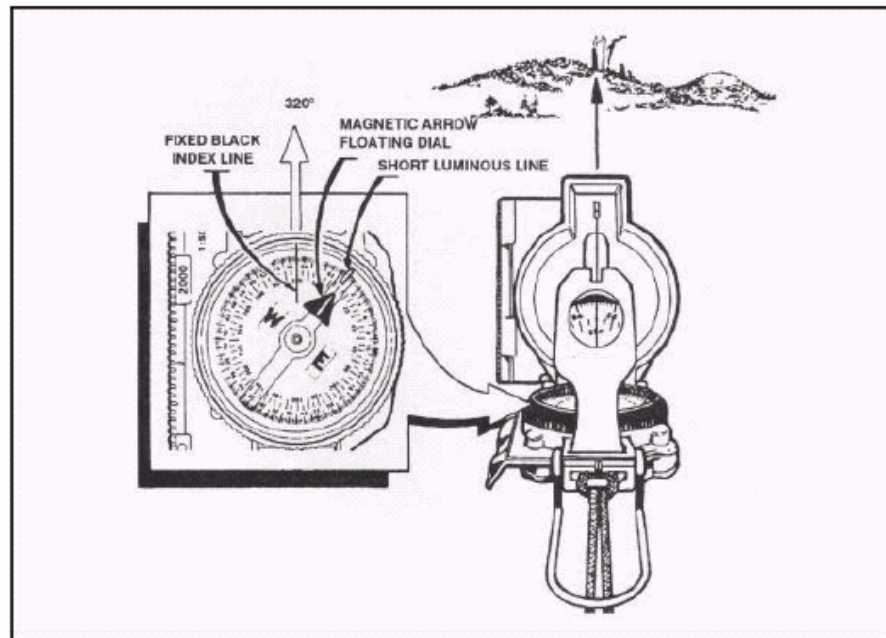


Figure 9-4. Compass preset at 320 degrees

(2) During limited visibility, an azimuth may be set on the compass by the click method. Remember that the bezel ring contains 3° intervals (clicks).

(a) Rotate the bezel ring until the luminous line is over the fixed black index line.

(b) Find the desired azimuth and divide it by three. The result is the number of clicks that you have to rotate the bezel ring.

(c) Count the desired number of clicks. If the desired azimuth is smaller than 180°, the number of clicks on the bezel ring should be counted in a counterclockwise direction. For example, the desired azimuth is 51°. Desired azimuth is $51^\circ \div 3 = 17$ clicks counterclockwise. If the desired azimuth is larger than 180°, subtract the number of degrees from 360° and divide by 3 to obtain the number of clicks. Count them in a clockwise direction. For example, the desired azimuth is 330°; $360^\circ - 330^\circ = 30 \div 3 = 10$ clicks clockwise.

(d) With the compass preset as described above, assume a centerhold technique and rotate your body until the north-seeking arrow is aligned with the luminous line on the bezel. Then proceed forward in the direction of the front cover's luminous dots, which are aligned with the fixed black index line containing the azimuth.

(e) When the compass is to be used in darkness, an initial azimuth should be set while light is still available, if possible. With the initial azimuth as a base, any other azimuth that is a multiple of three can be established through the use of the clicking feature of the bezel ring.

NOTE: Sometimes the desired azimuth is not exactly divisible by three, causing an option of rounding up or rounding down. If the azimuth is rounded up, this causes an

increase in the value of the azimuth, and the object is to be found on the left. If the azimuth is rounded down, this causes a decrease in the value of the azimuth, and the object is to be found on the right.

d. **Bypassing an Obstacle.** To bypass enemy positions or obstacles and still stay oriented, detour around the obstacle by moving at right angles for specified distances.

(1) For example, while moving on an azimuth of 90° change your azimuth to 180° and travel for 100 meters. Change your azimuth to 90° and travel for 150 meters. Change your azimuth to 360° and travel for 100 meters. Then, change your azimuth to 90° and you are back on your original azimuth line (Figure 9-5).

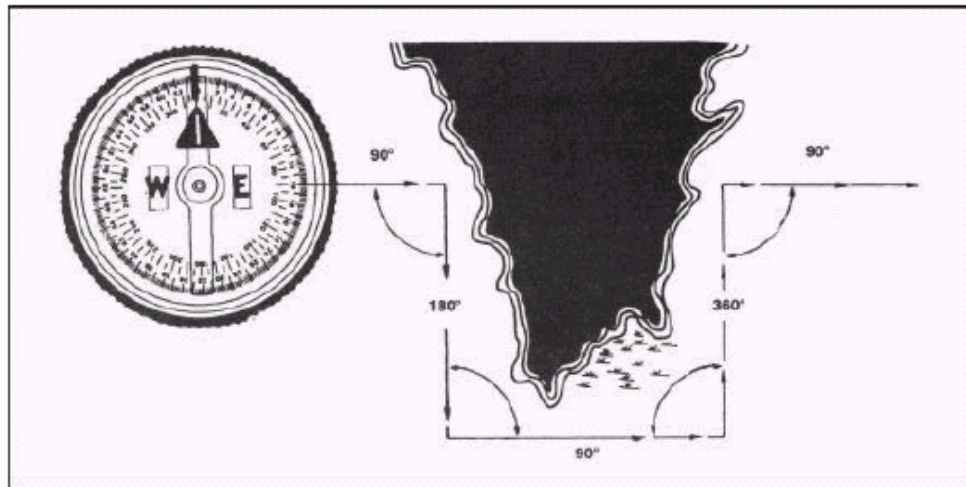


Figure 9-5. Bypassing an obstacle.

(2) Bypassing an unexpected obstacle at night is a fairly simple matter. To make a 90° turn to the right, hold the compass in the centerhold technique; turn until the center of the luminous letter E is under the luminous line (*do not* move the bezel ring). To make a 90° turn to the left, turn until the center of the luminous letter W is under the luminous line. This does not require changing the compass setting (bezel ring), and it ensures accurate 90° turns.

e. **Offset.** A deliberate offset is a planned magnetic deviation to the right or left of an azimuth to an objective. Use it when the objective is located along or in the vicinity of a linear feature such as a road or stream. Because of errors in the compass or in map reading, the linear feature may be reached without knowing whether the objective lies to the right or left. A deliberate offset by a known number of degrees in a known direction compensates for possible errors and ensures that upon reaching the linear feature, the user knows whether to go right or left to reach the objective. Ten degrees is an adequate offset for most tactical uses. Each degree offset moves the course about 18 meters to the right or left for each 1,000 meters traveled. For example, in Figure 9-6, the number of degrees offset is 10. If the distance traveled to "x" in 1,000 meters, then "x" is located about 180 meters to the right of the objective.

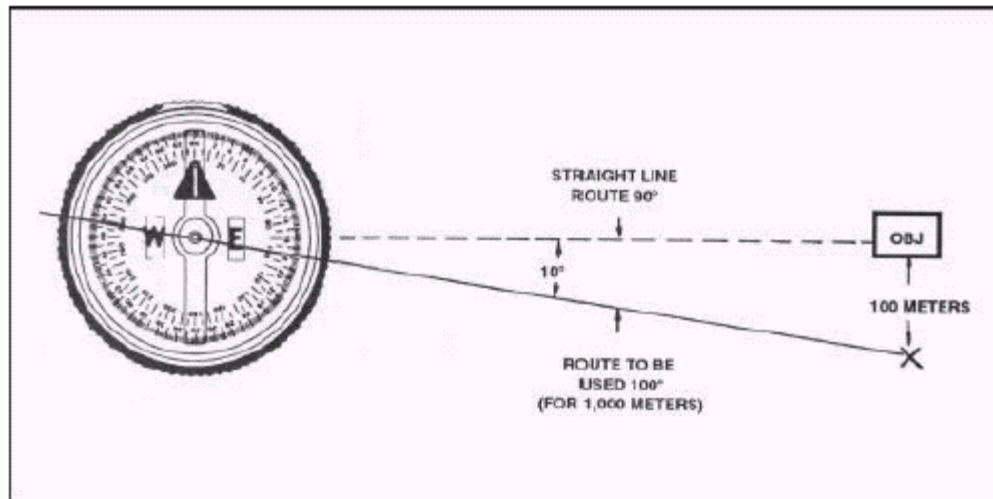


Figure 9-6. Deliberate offset to the objective.

9-5. FIELD-EXPEDIENT METHODS

When a compass is not available, different techniques should be used to determine the four cardinal directions.

a. Shadow-Tip Method.

(1) This simple and accurate method of finding direction by the sun consists of four basic steps (Figure 9-7).

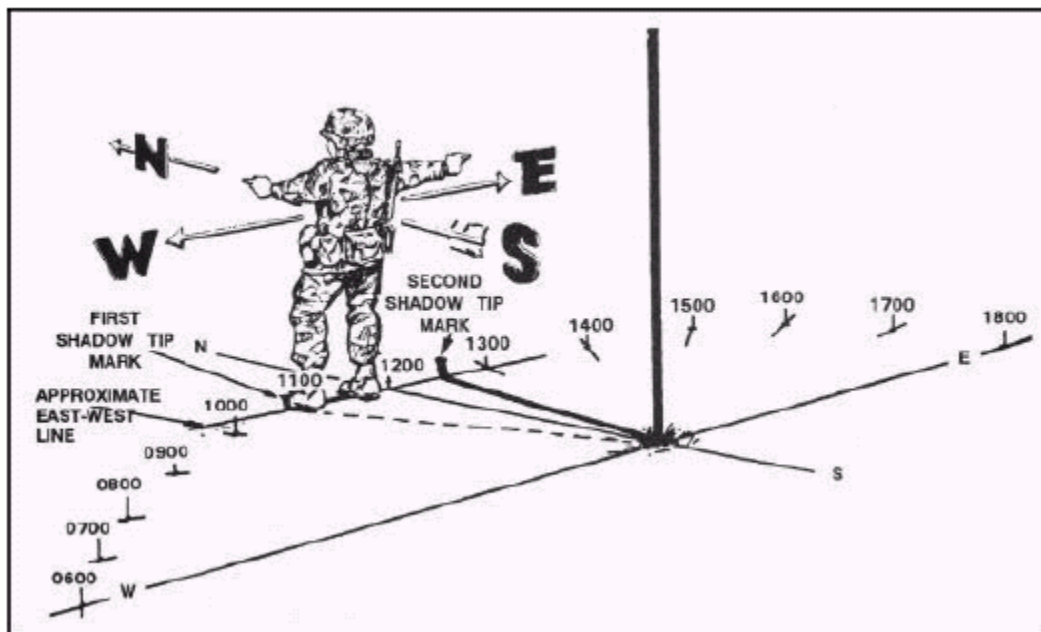


Figure 9-7. Determining directions and time by shadow

Step 1. Place a stick or branch into the ground at a level spot where a distinctive shadow will be cast. Mark the shadow tip with a stone, twig, or other means. This first shadow mark is always the west direction.

Step 2. Wait 10 to 15 minutes until the shadow tip moves a few inches. Mark the new position of the shadow tip in the same way as the first.

Step 3. Draw a straight line through the two marks to obtain an approximate east-west line.

Step 4. Standing with the first mark (west) to your left, the other directions are simple; north is to the front, east is to the right, and south is behind you.

(2) A line drawn perpendicular to the east-west line at any point is the approximate north-south line. If you are uncertain which direction is east and which is west, observe this simple rule--the first shadow-tip mark is always in the west direction, everywhere on earth.

(3) The shadow-tip method can also be used as a shadow clock to find the approximate time of day (Figure 9-7 on page 9-7).

(a) To find the time of day, move the stick to the intersection of the east-west line and the north-south line, and set it vertically in the ground. The west part of the east-west line indicates 0600 hours, and the east part is 1800 hours, anywhere on earth, because the basic rule always applies.

(b) The north-south line now becomes the noon line. The shadow of the stick is an hour hand in the shadow clock, and with it you can estimate the time using the noon line and the 6 o'clock line as your guides. Depending on your location and the season, the shadow may move either clockwise or counterclockwise, but this does not alter your manner of reading the shadow clock.

(c) The shadow clock is not a timepiece in the ordinary sense. It makes every day 12 unequal hours long, and always reads 0600 hours at sunrise and 1800 hours at sunset. The shadow clock time is closest to conventional clock time at midday, but the spacing of the other hours compared to conventional time varies somewhat with the locality and the date. However, it does provide a satisfactory means of telling time in the absence of properly set watches.

(d) The shadow-tip system is not intended for use in polar regions, which the Department of Defense defines as being above 60° latitude in either hemisphere. Distressed persons in these areas are advised to stay in one place so that search/rescue teams may easily find them. The presence and location of all aircraft and ground parties in polar regions are reported to and checked regularly by governmental or other agencies, and any need for help becomes quickly known.

b. Watch Method.

(1) A watch can be used to determine the approximate true north and true south. In the north temperate zone only, the hour hand is pointed toward the sun. A south line can be found midway between the hour hand and 1200 hours, standard time. If on daylight saving time, the north-south line is found between the hour hand and 1300 hours. If there is any doubt as to which end of the line is north, remember that the sun is in the east before noon and in the west after noon.

(2) The watch may also be used to determine direction in the south temperate zone; however, the method is different. The 1200-hour dial is pointed toward the sun, and halfway

between 1200 hours and the hour hand will be a north line. If on daylight saving time, the north line lies midway between the hour hand and 1300 hours (Figure 9-8).

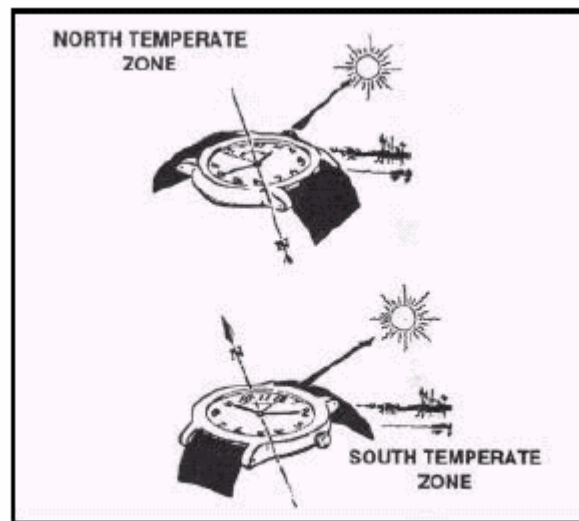


Figure 9-8. Determining direction by using a watch.

(3) The watch method can be in error, especially in the lower latitudes, and may cause *circling*. To avoid this, make a shadow clock and set your watch to the time indicated. After traveling for an hour, take another shadow-clock reading. Reset your watch if necessary.

c. Star Method.

(1) Less than 60 of approximately 5,000 stars visible to the eye are used by navigators. The stars seen as we look up at the sky at night are not evenly scattered across the whole sky. Instead they are in groups called constellations.

(2) The constellations that we see depends partly on where we are located on the earth, the time of the year, and the time of the night. The night changes with the seasons because of the journey of the earth around the sun, and it also changes from hour to hour because the turning of the earth makes some constellations seem to travel in a circle. But there is one star that is in almost exactly the same place in the sky all night long every night. It is the North Star, also known as the Polar Star or Polaris.

(3) The North Star is less than 1° off true north and does not move from its place because the axis of the earth is pointed toward it. The North Star is in the group of stars called the Little Dipper. It is the last star in the handle of the dipper. There are two stars in the Big Dipper, which are a big help when trying to find the North Star. They are called the Pointers, and an imaginary line drawn through them five times their distance points to the North Star. There are many stars brighter than the North Star, but none is more important because of its location. However, the North Star can only be seen in the northern hemisphere so it cannot serve as a guide south of the equator. The farther one goes north, the higher the North Star is in the sky, and above latitude 70° , it is too high in the sky to be useful (Figure 9-9).

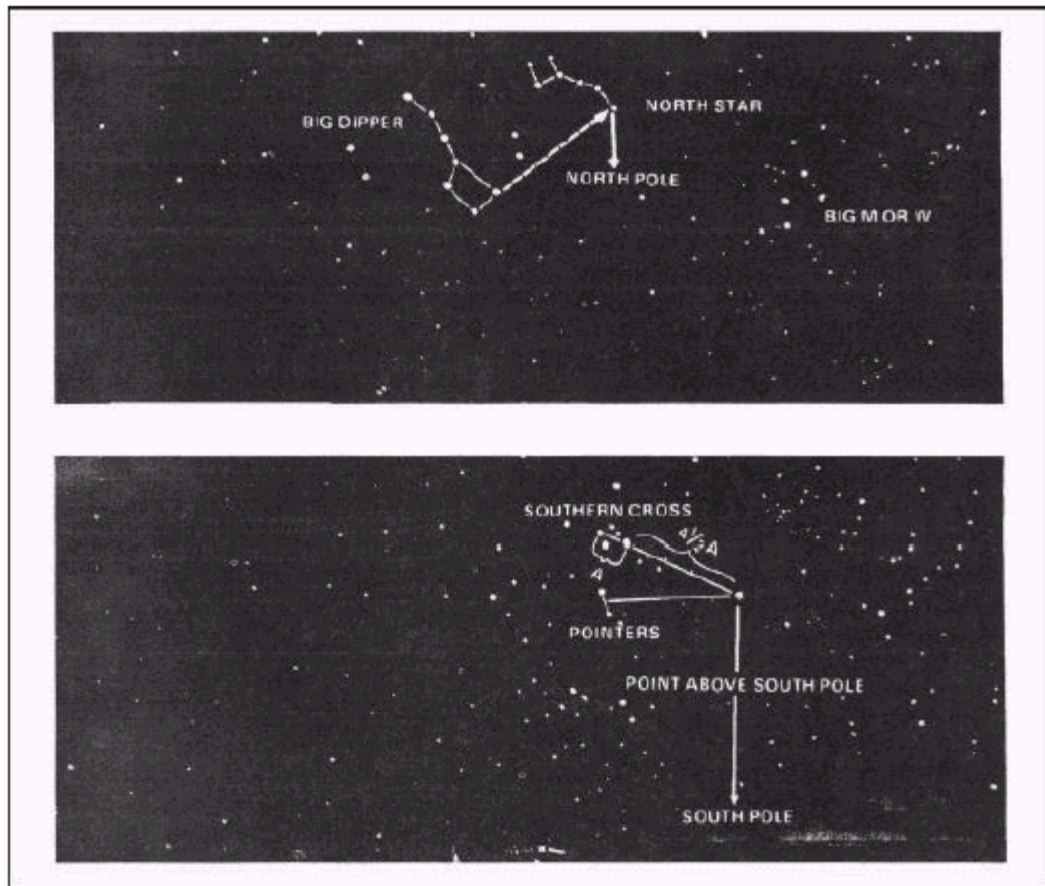


Figure 9-9. Determining direction by the North Star and Southern Cross.

(4) Depending on the star selected for navigation, azimuth checks are necessary. A star near the north horizon serves for about half an hour. When moving south, azimuth checks should be made every 15 minutes. When traveling east or west, the difficulty of staying on azimuth is caused more by the likelihood of the star climbing too high in the sky or losing itself behind the western horizon than it is by the star changing direction angle. When this happens, it is necessary to change to another guide star. The Southern Cross is the main constellation used as a guide south of the equator, and the above general directions for using north and south stars are reversed. When navigating using the stars as guides, the user must know the different constellation shapes and their locations throughout the world (Figure 9-10 and Figure 9-11 on page 9-12).

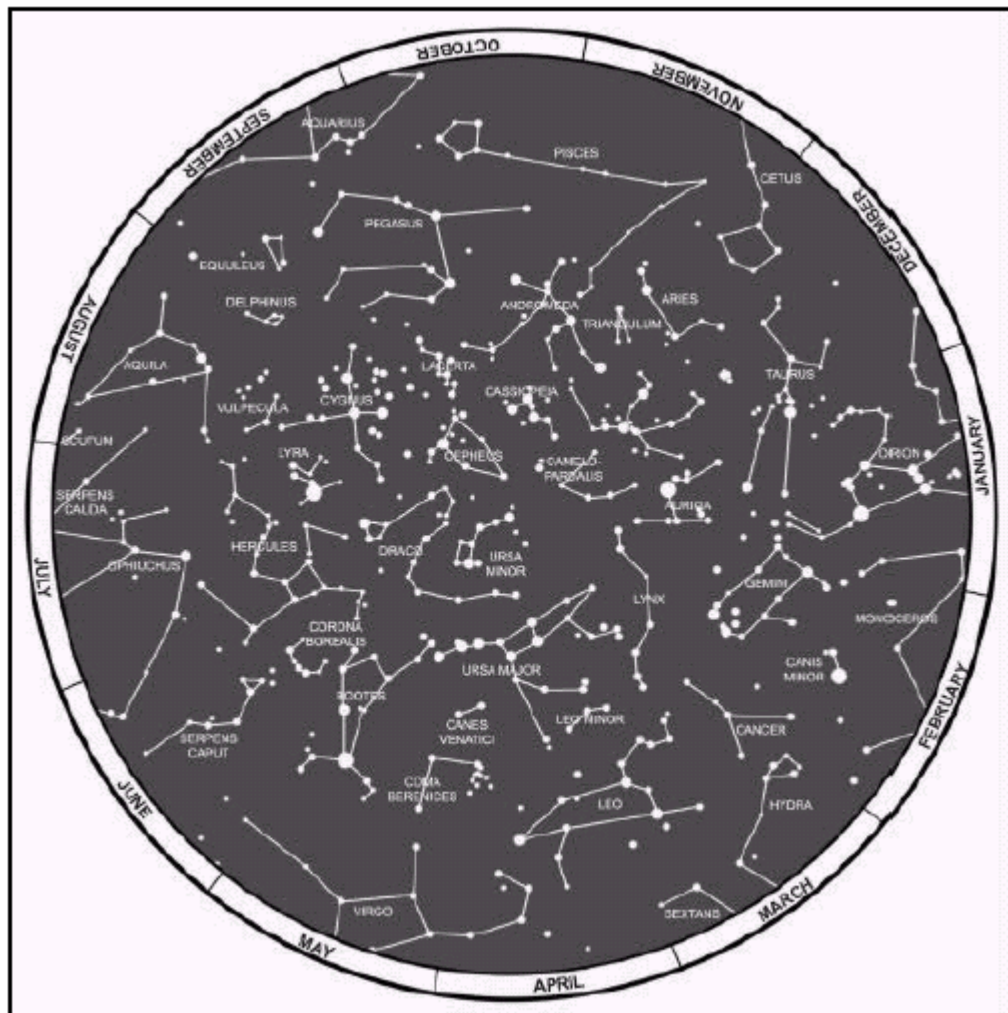


Figure 9-10. Constellations, northern hemisphere

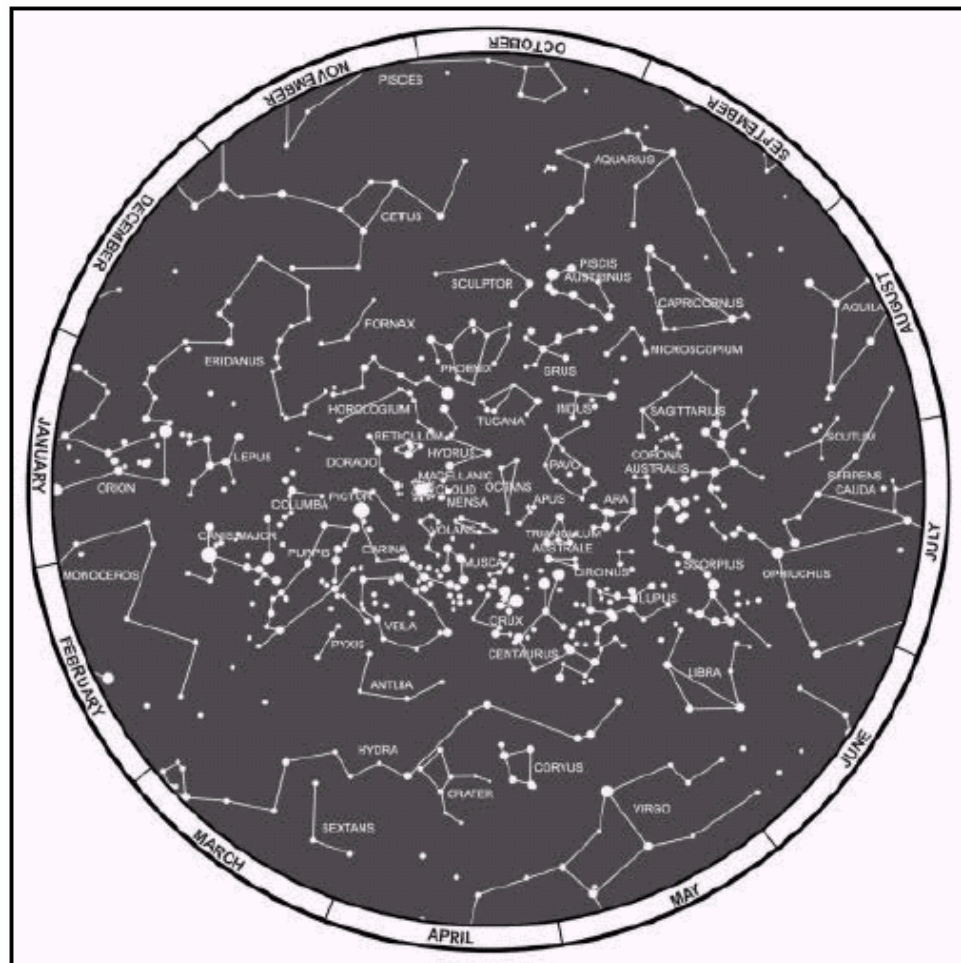


Figure 9-11. Constellations, southern hemisphere

9-6. GLOBAL POSITIONING SYSTEM

The GPS is a space-based, global, all-weather, continuously available, radio positioning navigation system. It is highly accurate in determining position location derived from signal triangulation from a satellite constellation system. It is capable of determining latitude, longitude, and altitude of the individual user. It is being fielded in hand-held, manpack, vehicular, aircraft, and watercraft configurations. The GPS receives and processes data from satellites on either a simultaneous or sequential basis. It measures the velocity and range with respect to each satellite, processes the data in terms of an earth-centered, earth-fixed coordinate system, and displays the information to the user in geographic or military grid coordinates.

- a. The GPS can provide precise steering information, as well as position location. The receiver can accept many checkpoints entered in any coordinate system by the user and convert them to the desired coordinate system. The user then calls up the desired checkpoint and the receiver will display direction and distance to the checkpoint. The GPS does not have

inherent drift, an improvement over the Inertial Navigation System, and the receiver will automatically update its position. The receiver can also compute time to the next checkpoint.

b. Specific uses for the GPS are position location; navigation; weapon location; target and sensor location; coordination of firepower; scout and screening operations; combat resupply; location of obstacles, barriers, and gaps; and communication support. The GPS also has the potential to allow units to train their soldiers and provide the following:

- Performance feedback.
- Knowledge of routes taken by the soldier.
- Knowledge of errors committed by the soldier.
- Comparison of planned versus executed routes.
- Safety and control of lost and injured soldiers.

(See Appendix J for more information of the GPS.)

CHAPTER 10

ELEVATION AND RELIEF

The elevation of points on the ground and the relief of an area affect the movement, positioning, and, in some cases, effectiveness of military units. Soldiers must know how to determine locations of points on a map, measure distances and azimuths, and identify symbols on a map. They must also be able to determine the elevation and relief of areas on standard military maps. To do this, they must first understand how the mapmaker indicated the elevation and relief on the map.

10-1. DEFINITIONS

The reference or start point for vertical measurement of elevation on a standard military map are the **datum plane** or **mean sea level**, the point halfway between high tide and low tide. **Elevation** of a point on the earth's surface is the vertical distance it is above or below mean sea level. **Relief** is the representation (as depicted by the mapmaker) of the shapes of hills, valleys, streams, or terrain features on the earth's surface.

10-2. METHODS OF DEPICTING RELIEF

Mapmakers use several methods to depict relief of the terrain.

a. **Layer Tinting.** Layer tinting is a method of showing relief by color. A different color is used for each band of elevation. Each shade of color, or band, represents a definite elevation range. A legend is printed on the map margin to indicate the elevation range represented by each color. However, this method does not allow the map user to determine the exact elevation of a specific point—only the range.

b. **Form Lines.** Form lines are not measured from any datum plane. Form lines have no standard elevation and give only a general idea of relief. Form lines are represented on a map as dashed lines and are never labeled with representative elevations.

c. **Shaded Relief.** Relief shading indicates relief by a shadow effect achieved by tone and color that results in the darkening of one side of terrain features, such as hills and ridges. The darker the shading, the steeper the slope. Shaded relief is sometimes used in conjunction with contour lines to emphasize these features.

d. **Hachures.** Hachures are short, broken lines used to show relief. Hachures are sometimes used with contour lines. They do not represent exact elevations, but are mainly used to show large, rocky outcrop areas. Hachures are used extensively on small-scale maps to show mountain ranges, plateaus, and mountain peaks.

e. **Contour Lines.** Contour lines are the most common method of showing relief and elevation on a standard topographic map. A contour line represents an imaginary line on the ground, above or below sea level. All points on the contour line are at the same elevation. The elevation represented by contour lines is the vertical distance above or below sea level. The three types of contour lines (Figure 10-1, page 10-2) used on a standard topographic map are as follows:

(1) **Index.** Starting at zero elevation or mean sea level, every fifth contour line is a heavier line. These are known as index contour lines. Normally, each index contour line is numbered at some point. This number is the elevation of that line.

(2) **Intermediate.** The contour lines falling between the index contour lines are called intermediate contour lines. These lines are finer and do not have their elevations given. There are normally four intermediate contour lines between index contour lines.

(3) **Supplementary.** These contour lines resemble dashes. They show changes in elevation of at least one-half the contour interval. These lines are normally found where there is very little change in elevation, such as on fairly level terrain.

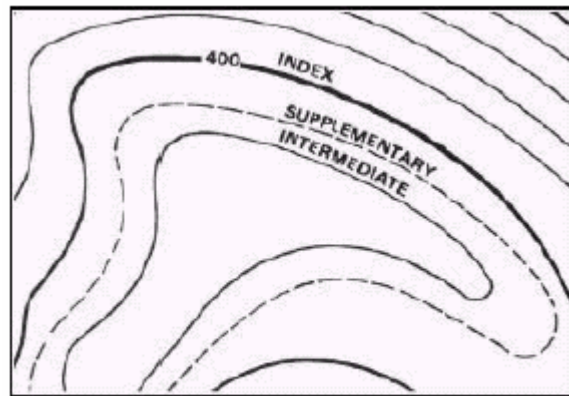


Figure 10-1. Contour lines.

10-3. CONTOUR INTERVALS

Before the elevation of any point on the map can be determined, the user must know the contour interval for the map he is using. The contour interval measurement given in the marginal information is the vertical distance between adjacent contour lines. To determine the elevation of a point on the map—

- a. Determine the contour interval and the unit of measure used, for example, feet, meters, or yards (Figure 10-2).

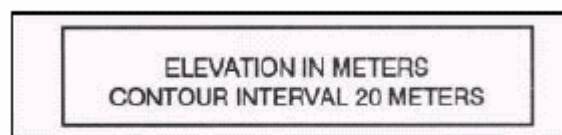


Figure 10-2. Contour interval note.

b. Find the numbered index contour line nearest the point of which you are trying to determine the elevation (Figure 10-3).

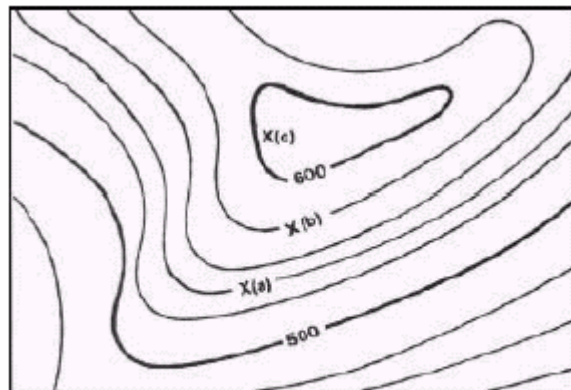


Figure 10-3. Points on contour lines.

c. Determine if you are going from lower elevation to higher, or vice versa. In Figure 10-3, point (a) is between the index contour lines. The lower index contour line is numbered 500, which means any point on that line is at an elevation of 500 meters above mean sea level. The upper index contour line is numbered 600, or 600 meters. Going from the lower to the upper index contour line shows an increase in elevation.

d. Determine the exact elevation of point (a), start at the index contour line numbered 500 and count the number of intermediate contour lines to point (a). Locate point (a) on the second intermediate contour line above the 500-meter index contour line. The contour interval is 20 meters (Figure 10-2), thus each one of the intermediate contour lines crossed to get to point (a) adds 20 meters to the 500-meter index contour line. The elevation of point (a) is 540 meters; the elevation has increased.

e. Determine the elevation of point (b). Go to the nearest index contour line. In this case, it is the upper index contour line numbered 600. Locate point (b) on the intermediate contour line immediately below the 600-meter index contour line. Below means downhill or a lower elevation. Therefore, point (b) is located at an elevation of 580 meters. Remember, if you are increasing elevation, add the contour interval to the nearest index contour line. If you are decreasing elevation, subtract the contour interval from the nearest index contour line.

f. Determine the elevation to a hilltop point (c). Add one-half the contour interval to the elevation of the last contour line. In this example, the last contour line before the hilltop is an index contour line numbered 600. Add one-half the contour interval, 10 meters, to the index contour line. The elevation of the hilltop would be 610 meters.

g. There may be times when you need to determine the elevation of points to a greater accuracy. To do this, you must determine how far between the two contour lines the point lies. However, most military needs are satisfied by estimating the elevation of points between contour lines (Figure 10-4).

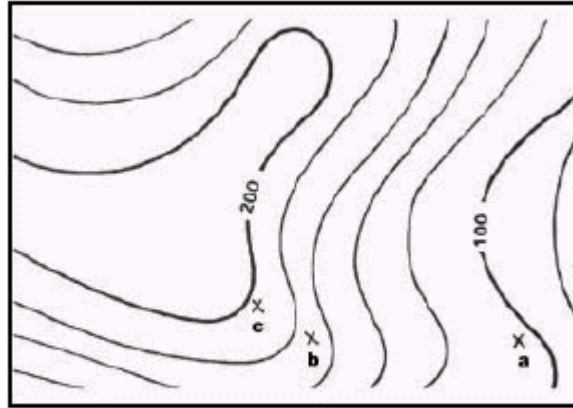


Figure 10-4. Points between contour lines.

(1) If the point is less than one-fourth the distance between contour lines, the elevation will be the same as the last contour line. In Figure 10-4, the elevation of *point a* will be 100 meters. To estimate the elevation of a point between one-fourth and three-fourths of the distance between contour lines, add one-half the contour interval to the last contour line.

(2) *Point b* is one-half the distance between contour lines. The contour line immediately below *point b* is at an elevation of 160 meters. The contour interval is 20 meters; thus one-half the contour interval is 10 meters. In this case, add 10 meters to the last contour line of 160 meters. The elevation of *point b* would be about 170 meters.

(3) A point located more than three-fourths of the distance between contour lines is considered to be at the same elevation as the next contour line. *Point c* is located three-fourths of the distance between contour lines. In Figure 10-4, *point c* would be considered to be at an elevation of 180 meters.

h. To estimate the elevation to the bottom of a depression, subtract one-half the contour interval from the value of the lowest contour line before the depression. In Figure 10-5, the lowest contour line before the depression is 240 meters in elevation. Thus, the elevation at the edge of the depression is 240 meters. To determine the elevation at the bottom of the depression, subtract one-half the contour interval. The contour interval for this example is 20 meters. Subtract 10 meters from the lowest contour line immediately before the depression. The result is that the elevation at the bottom of the depression is 230 meters. The tick marks on the contour line forming a depression always point to lower elevations.

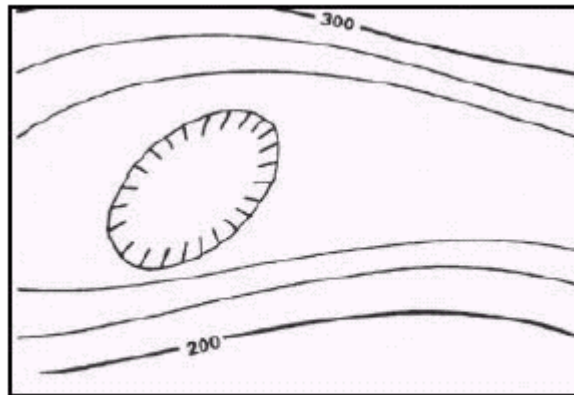


Figure 10-5. Depression.

i. In addition to the contour lines, bench marks and spot elevations are used to indicate points of known elevations on the map.

(1) Bench marks, the more accurate of the two, are symbolized by a black X, such as X BM 214. The 214 indicates that the center of the X is at an elevation of 214 units of measure (feet, meters, or yards) above mean sea level. To determine the units of measure, refer to the contour interval in the marginal information.

(2) Spot elevations are shown by a brown X and are usually located at road junctions and on hilltops and other prominent terrain features. If the elevation is shown in black numerals, it has been checked for accuracy; if it is in brown, it has not been checked.

NOTE: New maps are being printed using a dot instead of brown Xs.

10-4. TYPES OF SLOPES

Depending on the military mission, soldiers may need to determine not only the height of a hill, but the degree of the hill's slope as well. The rate of rise or fall of a terrain feature is known as its slope. The speed at which equipment or personnel can move is affected by the slope of the ground or terrain feature. This slope can be determined from the map by studying the contour lines—the closer the contour lines, the steeper the slope; the farther apart the contour lines, the gentler the slope. Four types of slopes that concern the military are as follows:

a. **Gentle.** Contour lines showing a uniform, gentle slope will be evenly spaced and wide apart (Figure 10-6, page 10-6). Considering relief only, a uniform, gentle slope allows the defender to use grazing fire. The attacking force has to climb a slight incline.

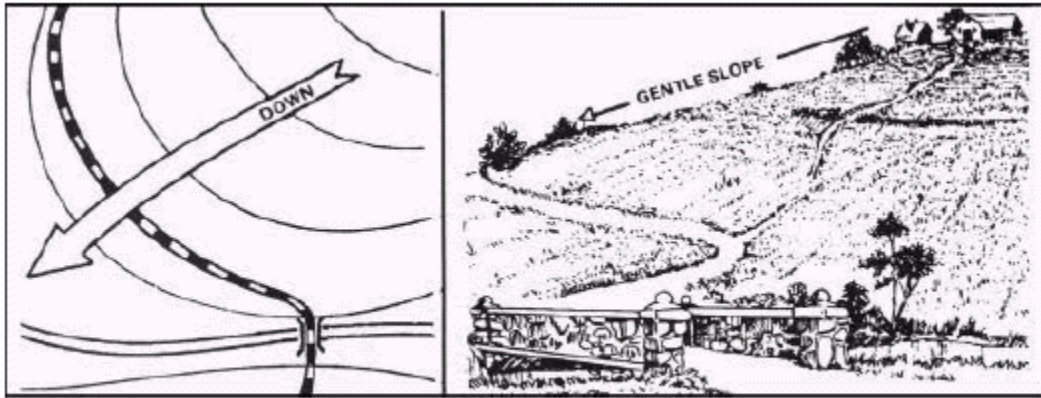


Figure 10-6. Uniform, gentle slope.

b. **Steep.** Contour lines showing a uniform, steep slope on a map will be evenly spaced, but close together. Remember, the closer the contour lines, the steeper the slope (Figure 10-7). Considering relief only, a uniform, steep slope allows the defender to use grazing fire, and the attacking force has to negotiate a steep incline.



Figure 10-7. Uniform, steep slope.

c. **Concave.** Contour lines showing a concave slope on a map will be closely spaced at the top of the terrain feature and widely spaced at the bottom (Figure 10-8, page 10-7). Considering relief only, the defender at the top of the slope can observe the entire slope and the terrain at the bottom, but he cannot use grazing fire. The attacker would have no cover from the defender's observation of fire, and his climb would become more difficult as he got farther up the slope.

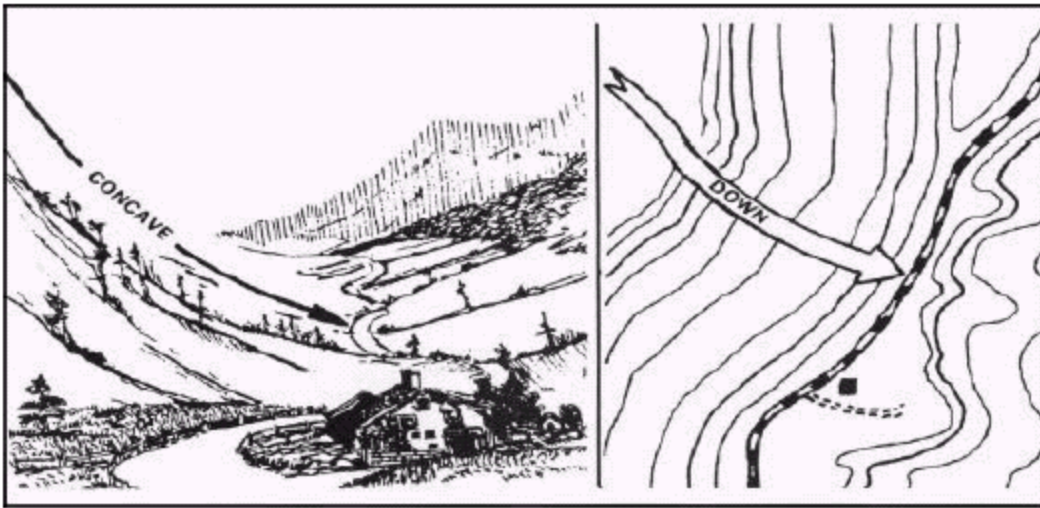


Figure 10-8. Concave slope.

d. **Convex.** Contour lines showing a convex slope on a map will be widely spaced at the top and closely spaced at the bottom (Figure 10-9). Considering relief only, the defender at the top of the convex slope can obtain a small distance of grazing fire, but he cannot observe most of the slope or the terrain at the bottom. The attacker will have concealment on most of the slope and an easier climb as he nears the top.



Figure 10-9. Convex slope.

10-5. PERCENTAGE OF SLOPE

The speed at which personnel and equipment can move up or down a hill is affected by the slope of the ground and the limitations of the equipment. Because of this, a more exact way of describing a slope is necessary.

a. Slope may be expressed in several ways, but all depend upon the comparison of vertical distance (VD) to horizontal distance (HD) (Figure 10-10). Before we can determine the percentage of a slope, we must know the VD of the slope. The VD is determined by subtracting the lowest point of the slope from the highest point. Use the contour lines to determine the highest and lowest point of the slope (Figure 10-11).

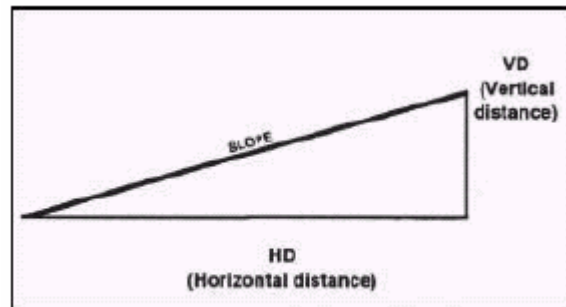


Figure 10-10. Slope diagram.

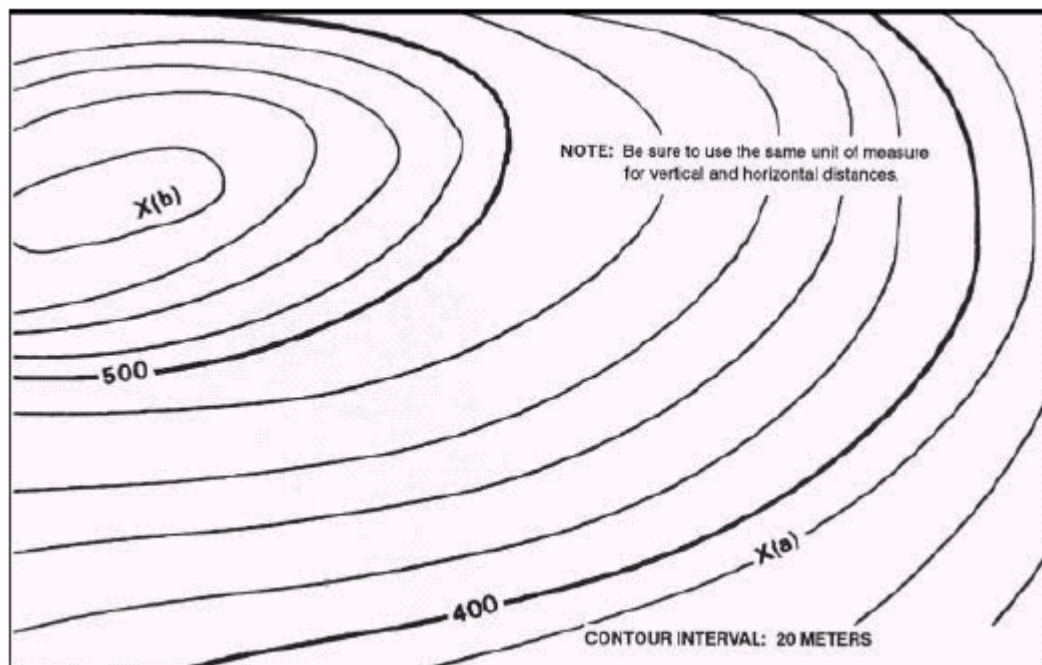


Figure 10-11. Contour line around a slope.

b. To determine the percentage of the slope between points (a) and (b) in Figure 10-11, determine the elevation of point (b) (590 meters). Then determine the elevation of point (a)

(380 meters). Determine the vertical distance between the two points by subtracting the elevation of point (a) from the elevation of point (b). The difference (210 meters) is the VD between points (a) and (b). Then measure the HD between the two points on the map in Figure 10-12. After the horizontal distance has been determined, compute the percentage of the slope by using the formula shown in Figure 10-13.

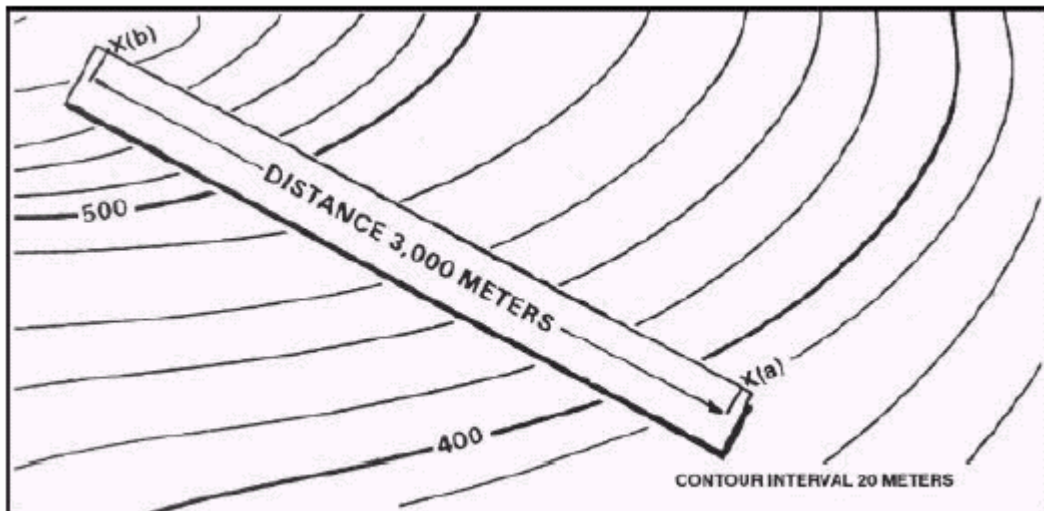


Figure 10-12. Measuring horizontal distance.

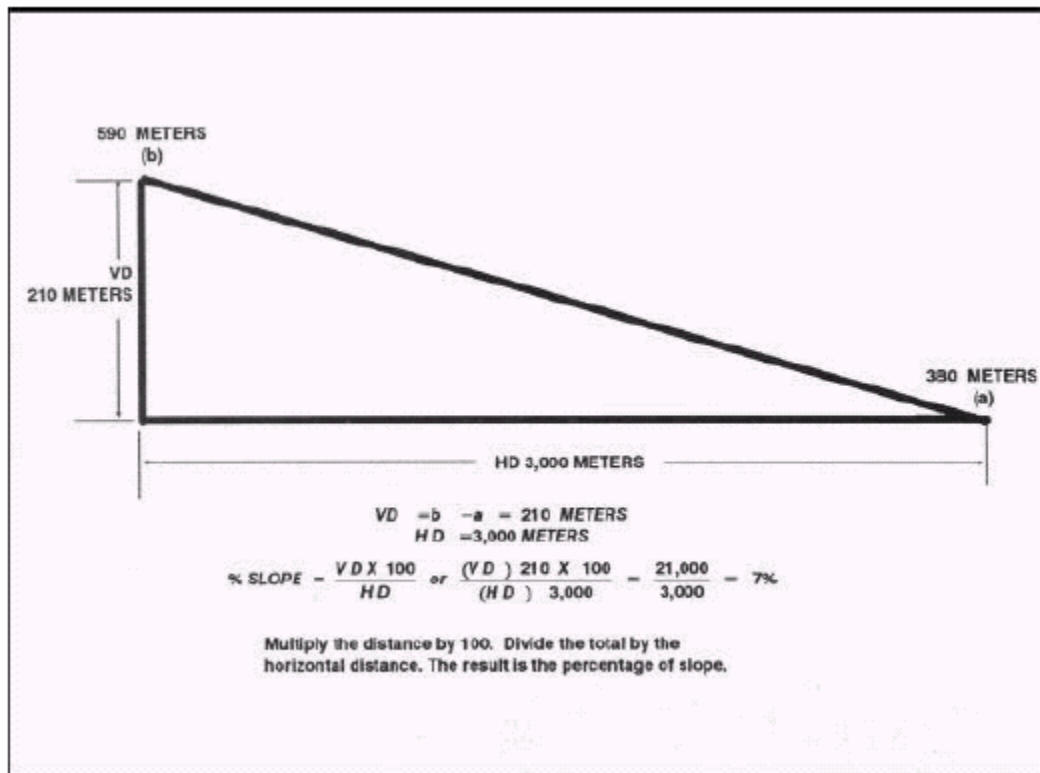


Fig 10-13. Percentabe of slope in meters.

c. The slope angle can also be expressed in degrees. To do this, determine the VD and HD of the slope. Multiply the VD by 57.3 and then divide the total by the HD (Figure 10-14). This method determines the approximate degree of slope and is reasonably accurate for slope angles less than 20°.

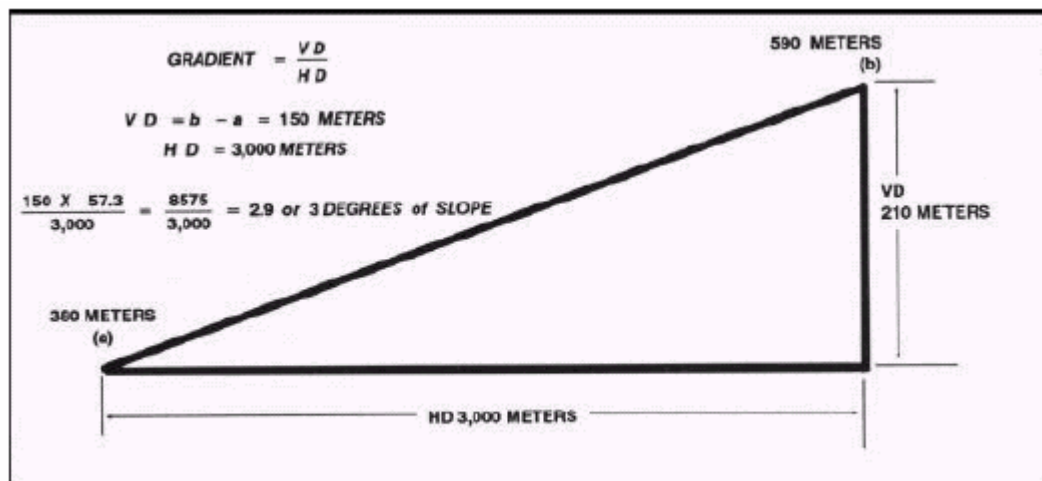


Figure 10-14. Degree of slope.

d. The slope angle can also be expressed as a gradient. The relationship of horizontal and vertical distance is expressed as a fraction with a numerator of one (Figure 10-15).

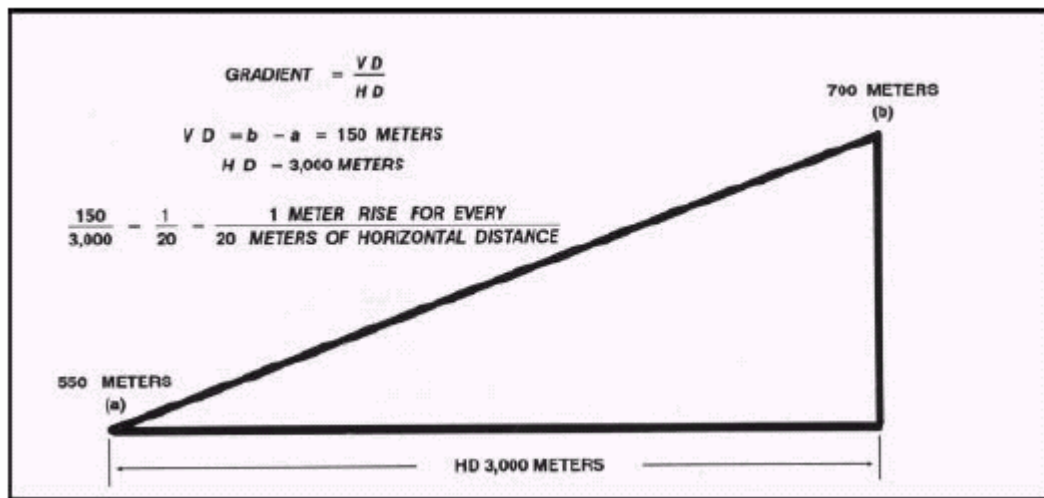


Figure 10-15. Gradient.

10-6. TERRAIN FEATURES

All terrain features are derived from a complex landmass known as a mountain or ridgeline (Figure 10-16). The term ridgeline is not interchangeable with the term ridge. A ridgeline is a line of high ground, usually with changes in elevation along its top and low ground on all sides from which a total of 10 natural or man-made terrain features are classified.

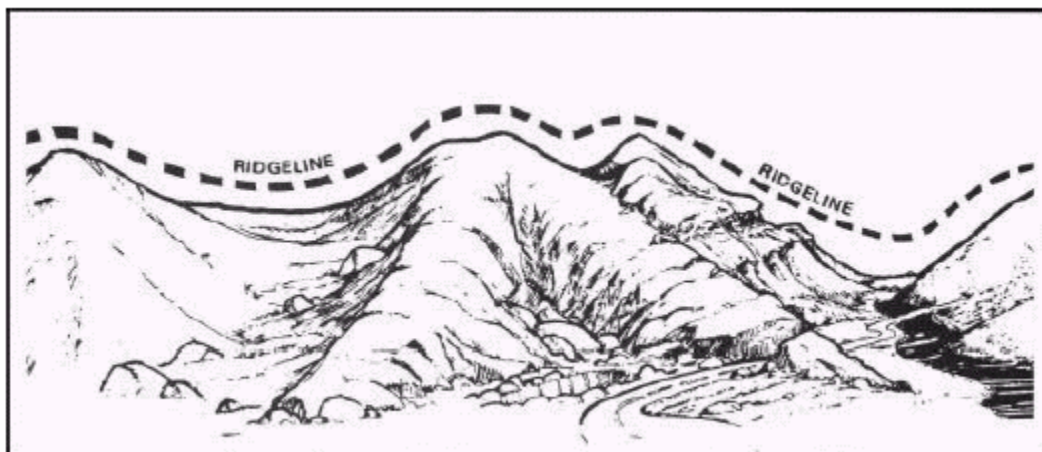


Figure 10-16. Ridgeline.

CHAPTER 11

TERRAIN ASSOCIATION

Failure to make use of the vast amounts of information presented by the map and available to the eye on the ground reduces the chances for success in land navigation. The soldier who has repeatedly practiced the skills of identifying and discriminating among the many types of terrain and other features knows how these features are mapped. He can begin to visualize the shape of the land by studying the map, estimate distances, and perform quick resection from the many landmarks he sees is the one who will be at the right place to help defeat the enemy on the battlefield. This chapter tells how to orient a map with and without a compass, how to find locations on a map as well as on the ground, how to study the terrain, and how to move on the ground using terrain association and dead reckoning.

11-1. ORIENTING THE MAP

The first step for a navigator in the field is orienting the map. A map is oriented when it is in a horizontal position with its north and south corresponding to the north and south on the ground. Some orienting techniques follow:

a. **Using a Compass.** When orienting a map with a compass, remember that the compass measures magnetic azimuths. Since the magnetic arrow points to magnetic north, pay special attention to the declination diagram. There are two techniques used.

(1) **First Technique.** Determine the direction of the declination and its value from the declination diagram.

(a) With the map in a horizontal position, take the straightedge on the left side of the compass and place it alongside the north-south grid line with the cover of the compass pointing toward the top of the map. This procedure places the fixed black index line of the compass parallel to north-south grid lines of the map.

(b) Keeping the compass aligned as directed above, rotate the map and compass together until the magnetic arrow is below the fixed black index line on the compass. At this time, the map is close to being oriented.

(c) Rotate the map and compass in the direction of the declination diagram.

(d) If the magnetic north arrow on the map is to the left of the grid north, check the compass reading to see if it equals the G-M angle given in the declination diagram. The map is then oriented (Figure 11-1, page 11-2).

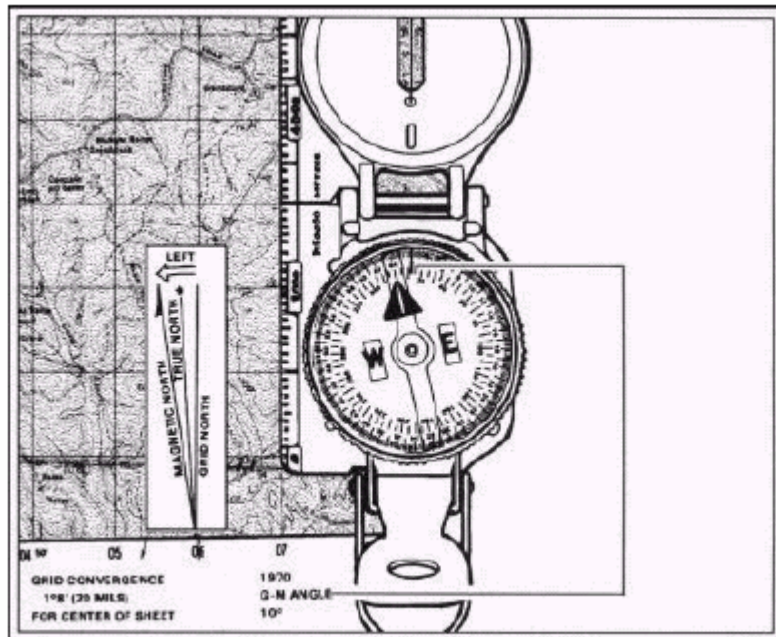


Figure 11-1. Map oriented with 11 degrees west declination.

(e) If the magnetic north is to the right of grid north, check the compass reading to see if it equals 360 degrees minus the G-M angle (Figure 11-2).

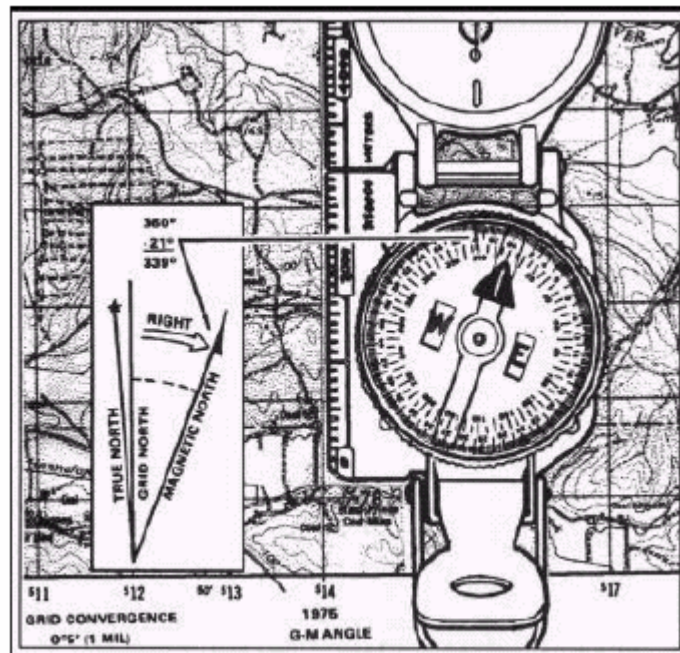


Figure 11-2. Map oriented with 21 degrees east declination.

(2) **Second Technique.** Determine the direction of the declination and its value from the declination diagram.

(a) Using any north-south grid line on the map as a base, draw a magnetic azimuth equal to the G-M angle given in the declination diagram with the protractor.

(b) If the declination is easterly (right), the drawn line is equal to the value of the G-M angle. Then align the straightedge, which is on the left side of the compass, alongside the drawn line on the map. Rotate the map and compass until the magnetic arrow of the compass is below the fixed black index line. The map is now oriented (Figure 11-3).

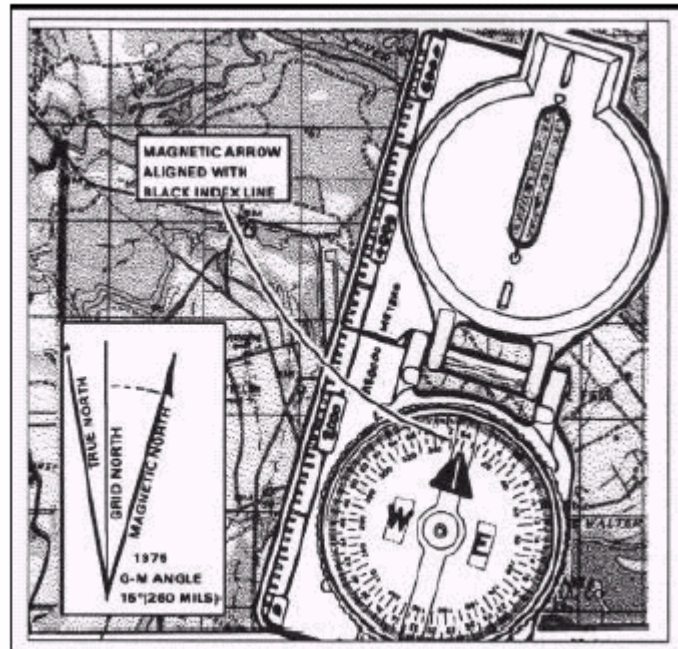


Figure 11-3. Map oriented with 15 degrees east declination.

(c) If the declination is westerly (left), the drawn line will equal 360 degrees minus the value of the G-M angle. Then align the straightedge, which is on the left side of the compass, alongside the drawn line on the map. Rotate the map and compass until the magnetic arrow of the compass is below the fixed black index line. The map is now oriented (Figure 11-4, page 11-4).

NOTES:

1. Once the map is oriented, magnetic azimuths are determined using the compass. Do not move the map from its oriented position since any change in its position moves it out of line with the magnetic north. [See paragraph 11-6b(1).]
2. Special care should be taken whenever orienting your map with a compass. A small mistake can cause you to navigate in the wrong direction.

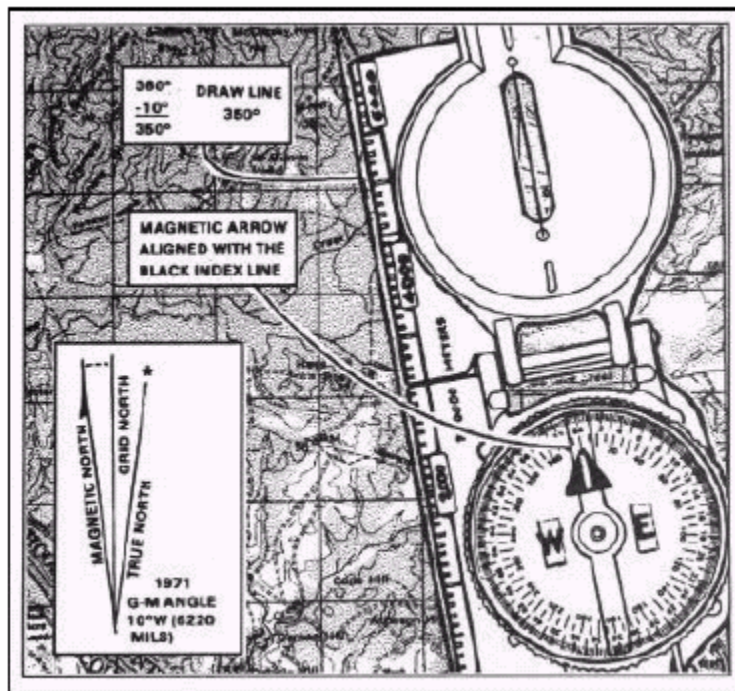


Figure 11-4. Map oriented with 10 degrees west declination.

b. **Using Terrain Association.** A map can be oriented by terrain association when a compass is not available or when the user has to make many quick references as he moves across country. Using this method requires careful examination of the map and the ground, and the user must know his approximate location (Figure 11-5). Orienting by this method is discussed in detail in paragraph 11-3.

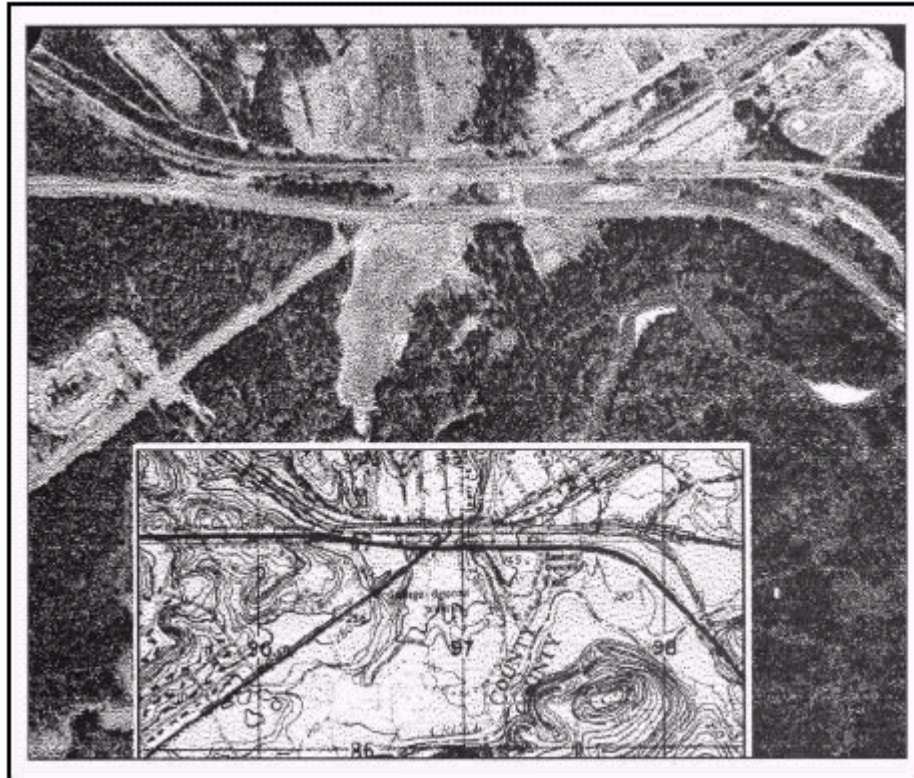


Figure 11-5. Terrain association.

c. **Using Field-Expedient Methods.** When a compass is not available and there are no recognizable terrain features, a map may be oriented by any of the field-expedient methods described in paragraph 9-5. Also see Figure 11-6.

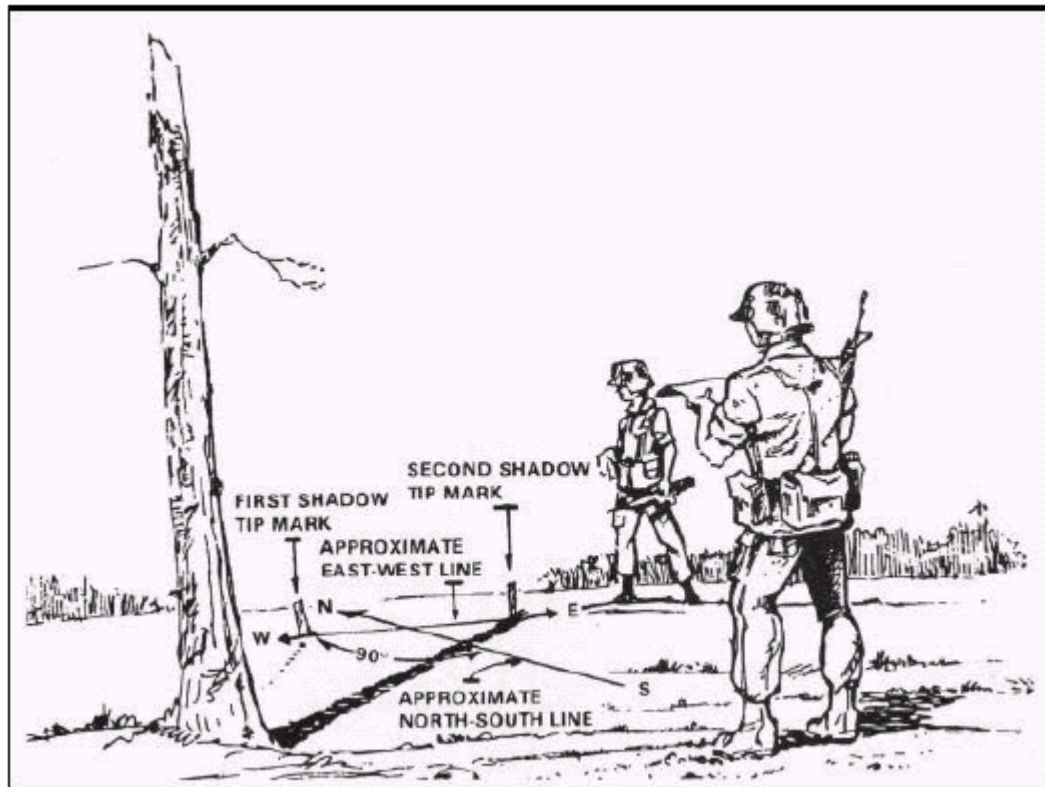


Figure 11-6. Field-expedient method.

11-2. LOCATIONS

The key to success in land navigation is to know your location at all times. With this basic knowledge, you can decide what direction and what distance to travel.

a. **Known Position.** Most important of all is the initial location of the user before starting any movement in the field. If movement takes place without establishing the initial location, everything that is done in the field from there on is a gamble. Determine the initial location by referring to the last known position, by grid coordinates and terrain association, or by locating and orienting your position on the map and ground.

b. **Known Point/Known Distance (Polar Plot).** This location can be determined by knowing the starting point, the azimuth to the desired objective, and the distance to it.

c. **Resection.** See Chapter 6.

d. **Modified Resection.** See Chapter 6.

e. **Intersection.** See Chapter 6.

f. **Indirect Fire.** Finding a location by indirect fire is done with smoke. Use the point of impact of the round as a reference point from which distances and azimuth can be obtained.

11-3. TERRAIN ASSOCIATION USAGE

The technique of moving by terrain association is more forgiving of mistakes and far less time-consuming than dead reckoning. It best suits those situations that call for movement from one area to another. Errors made using terrain association are easily corrected because you are comparing what you expected to see from the map to what you do see on the ground. Errors are anticipated and will not go unchecked. You can easily make adjustments based upon what you encounter. Periodic position-fixing through either plotted or estimated resection will also make it possible to correct your movements, call for fire, or call in the locations of enemy targets or any other information of tactical or logistical importance.

a. **Matching the Terrain to the Map by Examining Terrain Features.** By observing the contour lines in detail, the five major terrain features (hilltop, valley, ridge, depression, and saddle) should be determined. This is a simple task in an area where the observer has ample view of the terrain in all directions. One-by-one, match the terrain features depicted on the map with the same features on the ground. In restricted terrain, this procedure becomes harder; however, constantly check the map as you move since it is the determining factor (Figure 11-5).

b. **Comparing the Vegetation Depicted on the Map.** When comparing the vegetation, a topographic map should be used to make a comparison of the clearings that appear on the map with the ones on the ground. The user must be familiar with the different symbols, such as vineyards, plantations, and orchards that appear on the legend. The age of the map is an important factor when comparing vegetation. Some important vegetation features were likely to be different when the map was made. Another important factor about vegetation is that it can change overnight by natural accidents or by man (forest fires, clearing of land for new developments, farming, and so forth).

c. **Masking by the Vegetation.** Camouflage the important landforms using vegetation. Use of camouflage makes it harder for the navigator to use terrain association.

d. **Using the Hydrography.** Inland bodies of water can help during terrain association. The shape and size of lakes in conjunction with the size and direction of flow of the rivers and streams are valuable help.

e. **Using Man-made Features.** Man-made features are an important factor during terrain association. The user must be familiar with the symbols shown in the legend representing those features. The direction of buildings, roads, bridges, high-tension lines, and so forth make the terrain inspection a lot easier; however, the age of the map must be considered because man-made features appear and disappear constantly.

f. **Examining the Same Piece of Terrain During the Different Seasons of the Year.** In those areas of the world where the seasons are distinctive, a detailed examination of the terrain should be made during each of the seasons. The same piece of land does not present the same characteristics during both spring and winter.

(1) During winter, the snow packs the vegetation, delineating the land, making the terrain features appear as clear as they are shown by the contour lines on the map. Ridges, valleys, and saddles are very distinctive.

(2) During spring, the vegetation begins to reappear and grow. New vegetation causes a gradual change of the land to the point that the foliage conceals the terrain features and makes the terrain hard to recognize.

(3) During summer months, the effects are similar to those in the spring.

(4) Fall makes the land appear different with its change of color and gradual loss of vegetation.

(5) During the rainy season, the vegetation is green and thick, and the streams and ponds look like small rivers and lakes. In scarcely vegetated areas, the erosion changes the shape of the land.

(6) During a period of drought, the vegetation dries out and becomes vulnerable to forest fires that change the terrain whenever they occur. Also during this season, the water levels of streams and lakes drop, adding new dimensions and shape to the existing mapped areas.

g. **Following an Example of Terrain Association.** Your location is hilltop 514 in the lower center of the map in Figure 11-7.

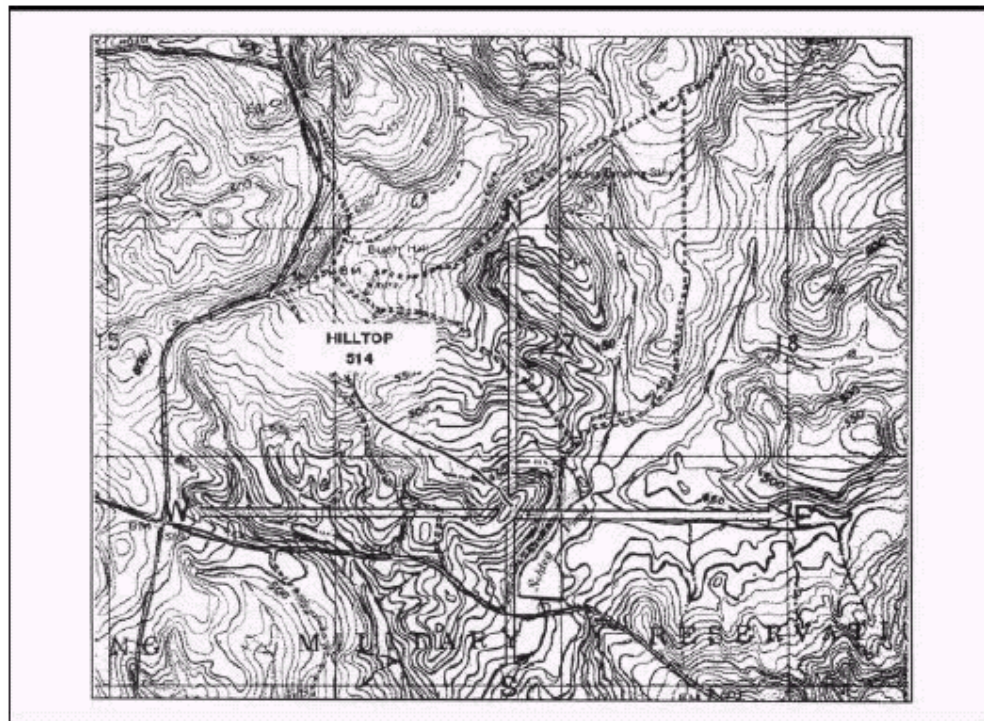


Figure 11-7. Example of terrain association.

(1) **To The North.** The contour lines indicate that the hill slopes down for about 190 meters, and that it leads into a small valley containing an intermittent stream. On the other side of the stream as you continue with your northerly inspection, the terrain starts a gradual ascent, indicating a hilltop partially covered with vegetation, until an unimproved road is reached. This road runs along a gradual ridgeline with north-west direction. Then the contour line spacings become narrow, indicating a steeper grade that leads to a narrow valley containing a small intermittent stream. As you continue up, you find a small but prominent ridge with a clearing. The contour lines once again show a steeper grade leading to a moderate valley containing an intermittent stream running in a south-east direction.

(2) **To The East.** There is a clearing of the terrain as it slopes down to Schley Pond. An ample valley is clearly seen on the right side of the pond, as indicated by the "U" and "V" shape of the contour lines. This valley contains some swamp areas and there is a long ridgeline on the north portion of the valley.

(3) **To The South.** The terrain gently slopes downward until a clear area is reached. It continues in a downward direction to an intermittent stream running south-east in a small valley. There is also an improved road running in the same direction as the valley. At the intersection of the roads as you face south, there is a clearing of about 120 meters on the ridge. At the bottom of it, a stream runs from Schley Pond in a south-west direction through an ample valley fed by two intermittent streams. As you continue, a steep, vegetated hill is found with a clearing on its top, followed by a small saddle and another hilltop.

(4) **To The West.** First, you see a small, clear valley. It is followed by a general ridgeline running north-west in which an unimproved road is located just before a hilltop. Continuing on a westerly direction, you will find a series of alternate valleys and ridges.

11-4. TACTICAL CONSIDERATIONS

Military cross-country navigation is intellectually demanding because it is imperative that the unit, crew, or vehicle survive and successfully complete the move in order to accomplish its mission. However, the unnecessary use of a difficult route makes navigation too complicated, creates more noise when proceeding over it, causes wear and tear on equipment and personnel, increases the need for and needlessly complicate recovery operations, and wastes scarce time. On receipt of a tactical mission, the leader begins his troop-leading procedures and makes a tentative plan. He bases the tentative plan on a good terrain analysis. He analyzes the considerations covered in the following mnemonics—OCOKA and METT-T.

a. **OCOKA.** The terrain should be analyzed for observation and fields of fire, cover and concealment, obstacles, key terrain, and avenues of approach.

(1) **Observation and Fields of Fire.** The purpose of observation is to see the enemy (or various landmarks) but not be seen by him. Anything that can be seen can be hit. Therefore, a field of fire is an area that a weapon or a group of weapons can cover effectively with fire from a given position.

(2) **Cover and Concealment.** Cover is shelter or protection (from enemy fire) either natural or artificial. Always try to use covered routes and seek cover for each halt, no matter how brief it is planned to be. Unfortunately, two factors interfere with obtaining constant cover. One is time and the other is terrain. Concealment is protection from observation or surveillance, including concealment from enemy air observation. Before, trees provided good concealment, but with modern thermal and infrared imaging equipment, trees are not always effective. When you are moving, concealment is generally secondary; therefore, select routes and positions that do not allow covered or concealed enemy near you.

(3) **Obstacles.** Obstacles are any obstructions that stop, delay, or divert movement. Obstacles can be natural (rivers, swamps, cliffs, or mountains) or they may be artificial (barbed wire entanglements, pits, concrete or metal anti-mechanized traps). They can be readymade or constructed in the field. Always consider any possible obstacles along your movement route and, if possible, try to keep obstacles between the enemy and yourself.

(4) **Key Terrain.** Key terrain is any locality or area that the seizure or retention of affords a marked advantage to either combatant. Urban areas that are often seen by higher headquarters as being key terrain because they are used to control routes. On the other hand, an urban area that is destroyed may be an obstacle instead. High ground can be key because it dominates an area with good observation and fields of fire. In an open area, a draw or wadi (dry streambed located in an arid area) may provide the only cover for many kilometers, thereby becoming key. You should always attempt to locate any area near you that could be even remotely considered as key terrain.

(5) **Avenues of Approach.** These are access routes. They may be the routes you can use to get to the enemy or the routes they can use to get to you. Basically, an identifiable route that approaches a position or location is an avenue of approach to that location. They are often terrain corridors such as valleys or wide, open areas.

b. **METT-T.** Tactical factors other than the military aspects of terrain must also be considered in conjunction with terrain during movement planning and execution as well. These additional considerations are mission, enemy, terrain and weather, troops, and time available.

(1) **Mission.** This refers to the specific task assigned to a unit or individual. It is the duty or task together with the purpose that clearly indicates the action to be taken and the reason for it—but not how to do it. Training exercises should stress the importance of a thorough map reconnaissance to evaluate the terrain. This allows the leader to confirm his tentative plan, basing his decision on the terrain's effect on his mission.

(a) Marches by foot or vehicle are used to move troops from one location to another. Soldiers must get to the right place, at the right time, and in good fighting condition. The normal rate for an 8-hour foot march is 4 kmph. However, the rate of march may vary, depending on the following factors:

- Distance.
- Time allowed.
- Likelihood of enemy contact.
- Terrain.
- Weather.
- Physical condition of soldiers.
- Equipment/weight to be carried.
- A motor march requires little or no walking by the soldiers, but the factors affecting the rate of march still apply.

(b) Patrol missions are used to conduct combat or reconnaissance operations. Without detailed planning and a thorough map reconnaissance, any patrol mission may not succeed. During the map reconnaissance, the mission leader determines a primary and alternate route to and from the objectives.

(c) Movement to contact is conducted whenever an element is moving toward the enemy but is not in contact with the enemy. The lead element must orient its movement on the objective by conducting a map reconnaissance, determining the location of the objective on both the map and the ground, and selecting the route to be taken.

(d) Delays and withdrawals are conducted to slow the enemy down without becoming decisively engaged, or to assume another mission. To be effective, the element leader must know where he is to move and the route to be taken.

(2) **Enemy.** This refers to the strength, status of training, disposition (locations), doctrine, capabilities, equipment (including night vision devices), and probable courses of action that impact upon both the planning and execution of the mission, including a movement.

(3) **Terrain and Weather.** Observation and fields of fire influence the placement of positions and crew-served weapons. The leader conducts a map reconnaissance to determine key terrain, obstacles, cover and concealment, and likely avenues of approach.

(a) Key terrain is any area whose control affords a marked advantage to the force holding it. Some types of key terrain are high ground, bridges, towns, and road junctions.

(b) Obstacles are natural or man-made terrain features that stop, slow down, or divert movement. Consideration of obstacles is influenced by the unit's mission. An obstacle may be an advantage or disadvantage, depending upon the direction of attack or defense. Obstacles can be found by conducting a thorough map reconnaissance and study of recent aerial photographs.

(c) Cover and concealment are determined for both friendly and enemy forces. Concealment is protection from observation; cover is protection from the effects of fire. Most terrain features that offer cover also provide concealment from ground observation. There are areas that provide no concealment from enemy observation. These danger areas may be large or small open fields, roads, or streams. During the leader's map reconnaissance, he determines any obvious danger areas and, if possible, adjusts his route.

(d) Avenues of approach are routes by which a unit may reach an objective or key terrain. To be considered an AA, a route must provide enough width for the deployment of the size force for which it is being considered. The AAs are also considered for the subordinate enemy force. For example, a company determines likely AAs for an enemy platoon; a platoon determines likely AAs for an enemy squad. Likely AAs may be either ridges, valleys, or by air. By examining the terrain, the leader determines the likely enemy AAs based on the tactical situation.

(e) Weather has little effect on dismounted land navigation. Rain and snow could possibly slow down the rate of march, that is all. But during mounted land navigation, the navigator must know the effect of weather on his vehicle. (See Chapter 12 for mounted land navigation.)

(4) **Troops.** Consideration of your own troops is equally important. The size and type of the unit to be moved and its capabilities, physical condition, status of training, and types of equipment assigned all affect the selection of routes, positions, fire plans, and the various decisions to be made during movement. On ideal terrain such as relatively level ground with little or no woods, a platoon can defend a front of up to 400 meters. The leader must conduct a thorough map reconnaissance and terrain analysis of the area his unit is to defend. Heavily wooded areas or very hilly areas may reduce the front a platoon can defend. The size of the unit must also be taken into consideration when planning a movement to contact. During movement, the unit must retain its ability to maneuver. A small draw or stream may reduce the unit's maneuverability but provide excellent concealment. All of these factors must be considered.

(a) Types of equipment that may be needed by the unit can be determined by a map reconnaissance. For example, if the unit must cross a large stream during its movement to the objective, ropes may be needed for safety lines.

(b) Physical capabilities of the soldiers must be considered when selecting a route. Crossing a large swampy area may present no problem to a physically fit unit, but to a unit that has not been physically conditioned, the swampy area may slow or completely stop its movement.

(5) **Time Available.** At times, the unit may have little time to reach an objective or to move from one point to another. The leader must conduct a map reconnaissance to determine the quickest route to the objective; this is not always a straight route. From point A to point B on the map may appear to be 1,000 meters, but if the route is across a large ridge, the distance will be greater. Another route from point A to B may be 1,500 meters—but on flat terrain. In this case, the quickest route would be across the flat terrain; however, concealment and cover may be lost.

11-5. MOVEMENT AND ROUTE SELECTION

One key to success in tactical missions is the ability to move undetected to the objective. There are four steps to land navigation. Being given an objective and the requirement to move there, you must know where you are, plan the route, stay on the route, and recognize the objective.

a. **Know Where You Are (Step 1).** You must know where you are on the map and on the ground at all times and in every possible way. This includes knowing where you are relative to—

- Your directional orientation.
- The direction and distances to your objective.
- Other landmarks and features.
- Any impassable terrain, the enemy, and danger areas.
- Both the advantages and disadvantages presented by the terrain between you and your objective.

This step is accomplished by knowing how to read a map, recognize and identify specific terrain and other features; determine and estimate direction; pace, measure, and estimate distances, and both plot and estimate a position by resection.

b. **Plan the Route (Step 2).** Depending upon the size of the unit and the length and type of movement to be conducted, several factors should be considered in selecting a good route or routes to be followed. These include—

- Travel time.
- Travel distance.
- Maneuver room needed.
- Trafficability.
- Load-bearing capacities of the soil.
- Energy expenditure by troops.
- The factors of METT-T.
- Tactical aspects of terrain (OCOKA).
- Ease of logistical support.
- Potential for surprising the enemy.
- Availability of control and coordination features.
- Availability of good checkpoints and steering marks.

In other words, the route must be the result of careful map study and should address the requirements of the mission, tactical situation, and time available. It must also provide for ease of movement and navigation.

(1) Three route-selection criteria that are important for small-unit movements are cover, concealment, and the availability of reliable checkpoint features. The latter is weighted even more heavily when selecting the route for a night operation. The degree of visibility and ease of recognition (visual effect) are the key to the proper selection of these features.

(2) The best checkpoints are linear features that cross the route. Examples include perennial streams, hard-top roads, ridges, valleys, railroads, and power transmission lines. Next, it is best to select features that represent elevation changes of at least two contour intervals such as hills, depressions, spurs, and draws. Primary reliance upon cultural features and vegetation is cautioned against because they are most likely to have changed since the map was last revised.

(3) Checkpoints located at places where changes in direction are made mark your **decision points**. Be especially alert to see and recognize these features during movement. During preparation and planning, it is especially important to review the route and anticipate where mistakes are most likely to be made so they can be avoided.

(4) Following a valley floor or proceeding near (not on) the crest of a ridgeline generally offers easy movement, good navigation checkpoints, and sufficient cover and concealment. It is best to follow terrain features whenever you can—not to fight them.

(5) A lost or a late arriving unit, or a tired unit that is tasked with an unnecessarily difficult move, does not contribute to the accomplishment of a mission. On the other hand, the unit that moves too quickly and carelessly into a destructive ambush or leaves itself open to air strikes also have little effect. Careful planning and study are required each time a movement route is to be selected.

c. **Stay on the Route (Step 3).** In order to know that you are still on the correct route, you must be able to compare the evidence you encounter as you move according to the plan you developed on the map when you selected your route. This may include watching your compass reading (dead reckoning) or recognizing various checkpoints or landmarks from the map in their anticipated positions and sequences as you pass them (terrain association). A better way is to use a combination of both.

d. **Recognize the Objective (Step 4).** The destination is rarely a highly recognizable feature such as a dominant hilltop or road junction. Such locations as this are seldom missed by the most inexperienced navigators and are often dangerous places for soldiers to occupy. The relatively small, obscure places are most likely to be the destinations.

(1) Just how does a soldier travel over unfamiliar terrain for moderate to great distances and know when he reaches the destination? One minor error, when many are possible, can cause the target to be missed.

(2) The answer is simple. Select a checkpoint (reasonably close to the destination) that is not so difficult to find or recognize. Then plan a short, fine-tuned last leg from the new *expanded objective* to the final destination. For example, you may be able to plan and execute the move as a series of sequenced movements from one checkpoint or landmark to another using both the terrain and a compass to keep you on the correct course. Finally, after

arriving at the last checkpoint, you might follow a specific compass azimuth and pace off the relatively short, known distance to the final, pinpoint destination. This procedure is called *point navigation*. A short movement out from a unit position to an observation post or to a coordination point may also be accomplished in the same manner.

Student Handout 3

This student handout contains 2 pages of extracted material from pages 79 thru 81, para 22 of FM 21-31.

Disclaimer: The training developer downloaded this extract from the General Dennis J. Reimer training and Doctrine Library. The text may contain passive voice, misspelled words, grammatical errors, etc., and may not be in compliance with the Army Writing Style Program.

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22. Control Points and Elevations

a. Applications of Definitions. The definitions of horizontal and vertical control stations which follow are generally applicable only to the United States.

b. Exceptions. In foreign areas, horizontal stations may not be monumented and in some cases, may be less than third order accuracy. Whenever information is available, exceptions are noted in the marginal legend of the map.

c. Symbols. The following pages contain the approved symbols for control points and elevations.

Figure 227. Horizontal Control Point. The symbol represents a described horizontal control point which is marked on the ground and which was established by triangulation or traverse of third or higher order accuracy.

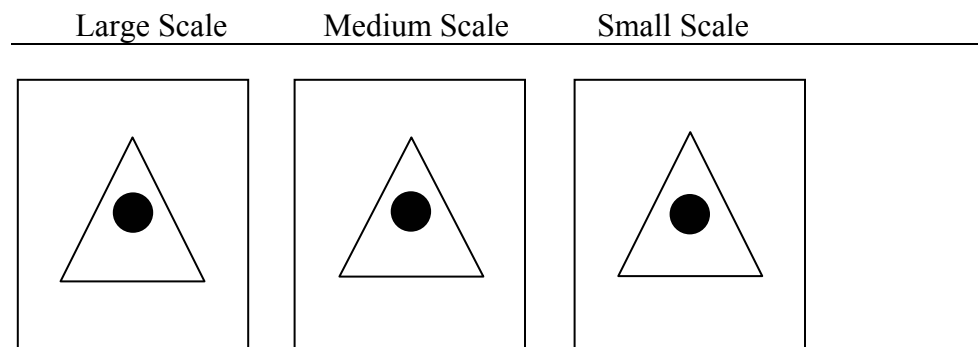


Figure 228. Monumented Bench Mark. The symbol represents a described vertical control point which is marked by a tablet on the ground and which was established by survey methods of third or higher order accuracy. On medium and small-scale maps Bench Marks are not specially symbolized. Their elevations are shown as spot elevations. (a) and (b) are alternate symbols.

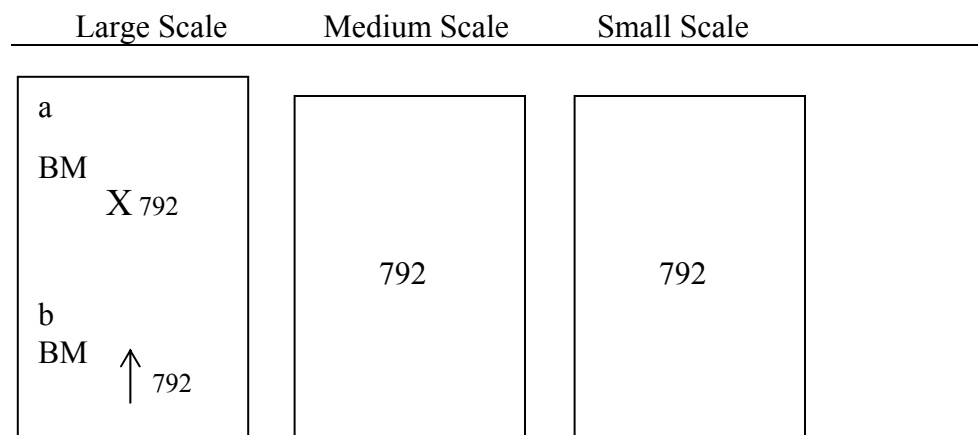


Figure 229. Monumented Bench Mark At Horizontal Control Point. The symbol represents a described control point which is marked on the ground and whose horizontal and vertical positions were established by survey methods of third or higher order accuracy.

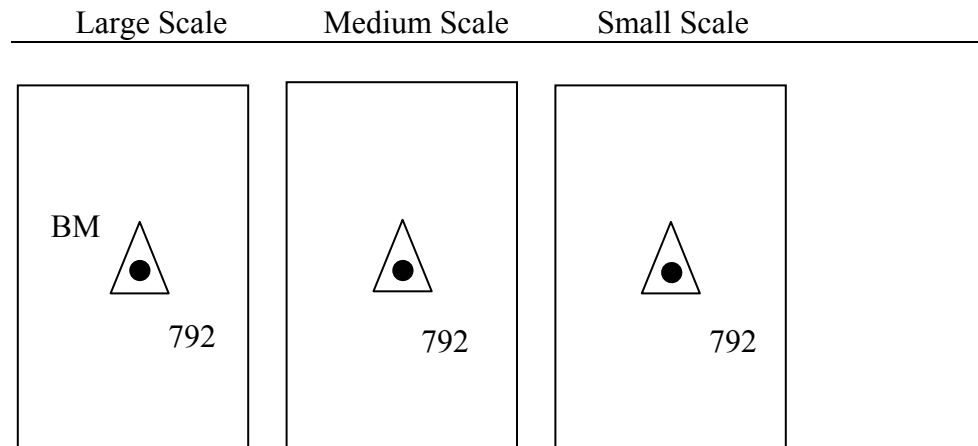


Figure 230. Non-monumented Bench Mark (Sometimes called temporary, supplemental, or intermediate). The symbol represents a described control point which is marked on the ground and whose horizontal and vertical positions were established by survey methods of third or higher order accuracy.

